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Technical Report

No. 13492

FINITE RLEMENT STRESS ANALYSIS FOR

COMPONENT ADVANCED TECHNOLOGY TEST BED (CATTB)

HAY 1990



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Samir Khourdaji U.S. Army Tank-Automotive Command ATTN: AMSTA-TDS

By Warren, MI 48397-5000

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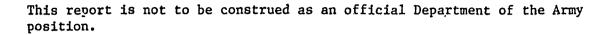
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PREFACE

This report illustrates the process necessary to make structural analysis and design of tracked vehicles a systematic procedure in which state-of-the art structural analysis, design and simulation are fully utilized. It is a modest step towards understanding the behavior of tracked vehicles under various loading conditions. It will be a good starting point in any subsequent research in this area. For this reason, the various results and the approach utilized were presented chronologically to keep the reader continuously in touch with the changes in analysis approach, which was necessary for achieving the final results.

The rapid development in computer hardware and software technology make undertaking such a task possible, something not even thought of a few years ago. Undoubtedly, this development will allow TACOM Personnel to tap into new area of research, which will allow them to revolutionize their design and analysis process.

I would like to take this opportunity to express my appreciation for the confidence and support that Mr. Art Adlam and John Korpi have shown which allow me to dedicate myself to this investigative study. Also I would like to thank Dr. Ron Beck and Mr. Zoltan Janosi for allowing me to get hands-on training on DADS program. Also I would like to thank Mr. Ken Cerelli and Bob Garcia for their cooperation in utilizing the Finite Element Code (IRM) and Patran Software. Also I would like to thank Mr. John Weller for his support in utilizing DADS program in the Dynamic Analysis area and providing access to mathematical program (MATLAB) which was utilized in performing the necessary mathematical calculation with high accuracy and great speed.



1. Summary - In this study, the dynamic effects of terrain load, in term of stresses in Components Advanced Technology Test Bed (CATTB) Chassis, was investigated. The stresses in the chassis due to terrain load is in the range of 3,000 PSI, at which the Chassis experience a vertical acceleration of 2 at its CG. To anticipate the maximum terrain effects, either a more drastic custom-made terrain can be used (Fig. 97) instead of ABG4 (utilized in Fig 96), or the traveling speed of the CATTB could be increased from the 30 mph. For simplicity, the maximum terrain effects can be assumed to be a factor of those experienced by the chassis based on previous road tests. In any event, a follow-up stress analysis is required.

Stresses due to firing load (375,000 lb) is maximum in the turret top plate (70,000 PSI). In the trunnion, it is in the range of 40,000 PSI. Stresses in the hull is maximum when the gun is firing at 90 degrees, and it is in the range of 80,000 PSI. To maximize these stresses, only two road wheels were assumed to provide resistance against lateral movement. In real situations, all road wheels resist lateral movement in a complex interaction between the track and terrain. To understand this behavior, a separate 3D DADS analysis is required. The transient dynamic effect of gun firing force could not be performed due to software difficulties. However, the model and input file are saved for further studies in this area.

2. INTRODUCTION

The continuous advancement in technology, the introduction of the solid modelers, and the supercomputer lead to the evolution of the design process at TACOM. The old design method "shave it till it breaks" simply will not work due to the complexity of automotive structure and the forces affecting it, and because of the enormous amount of time required by such an approach. the new evolved design, all parameters and their effects can be quantified, and better results can be achieved in a much shorter period of time. This can be accomplished by building a computer model which will serve as an inexpensive and expendable The mass properties (weight, moments of inertia and C.G location) for this prototype can be calculated easily by using the solid modeler capabilities. The forces acting on this prototype can be evaluated by performing a dynamic analysis utilizing the Dynamic Analysis and Design Software (DADS) available on the supercomputer. The strength of each component will be assured by conducting a Comprehensive Finite Element Analysis for this prototype under various loading conditions. such as firing load terrain forces, vibration, airdrop or blast, and other destructive testing. The new design will produce the best and most efficient product within the shortest span of In addition, it will provide understanding of the interaction of the various design parameters, which will help make any subsequent design modifications to be done with speed and confidence. The purpose of this study is to apply this systematic design approach to the design of the Components Advanced Technology Test Bed (CATTB).

3.0 <u>Discussion</u> - The material presented in this report represents design stages for the Component Advanced Technology Test Bed (CATTB). It is categorically divided into four stages as follows:

Solid Modeling;

In this stage, CATTB geometry for turret and hull is established, and their physical properties are evaluated.

Static Finite Element Analysis:

The configuration of the CATTB chassis was established to accommodate the new light weight gun. For this, a complete static finite element analysis was performed to assure the adequacy of the CATTB Chassis strength under various loading conditions.

Dynamic Analysis:

In this stage, a CATTB dynamic model was built and analyzed using DADS software. The forces and acceleration acting on the various components were established.

Dynamic Finite Element Stress Analysis:

A detailed finite element analysis was performed to study the dynamic nature of terrain and firing forces and the effects of vibration on CATTB structure.

The assumptions made and the results obtained for these four stages as presented in detail on the following pages.

4, Results:

The results of the four design stages are presented as follows:

4.1 CATTB Solid Model

4.1.1 Turret Solid Model:

The objective of creating a solid model for the CATTB turret is to study the effects of the new turret feature (trunnion, new gun mount and side-plate locations) on the characteristic behavior of the CATTB turret. Also, it was necessary to determine the new turret mass properties for establishing the requirement for the hydraulic system necessary to power the turret. A solid model was created on the Intergraph CAD system utilizing EMS software. This model was created from a series of primitive solids (cubes Tetrahedron....) because changing dimensions length, height, and width can be achieved quite easily by lifting the faces or edges of these primitive solids. turret geometry is shown in Fig (1 - 3), turret solid model is shown in Fig (4 - 8).

4.1.2 Evaluation of CATTB Turret Mass Properties:

The powerful capabilities of the CAD system were utilized to evaluate CATTB mass properties. These properties, which include weight, CG locations, and moments of inertias for the CATTB turret's various components, are shown in Appendix A. Total CATTB turret weight and the location of is C.G were determined mathematically as, shown in Table 1. CATTB mass properties at about any point can be determined by transforming mass properties of the various components from their own CG to that given point as shown in Table 2 & 3.

Plate thickness for CATTB turret structure is shown in Fig (1) side-armor thickness is 40 inches in the front area and projected through proper angles to both sides. The density of side armor used is 0.095 lb/in³ and is based on 550 lb/ft². For 50" armor, the density is 0.104 lb/in³ and is based on 750 lb/ft².

Top-armon thickness used is 4 inches, except over the L.W. 120mm gun front area, where it is 2 inches. At the rear gun area, no top armor is used. The density of the top armor is 0.1215 lb/in³ and is based on 70 lbs. per square ft. for 4 inches thick.

Spall liner is used on the inside of the CATTB Turret crew area. At thickness of one inch, the density of the spall liner used is 0.04 lb/in3 and is based on weight of 5.7 lb. per square ft.

To convert mass properties from lbs. - in² to slug - ft² (lbs. - rt - sec²), the following multiplication factor was used:

$$\frac{1}{32.2} \times \frac{1}{12} \times \frac{1}{12}$$
= 0.0002157 or 2.15; x 10 -4

4.1.3 HULL Solid Model:

CATTB solid model for the hull and suspension are shown in Fig (9 - 11). The basic hull structure, skirts, spansons, grills and suspension (idler, roadarms, roadwheels and final drive) were created as solids. Whereas, the power pack, fuel tank, autoloader, and various electrical control boxes were not modeled as a solid, but primitive solids were used to represent their Geometry.

4.1.4 HULL Mass Properties:

The mass properties of the various hull components about their own CG was calculated using EMS software and are shown in detail in Appendix B. The hull CG was found and hull mass properties about the axis, passing through its CG was obtained by transforming mass properties of the various hull components to the hull CG location, as shown in Table 4.

Table 1 Weight and C.G Location for CATTE Turret Components

COMPONENT	WEIGHT	C.G LO	CATION	(IN)	FIRST MOM		
	M (lbs)		<u> </u>	.2	MX	MY	MZ
(2);	10,000	-90.4	0	17.0	-913,040	0	171,700
GUN (1)	6,810	-67.8	Ø	17.0	-461.718	Ø	115,770
SIDE ARMOR(40"			+ 0.6	18.0	-421,060	~ 9,460	283,860
	24,150		- G.5	18.4	-712,43Ø	-12,080	444,360
TOP ARMOR	2,900	14.0	Ø . 3	42.0	40,600	87Ø . Ø	121,800
SPALL LINER	1,250	18.0	Ø.3	26.0	22,500	375.0	32,500
BASKET	830	- 2.6	Ø.7	-32.5	- 2,158	581.0	-26,975
COM'DR CHAIR	160	18.4	-25.0	- 9.5	2,944	- 4,000	- 1,520
GUN CHAIR	180	12.0	25.8	-16.5	2,160	4,644	- 2,970
GUN HATCH	120	12.0	14.3	38.3	1,440	1,716	4,596
WEAPON ST	860	20.6	-23.6	40.3	17,716	-20,296	34,658
GEAR BOX	570	-23.4	27.3	4.4	-13,338	15,561	2,508
AUTO LOADER	3,650	90.6	- Ø.8	24.50	330,690	- 2,920	89,425
BASIC	13,560	54.7	- Ø.7	21.0	741,730	- 9,490	284,700
STRUCTURE TOP PLATE	3,650	47.1	Ø.4	37.4			
BOTTOM PLATE	4,340	56.4	- Ø.1	5.9			
VERTICAL PLATI (Crew Area)	E 2,885	18.7	- 3.4	19.4			
VERTICAL PLATI (Bustle Area)	2,685	101.0	- Ø.4	24.7			٠
BEARING	265	Ø	Ø	- 1.50	Ø	Ø	- 398
GUN SHIELD	210	-48.5	Ø.2	16.70	- 10,185	- 42	351
ELECTRICAL BOX	KES 900	- 2.5	Ø.4	16.70	- 2,250	360	-15,030
GPS & MTAS	630	17.70	29.5	39.00	11,150	18,585	24,570
SIGNATURE SUPPOSKIN	P 75Ø	-25 . Ø	Ø	18.50	- 18,750	y Ø	13,875
TOTAL 40" Armon	()49,415	4.80	- Ø.Ø7	19.50	241,471	- 3,516	961,720
(1) (50" Armo	(1) (50" Armor) 57,795 - Ø.86 - Ø.11 19.4Ø - 49,9ØØ - 6,136 1,122,22Ø (2) 40" (Armor) 52,700 -4.0 -0.05 19.3 -209,850 -3,516 1,017,650 50" (Armor) 61,000 -8.2 -0.10 20.3 -501,220 -6,136 1,234,080						
(2) 40" (Armo	(x) 52,70	U -4.0	-0.05	T9.3	-209,85 0	0 -3,516	1,017,650
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Table 2 Mass Properties of CATTB Turret Components About Axis Passing Through Their C.G's

COMPONENTS	$\frac{\text{I x (1b - in}^2)}{}$	$\underline{\text{I y (lb - in}^2)}$	I z (lb - in')				
_GUN (1) (2) SIDE ARMOR(40") (50") TOP ARMOR	172,116 490,880 31,060,200 53,873,400 1,731,330	30,965,700 59,680,700 17,704,900 30,777,100 1,611,100	30,965,300 59,680,700 46,325,900 80,912,900 3,914,860				
SPALL LINER	1,333,180	1,180,060	2,188,140				
BASKET	456,150	404,680	771,670				
CCM'D CHAIR	38,790	40,260	6,860				
GUN'R CHAIR	9,770	11,750	7,460				
GUN'R HATCH	7,370	4,440	11,590				
WEAPON STATION	90,740	85,660	172,140				
GEAR BOX	33,820	26,980	25,080				
AUTOMATIC LOADER	2,124,560	1,202,440	3,032,340				
BASIC STRUCTURE	13,976,550	20,823,640	33,667,790				
TOP PLATE	2,206,820	7,791,350	9,987,530				
BOTTOM PLATE	3,542,470	8,690,130	11,997,000				
VERTICAL PLATE	4,174,550	3,013,540	6,607,190				
(Crew Area) VERTICAL PLATE	4,052,710	1,328,620	5,076,070				
(Bustle Area) BEARING	158,365	158,365	316,330				
GUN SHIELD	16,930	10,880	12,575				
ELECTICAL BOXES	360,405	373,095	661,745				
GPS & MTAS	41,820	287,635	276,595				
SIGNATURE SUPP SKIN	238,875	47,670	286,540				

Table 3 Mass Properties of CATTB Components About Axis Passing Through Its Center of Rotation

COMPONENT	$I \times (lb - in^2)$) Iy (lb - in ²) Iz(lb-in²)
GUN (1) (2)	2,133,500 3,409,780	64,252,400 145,138,420	62,290,000 142,219,520
SIDE ARMOR (40")	36,220,700	34,089,700	57,560,700
(50") TOP ARMOR	62,060,700 6,854,600	59,950,100 7,315,600	101,912,000 4,496,440
SPALL LINER	2,187,400	2,438,800	2,592,830
BASKET	1,340,000	1,293,900	777,900
COM'DR CHAIR	152,300	103,960	165,890
GUN CHAIR	183,930	89,486	157,880
GUN HATCH	245,560	191,030	96 , 78Ø
WEAPON STATION	1,978,800	1,856,800	1,025,180
GEAR BOX	66,780	57,815	44,240
AUTOMATIC LOADER	4,320,000	33,417,000	33,056,000
BASIC STRUCTURE	21,989,340	79,068,730	83,967,880
TOP PLATE	7,314,150	20,999,400	18,089,100
BOTTOM PLATE	.3,692,880	22,633,300	25,789,800
VERTICAL PLATES	5,297,430	5,116,830	7,653,480
(Crew Area) VERTICAL PLATE (Bustle Area)	5,684,880	30,319,200	32,435,500
BEARING	158,365	158,365	316,330
GUN SHIELD	74,510	553,560	497,690
ELECTRICAL BOXES	611,180	629,115	667,250
GPS & MTAS	1,541,730	1,436,130	1,021,740
SIGNATURE SUPP SKIN	2,189,625	516,425	2,706,050
TOTAL (40" Armor) (lb - in²) (50" Armor)	82,248,320 108,088,320	227,468,816 253,329,216	251,440,780 295,792,080
TOTAL (40" Armor) (1) (Slug - ft ²) (50" Armor	17,741 r) 23,315	49,065 54,643	54,236 63,802
TOTAL (40" Armor) (2) SLUG-FT ² (50" Armor)	18,013 23,586	66,526 72,103	71,465 81,030

Moment of Inertia of CATTB Turret About Axis Passing Through its C.G

$$I x_o = I x - (\overline{y}^2 + \overline{z}^2) M$$

$$I y_o = I y - (\overline{x}^2 + \overline{z}^2) M$$

$$I z_o = I z - (\overline{x}^2 + \overline{y}^2) M$$

Where I x, I y, and I z are moment of inertia about turnet rotational center (table 4). x, y, z and M are given in table 2.

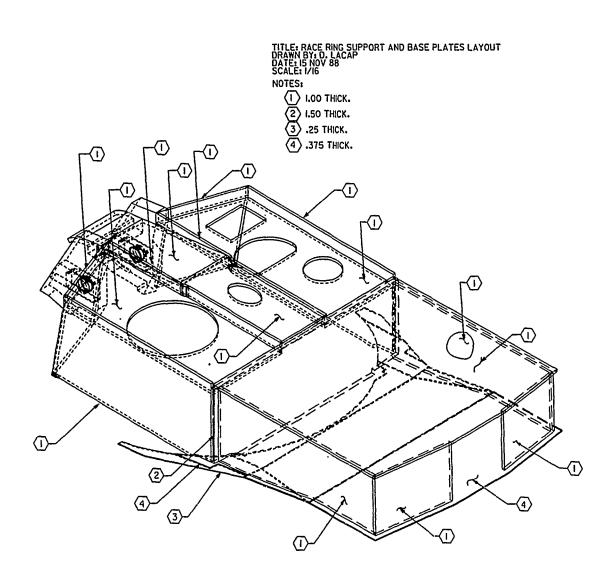
Using the above equations

I
$$x_o = 82,248,320 - (19.50^2 + 0.07^2) \times 49,415$$

= $82,248,320 - 18,790,300$
= $63,458,020$ lb - in²
= $13,688$ slug - ft² (x 0.2157 x 10)
I $y_o = 227,468,820 - (4.8^2 + 19.50^2) \times 49,415$
= $227,468,820 - 19,928,580$
= $207,540,240$ lbs - in²
= $44,766$ slug - ft²
I $z_o = 251,440,780 - (4.8^2 + 0.07^2) \times 49,415$
= $251,440,780 - 1,138,760$
= $250,302,020$ lbs - in²
= $53,990$ slug - ft²

ABLE 4

	s 10 ⁶ 1z	221.4	14.61	42.61	39.6	92.60	98.8	7.84	20.8	5.40	4.10	14.32	49.52	43.86	36.92	93.27	787.57
	MASS PROPERTIES ABOUT HULL C.G.X10 ⁶	201.6	8.96	30.10	40.00	90.46	94.3	6.3	19.4	5.10	4.1	13.70	44.86	37.38	28.84	. 68.47	693.57 1,794,950 2
	MASS ABOUT Ix	29.0	5.82	15.96	4.66	2.44	6.9	2.34	1.66	0.37	0.04	89:0	4.96	10.26	13.84	32.25	131.18 339,490 1
	A .G.X10 ⁶	191.9	14.5	39.8	7.0	. 2.53	8.58	2.83	0.28	0.07	90.0	0.024	0.30	32.00	11.20	t	ر\$ر
	MOMENT OF INEKTIA ABOUT COMPONENT C.G.X10 ⁶ IX I2	172.28	8.8	25.6.	5.0	0.41	4.10	1.28	0.35	0.09	0.07	0.03	0.15	32.00	11.20	1	IN ² ×(10 ⁶)
носс	MOMENT ABOUT C	28.83	5.8	14.3	2.3.	2.43	6.88	2.32	0.17	0.05	0.04	0.03	0.03	0.38	0.16	,	- BLUS
MASS PROPERTIES FOR CATTB HULL	23	-24.3	-23.0	1 6.3	0.21	-24.7	-24.9	-26.3	-24.6	25.2	-24.6	-25.7	-29.1	-39.2	-45.2	-29.0	-24.61
	. LOCATION Y (IN)	0.86	0.12	0	0	0.53	0	0	30.4	30	0.4	0	0	0	0	0	-1.2
	ດ ×	-3.10	22.6	56.0	123,30	-116.9	124.6	69.3	6.08-	-80.8	-80.8	-111.0	143.7	9.6	19.6	14.6	31.66
	WEIGHT (LBS)	23815	1320	4900	3920	4050	10523	3600	1500	390	315	335 X 2	1780 X 2	3870 X 2	1390 X 2	8900	77,990
	COMPONENT	HASIC STRUCTURE .	Skirt	SPANSON	GHILLS	FRON'! ARMOR	POWER PACK	MAGIZINE	FUEL TANK	ELEC CONTROL EQUPT	DRIVER	IULER	FINAL DR	HOAD ARMS	ROAD WHEELS	TRACK	::OTAL



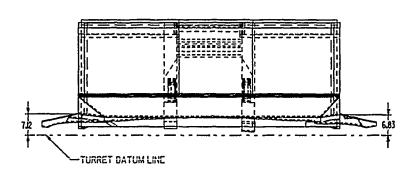
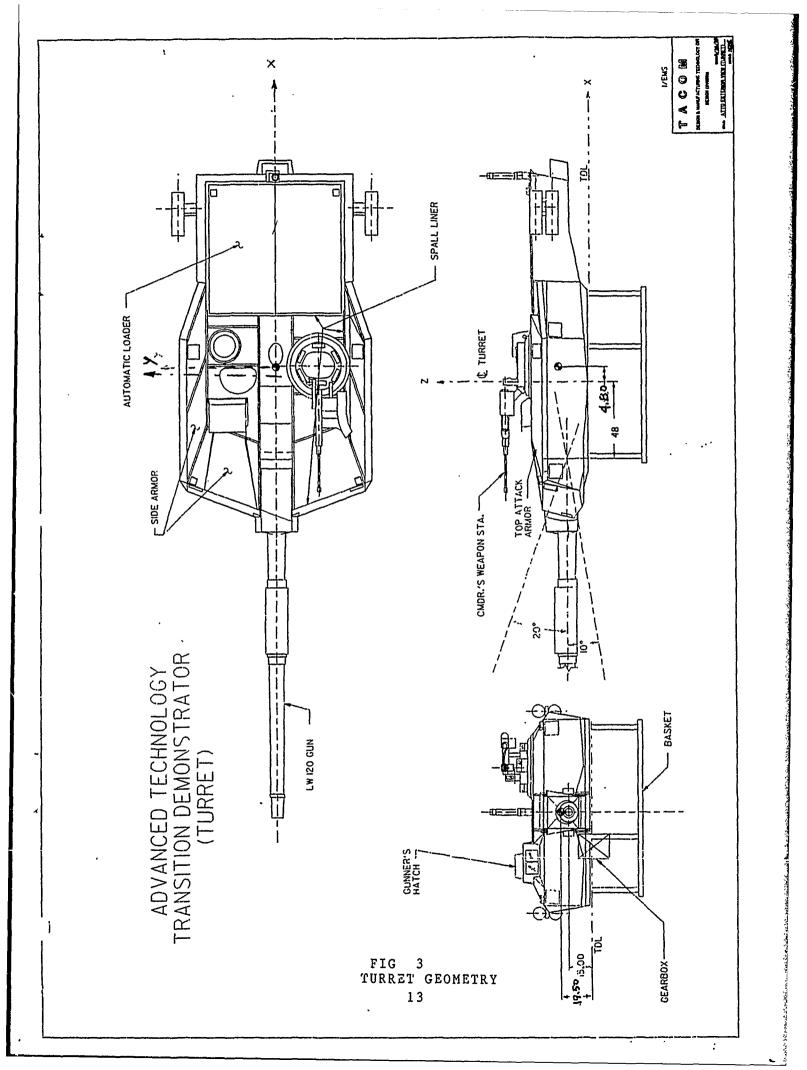
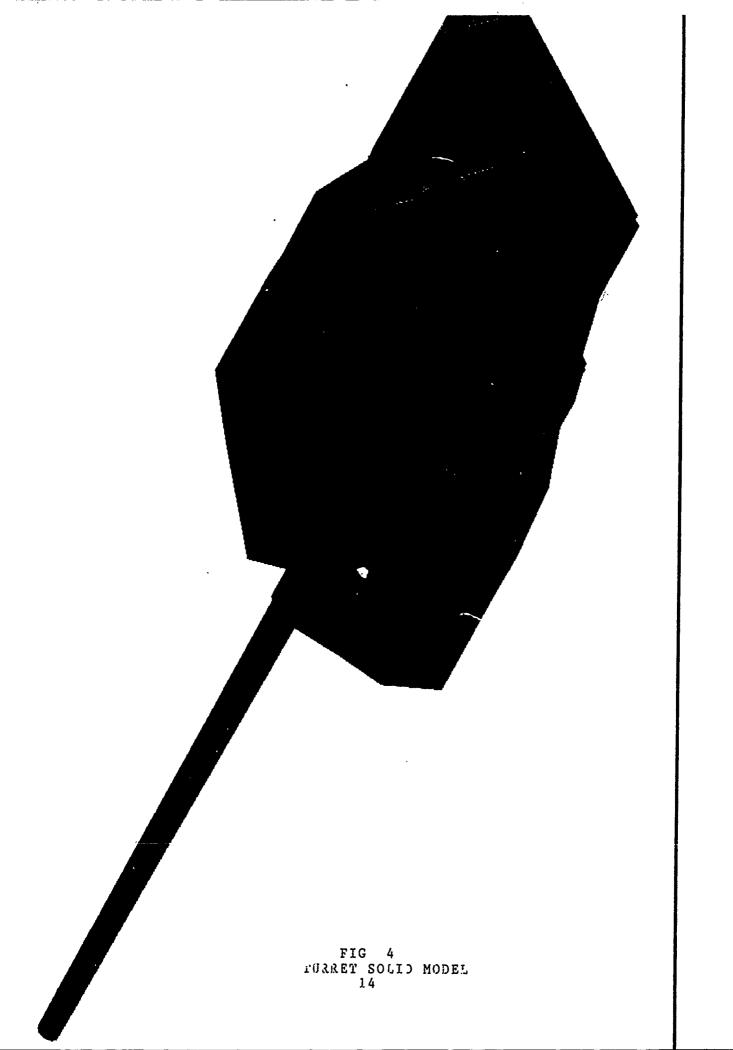
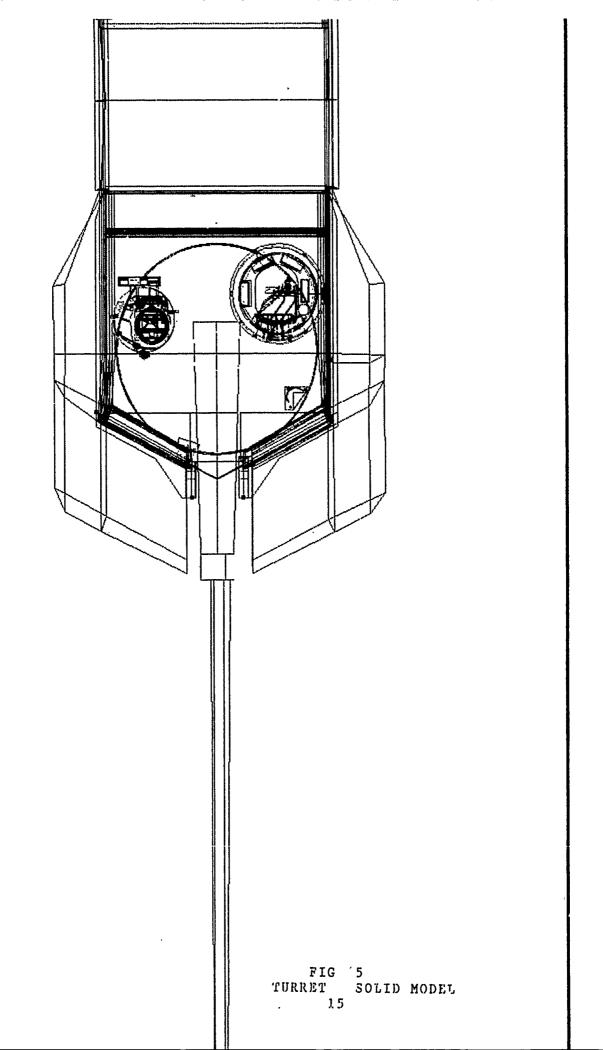
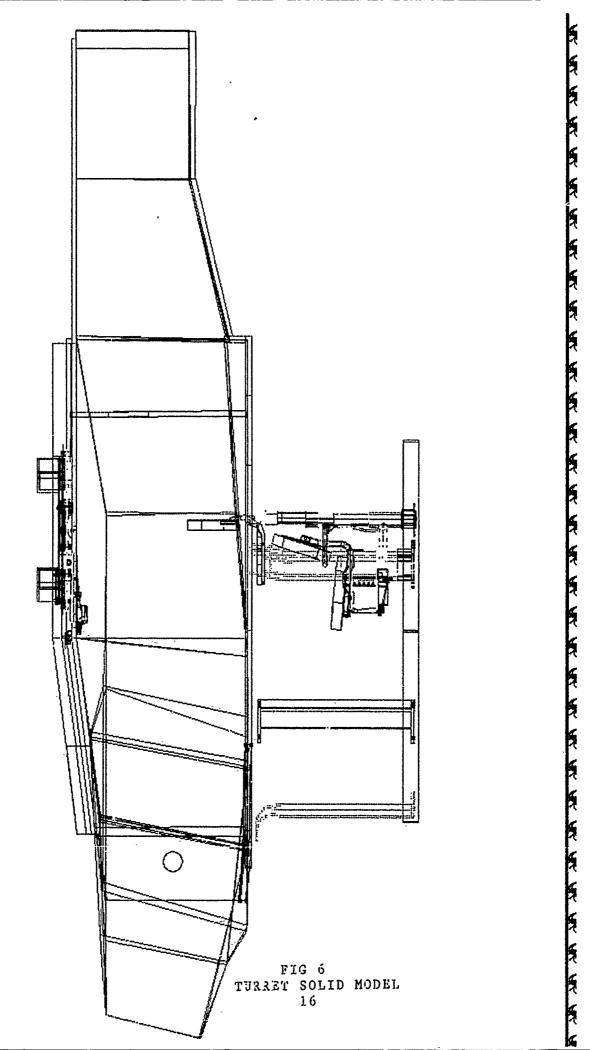


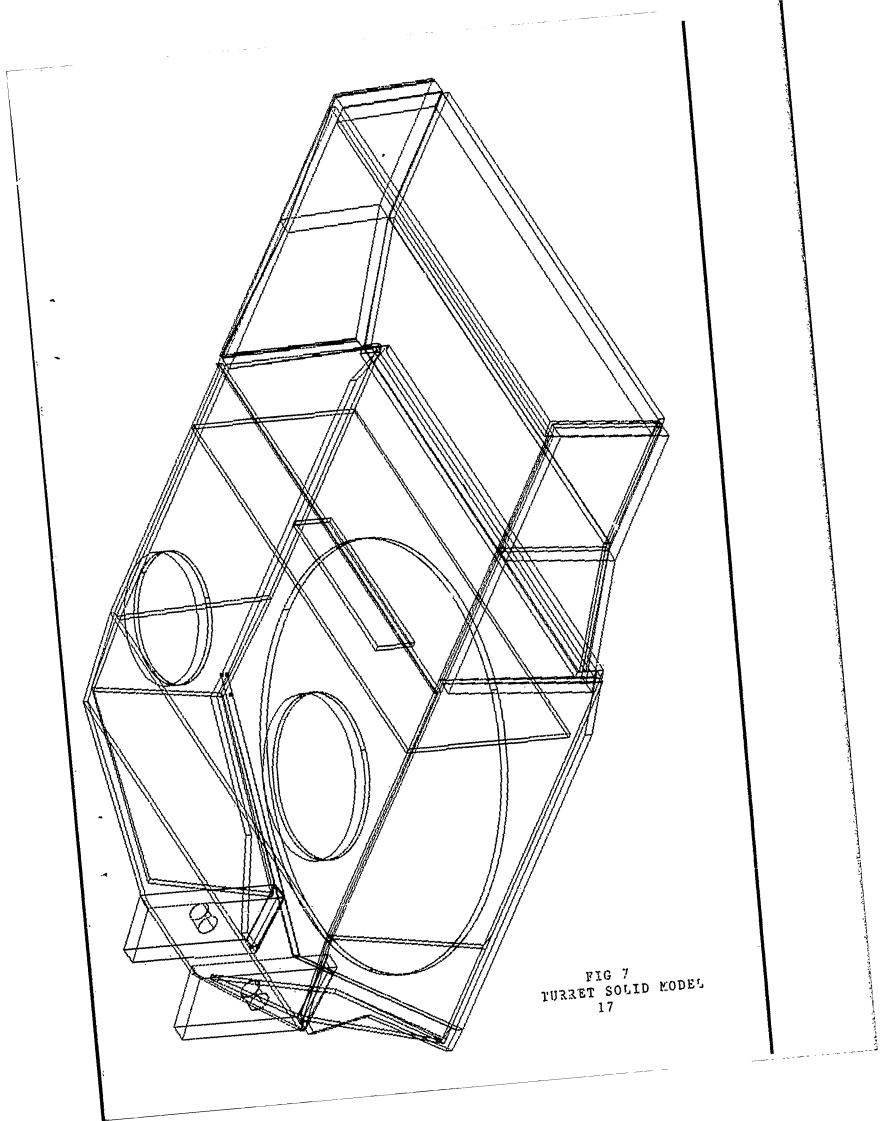
FIG 2
TURRET GEOMETRY
12

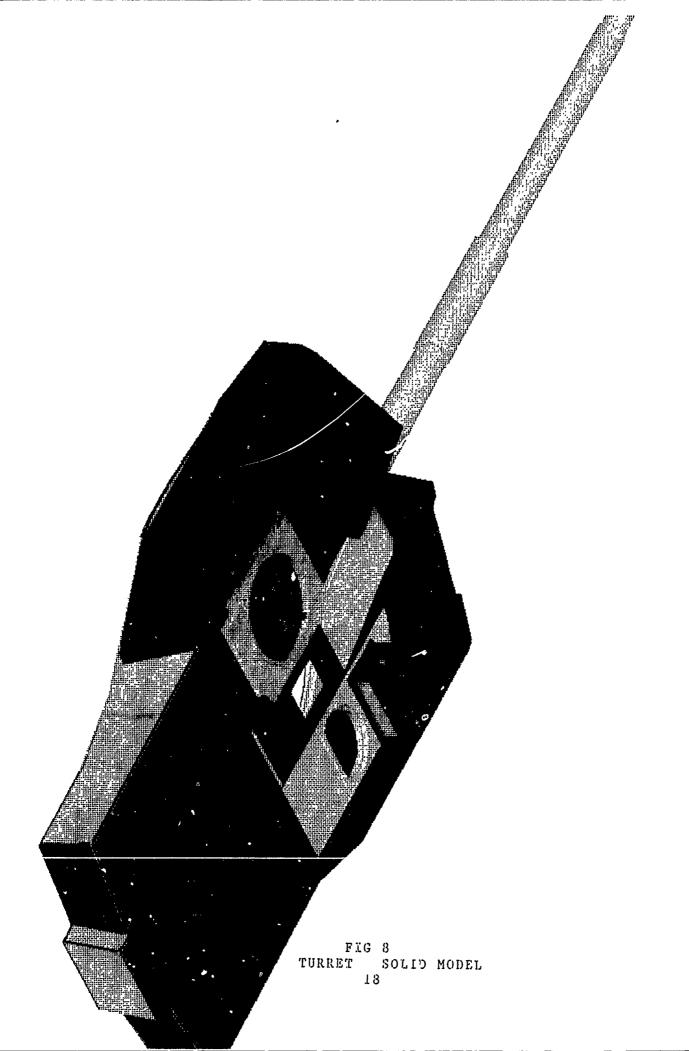


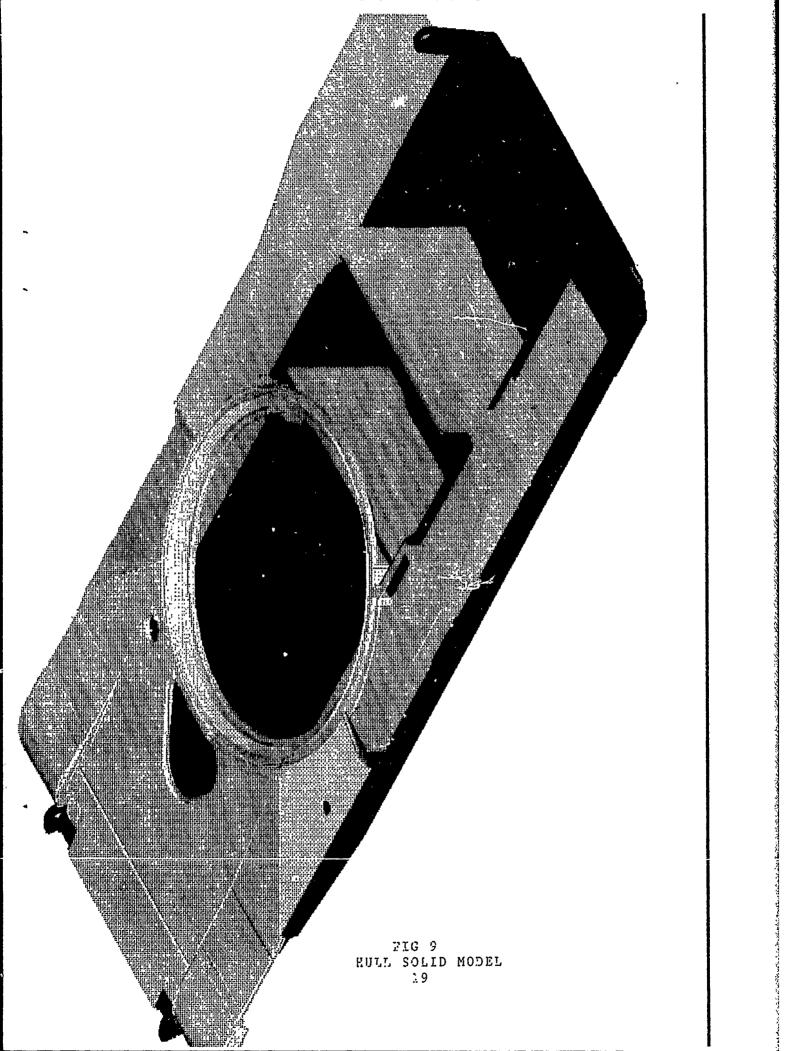












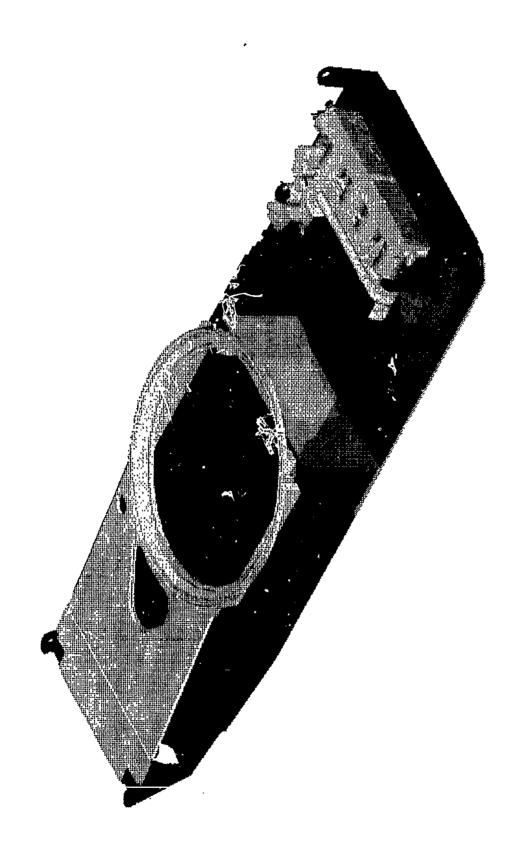
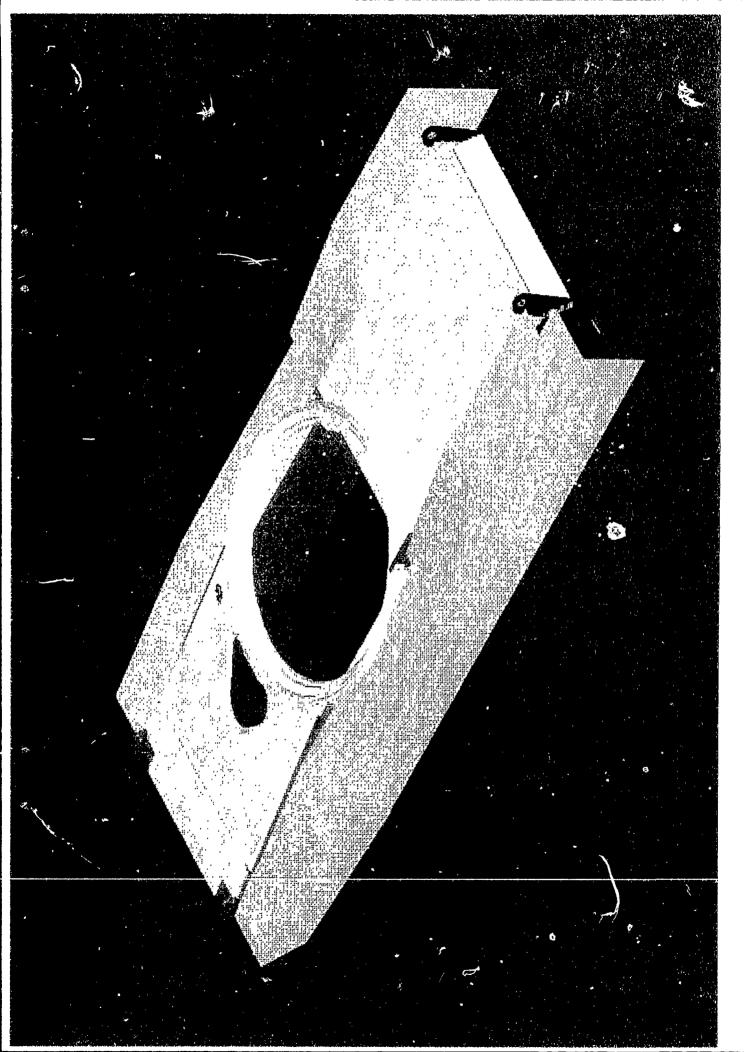
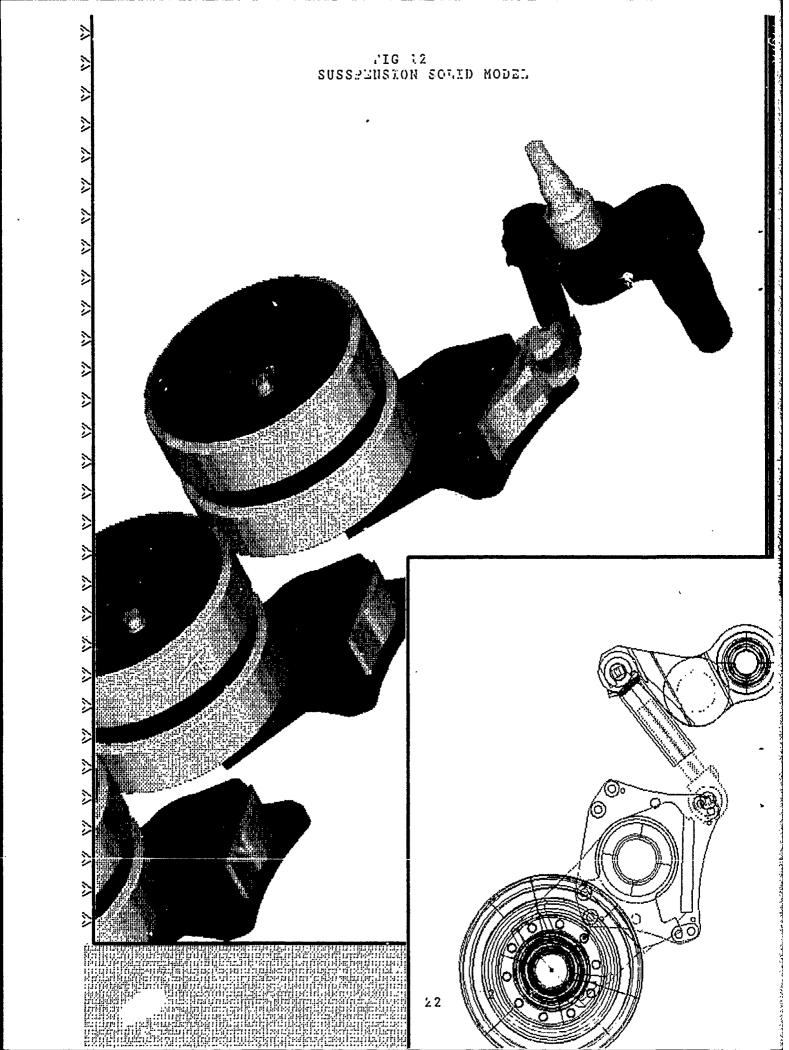


FIG 10 HULL SOLID MODEL 20





4.2 Static Finite Element Analysis

A Finite Element Model for the CATTB chassis was created utilizing Intergraph Randmicas Finite Element software (IRM). The FEM Turret Model was built first. Afterwards, the hull was modeled, and the two models were merged together to form the CATTB chassis model.

4.2.1 Turret Model:

The CATTB turret is unique in its geometry, specifically in the location of the side plates and the manner in which the gun mount interfaces with the Trunnion. To study the impact of this new geometry on turret behavior, it was necessary to build a Finite Element Model for the turret and analyze it under various loading conditions. Since a 3D solid model was available on the Intergraph CAD System, a wire frame was constructed from this 3D model and transferred to the VAX Computer, after it has been translated to IGDS, which is the graphic base for IRM. This wire frame will serve as a skeleton on which the Finite Element Model will be built.

The Turret FEM model consists of 132 four-noded shell elements. Each node has six degrees of freedom, three translations and three rotations about the global axis x, y, and z. The thickness of the various plates forming the FEM model are shown in Fig (1). The turret is fastened to the hull by a ring which has 48 mounting bolts. To reflect this geometry in the FEM model, the turret is assumed to be supported at 48 nodes, as shown in Fig (18). The turret FEM model will be used as a prototype to study the effect of the new trunnion design in comparison with the conventional one Fig (13), As a result of this study, the trunnion will be reshaped Fig (16 and 17).

4.2.2 Turret Loads

The following design loads are applied on the FEM Model:

2G (turret's own weight)
3000 lb (weight of the AutoLoader)
375,000 lb (Gun Firing wad at -10 degree or +15 degree)

To study the compounding effect of this load, two load combinations were considered:

2G (Down) + AutoLoader + Firing at -10 degree case(5)
2G (Down) + AutoLoader + Firing at 15 degree case(6)

4.2.3 Turret Analysis Results - (turret is independent)

4.2.3.1 IRM Results

VON mise stresses (which reflect bending and shear effects about the three major axis) are in the 70,000 PSI range, as shown in Fig (14). The vertical deformations are shown in Fig (15). Reshaping the trunnion area resulted in a more refined model. For the turret, as shown in Fig (16 & 17), VON mise stresses in this refined model is 44,000 PSI and occurs around the slot provided for the gun mounting block, as shown in Fig (19 & 20), this area is shown in detail in Fig (21). Maximum vertical deflection is 0.07 inch, as shown in Fig (22). The forces in the 48 mounting bolts are tabulated in Appendix C.

4.2.3.2 NISA Results

Since the CATTB Chassis FEM Model had to be made available on the Cray Supercomputer (to conduct Dynamic stress analysis, as will be shown in section 4.4), a stress analysis for the turret was conducted using NISA software. The results are shown in Fig (23 & 24). Comparing NISA results, with IRM results which is shown in Fig (19 & 20), indicates that NISA yields higher stresses in the top plate around hatche openings (76,000 PSI vs 45,000 PSI). This is primarily due to the inherit difference of stress and strain formulas in each code. NISA results are more accurate, since stress in the top plate are expected to increase due to the reduction of the resisting area.

4.2.4 Turret Analysis Results (Turret as part of Chassis):

It was found necessary when analyzing the hull to merge the turret and hull models and study their interaction effects (section 4.2.11). This provides the following actual stresses in the turret.

4.2.4.1 IRM Results

VON mise stresses are in the range of 36,000 PSI, as shown in Fig (25 & 26)

4.2.4.2 NISA Results

VON mises stresses are in the 67,000 PSI range, as shown in Fig (27). Comparison of the results (4.2.3.1) and (4.2.3.2) indicate that analyzing the turret independently from the hull yield higher stresses, because support points are considered as rigid. In contrast, when this support is considered flexible (has relative movement), it yields lower stresses. The latter are the actual results which reflect turret-hull interaction.

FIG 13 CATTB TURRET (CONVENTIONAL TRUNNION)

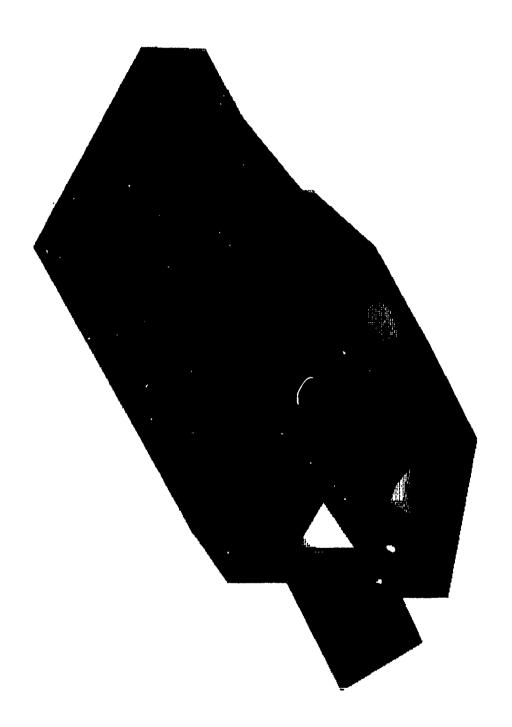
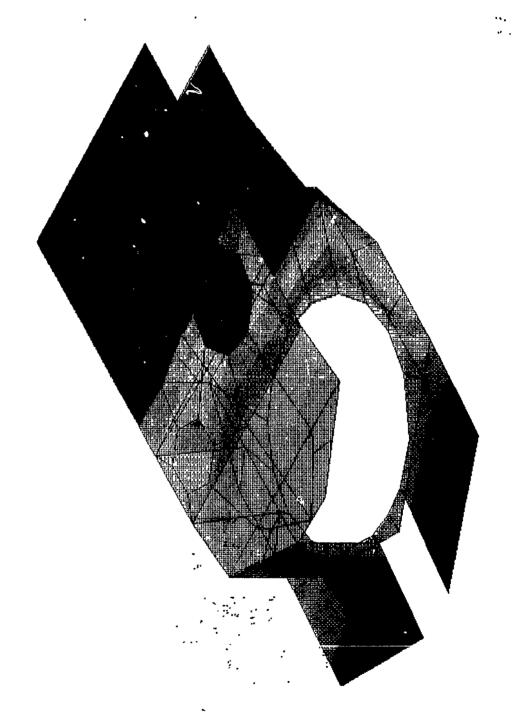
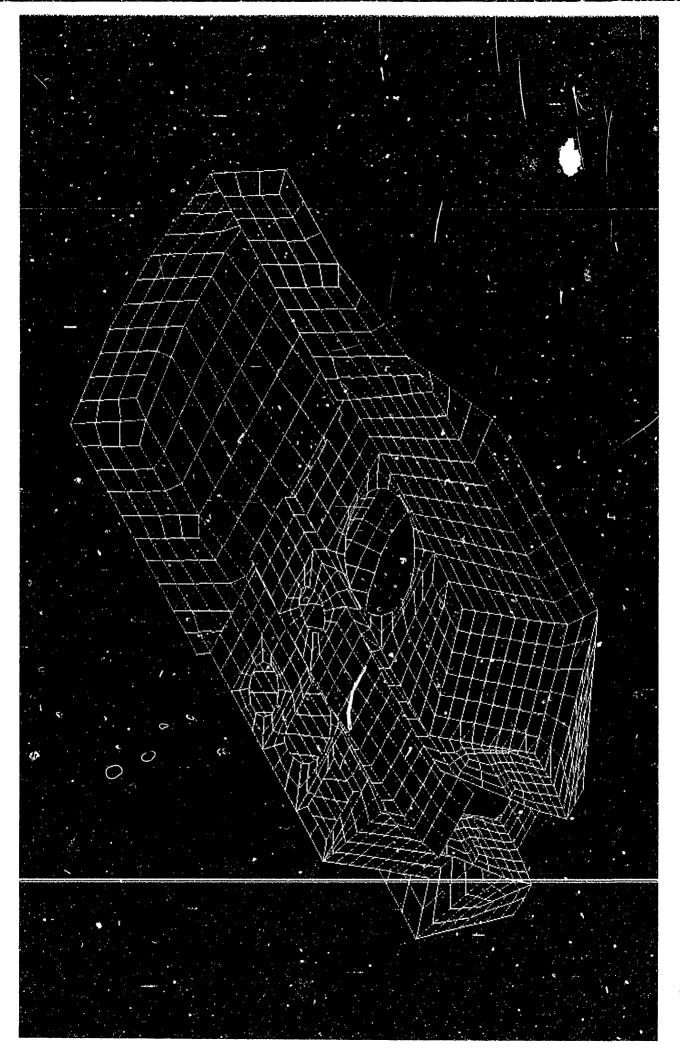
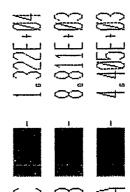


FIG 14 STRESS IN CATTB (CONVENTIONAL TRUNNION)



.fig 15 DEFLECTION.IN CATTB (CONVENTIONAL TRUNNION)









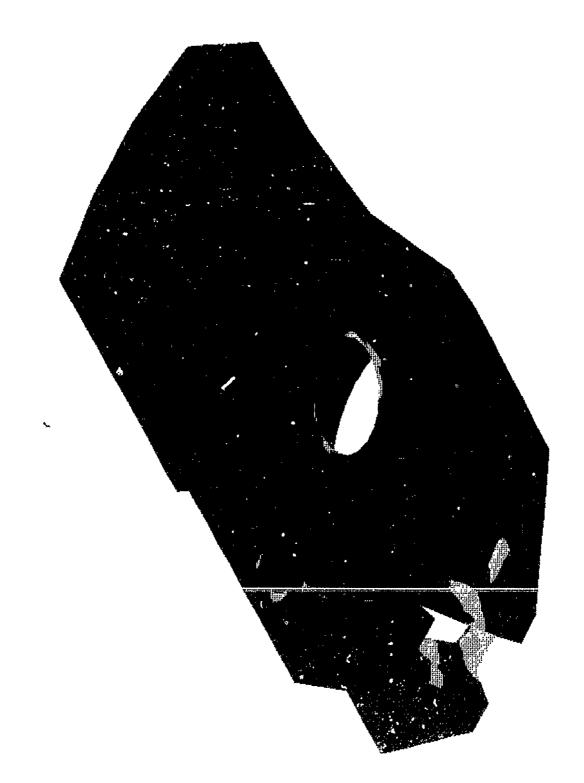


FIG 20 - IRM STRESS RESULTS (TURRET INDEPENDANT)



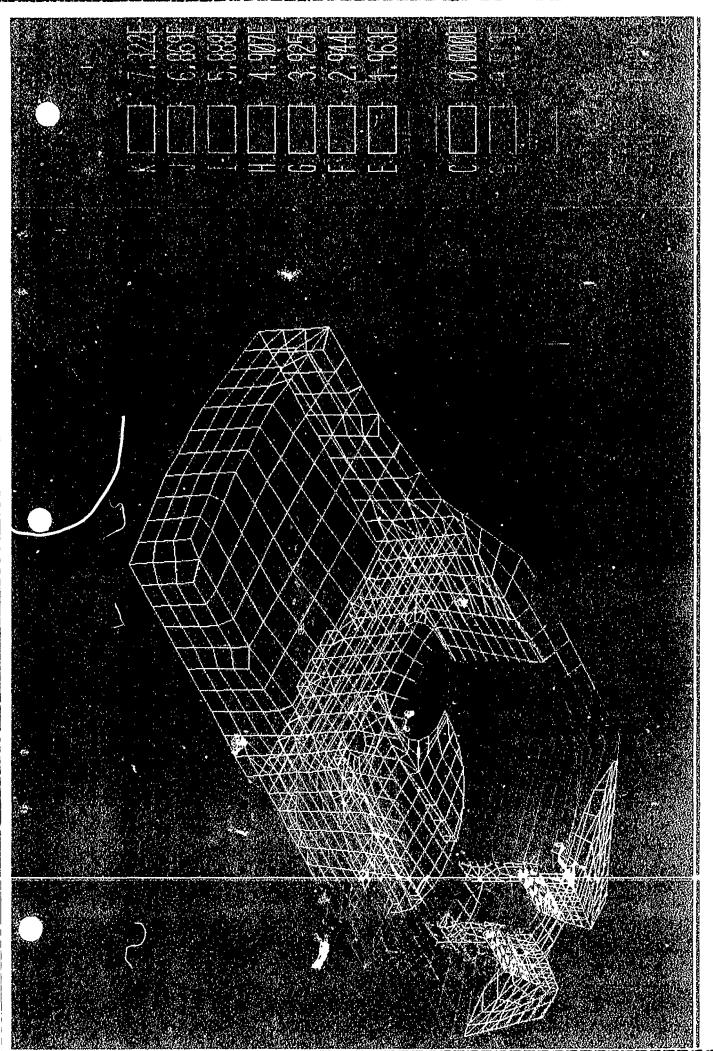
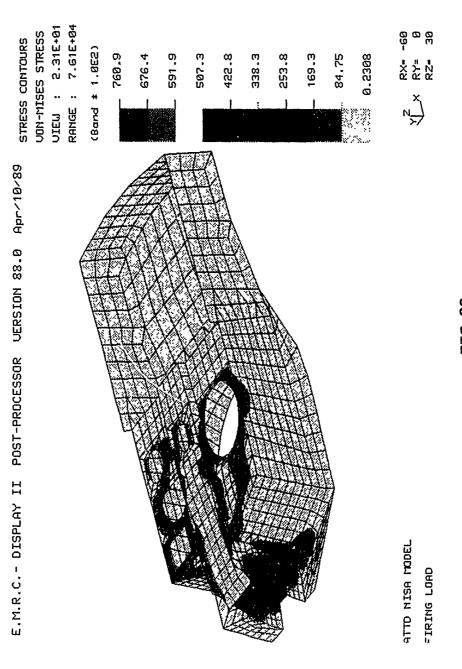
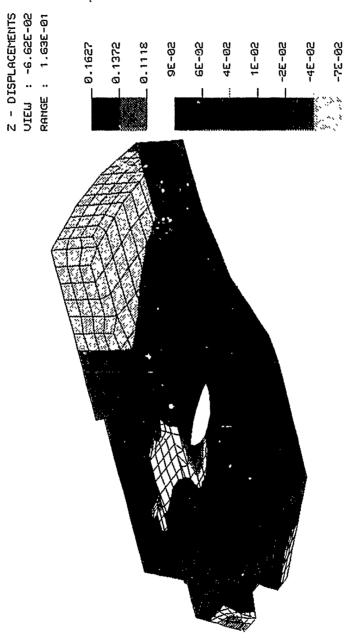


FIG 23 NISA STRESS RESULTS (TURRET INDEPENDANT)



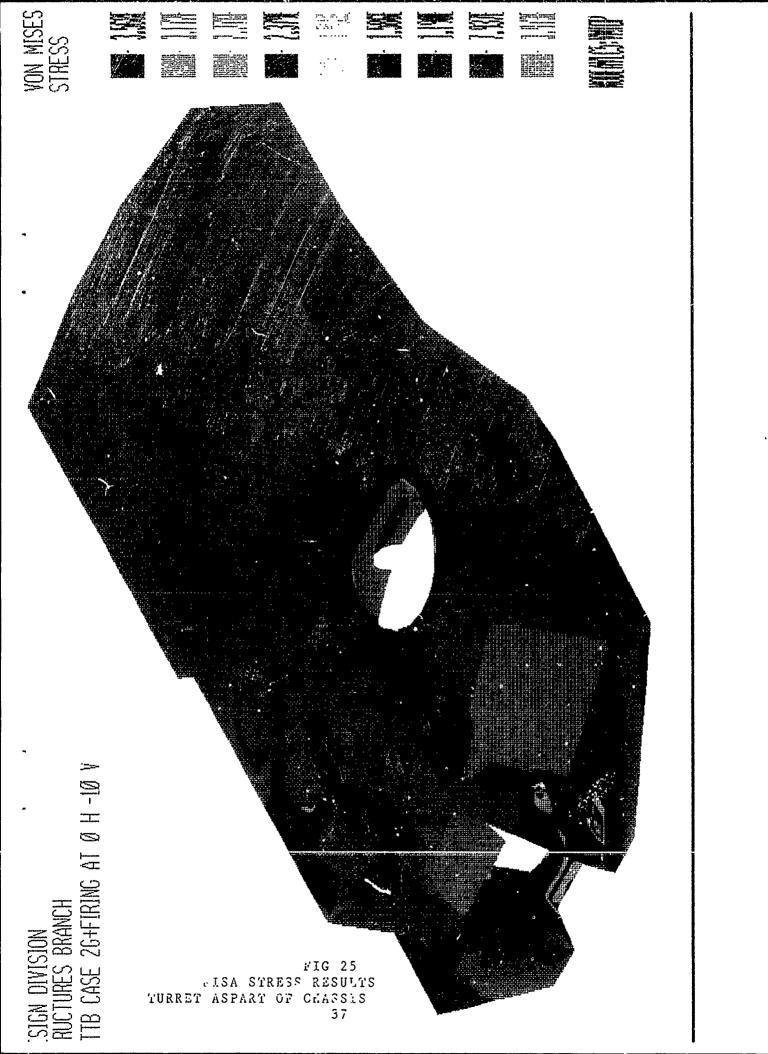
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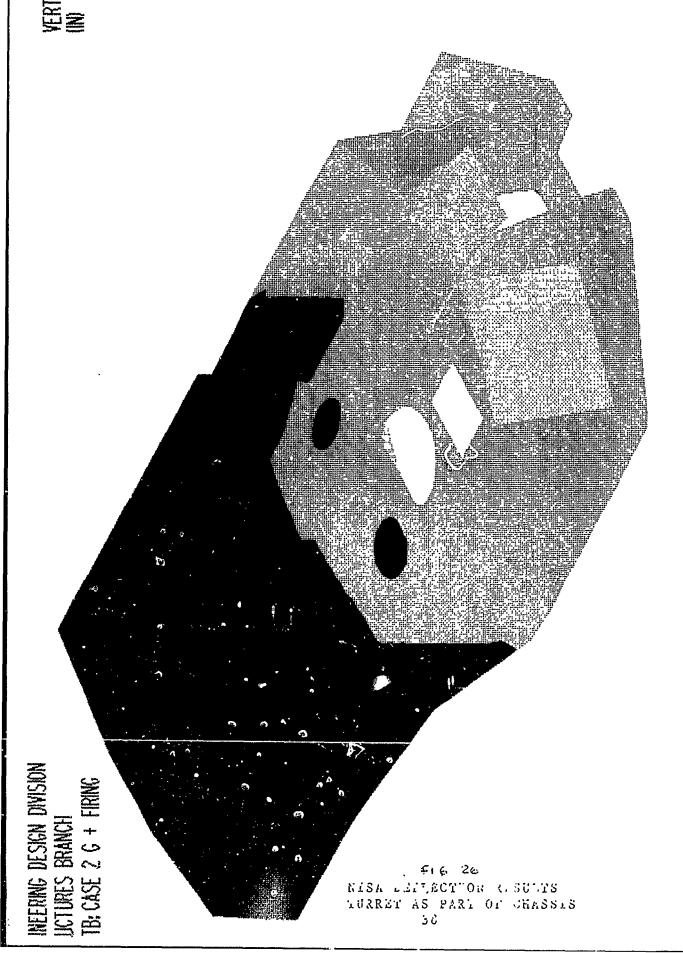
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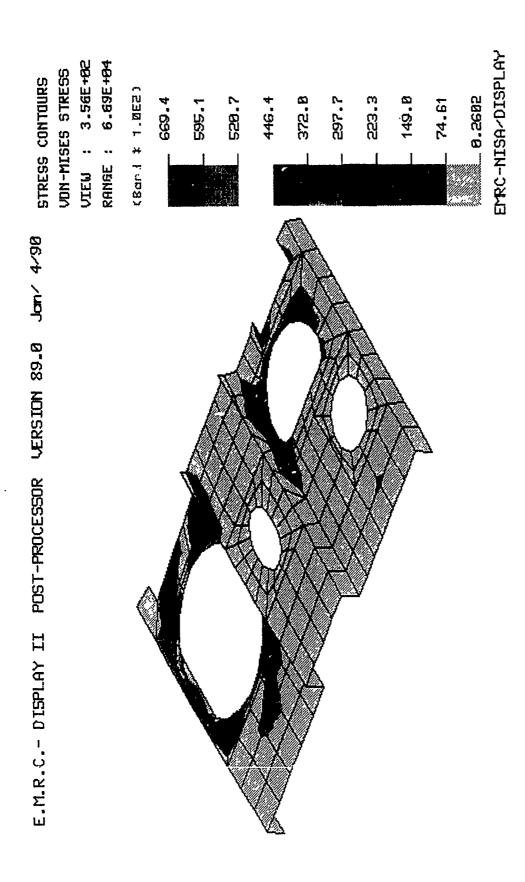


ATTO NISA MODEL FIRING LOAD

RX= -58 RY= 0 RZ= 30 ν,







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Z RX= -69 X RY= 9 RZ=-138

FIG 27
NISA STRFSS RESULTS-TOP PLATE
39

4.2.5 Trunnion Model

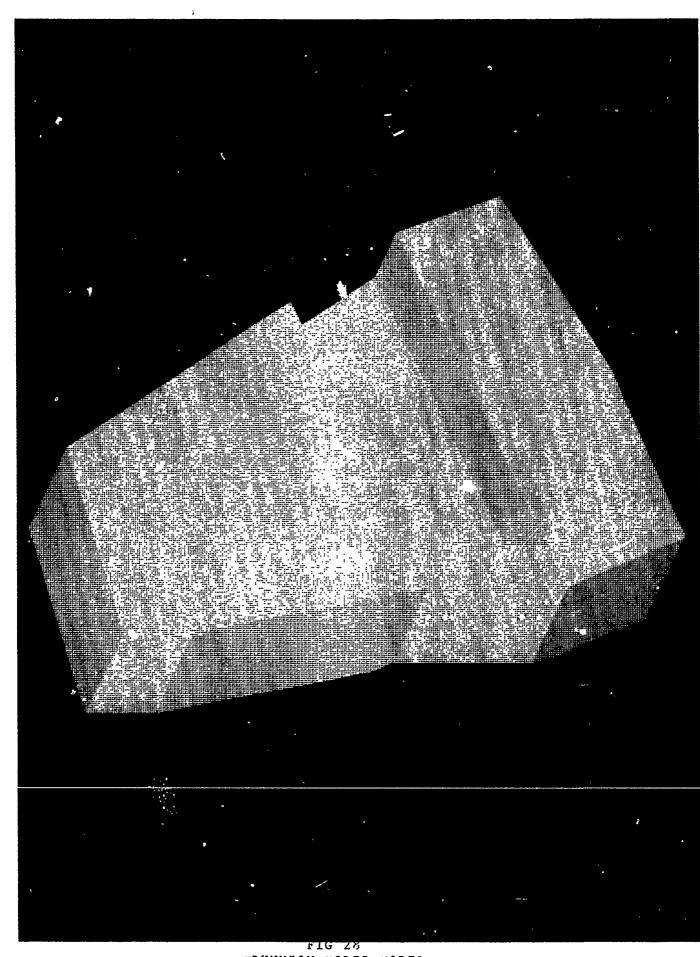
Preliminary turret stress analysis indicates high stress in the trunnion area (44,000 PSI). Since the trunnion strength will be reduced by the 8 holes (necessary to accommodate the mounting bolts), a detailed stress analysis for the trunnion is needed. For this, a solid finite element model for the trunnion was built (Fig. 28 & 29). This model consists of 1860 eight-noded solid brick elements and each node has three degrees of freedom (translation in x, y and z directions). The trunnion was constrained at the location of the turret casting and top plate.

4.2.6 Trunnion Load

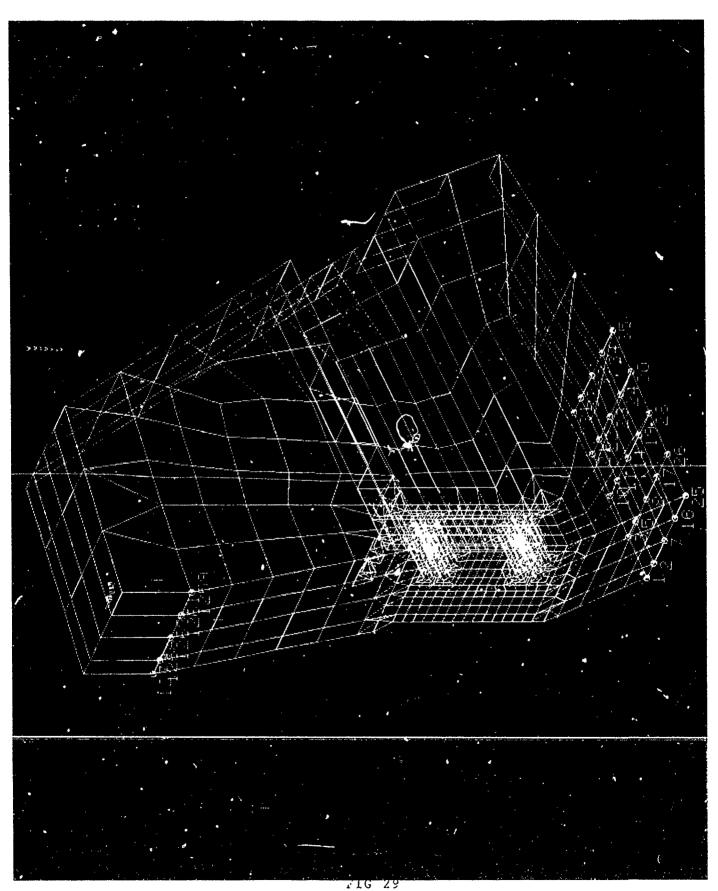
The gun firing force is (375,000 lb). If this force increased by dynamic load factor of 2 (To account for the transient nature of load application), then each trunnion must transmit 375,000 lbs to the turret casting and top plate. This force is applied at the depth of the slot provided for mounting the gun block. The gun mounting block had to be secured by 8 mounting bolts to the trunnion to prevent any movement due to rebound effects. To accomplish this, it is necessary to torque the load mounting bolt so that the total pretension in them can resist the rebound recoil force. This pretension force is a compressive force applied at the perimeter of each mounting-bolt hole. A pretension load of 3200 lbs per bolt was used. This will give a 50,000-lb resistance or about 14% of the recoil force.

4.2.7 Trunnion Analysis Results

The maximum VON mises stress is 57,000 PSI, and it occurs just below the surface of the inner face of the trunnion at the edge of the slot for mounting the gun block (Fig 30). A detailed stress plot for this area is shown in (Fig 31). The maximum stress due to pretension load of 3200 lb/bolt is in the range of 4000-5000 PSI, as shown in (Fig 32). Maximum horizontal deformation is 0.022 inches, as shown in (Fig 33). To keep stresses and deformations at their current level. The distance between slot and trunnion edges had to be increased from 3.0 to 3.75 inches, and trunnion thickness was increased from 4.5 to 5.5 inches as a result of this analysis.



TRUNNION SOLID MODES.
41



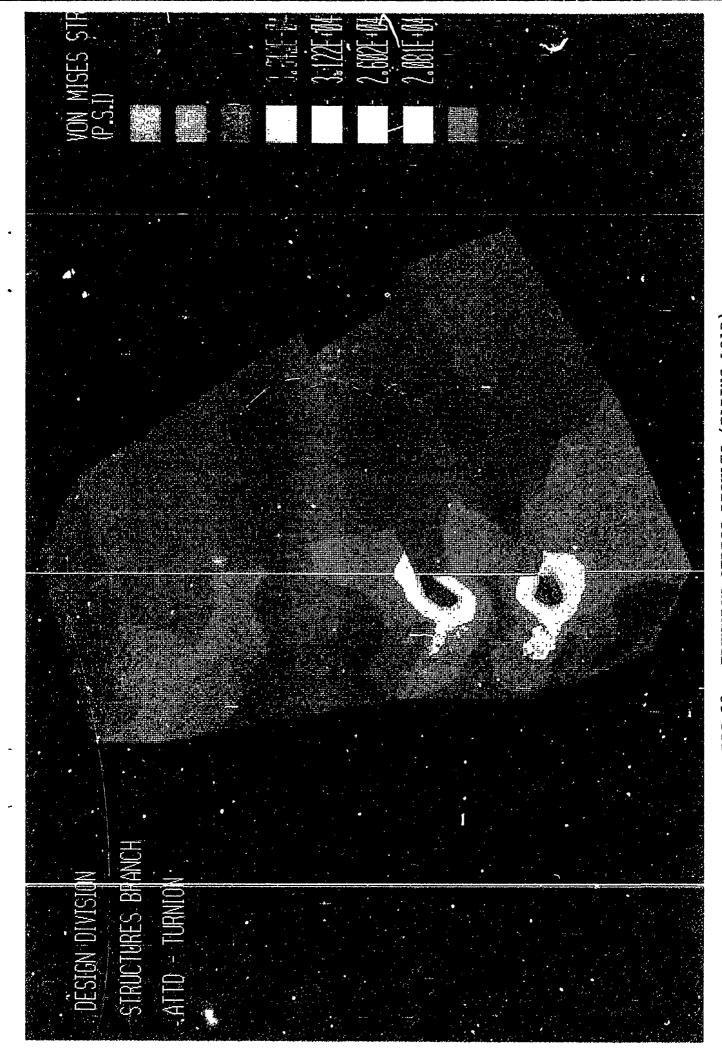


FIG 30 - TRUNNION STRESS RESULTS (FIRING LCAD)

LOAD)

4.2.8 Turret and Hull Castings

The turret and hull casting, are complicated parts and their interaction through the race ring deserves a separate study by itself. To represent turret and hull casting in this study in the best possible way some simplifications were necessary. The turret race ring was replaced in the FEM Model with a stiff truncated cone (2.5 inches thick). This allowed the forces to be transferred from the turret to the hull with minimum deformations. The hull casting configurations in the finite element model were obtained in such a way that the hull casting FEM model has the same mass properties obtained for the 3D solid model available on the Intergraph CAD System and obtained utilizing EMS.

4.2.9 Casting Analysis Results

Stresses and deformation for the turret and hull castings were extracted from the total chassis results for the following two cases:

4.2.9.1 Gun Firing At 0 degrees Horizontal

Maximum VON mises stress in the turret and hull casting is in the range of 30,000 PSI as shown in Fig (34 - 36). Stresses in these casting around the trunnion area are shown in Fig (37 & 38). Vertical deformation plots are shown in Fig (39).

4.2.9.2 Gun Firing at 90 degrees Horizontal

Max VON mises stress is 36,000 PSI as shown in Fig (40 & 41). Lateral displacement are shown in Fig (42). Stresses in trunnion and hull casting and around road where no 3 are shown in Fig (43).

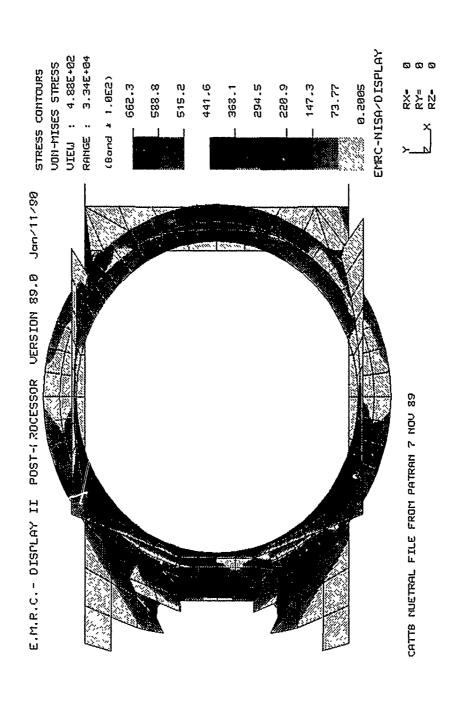
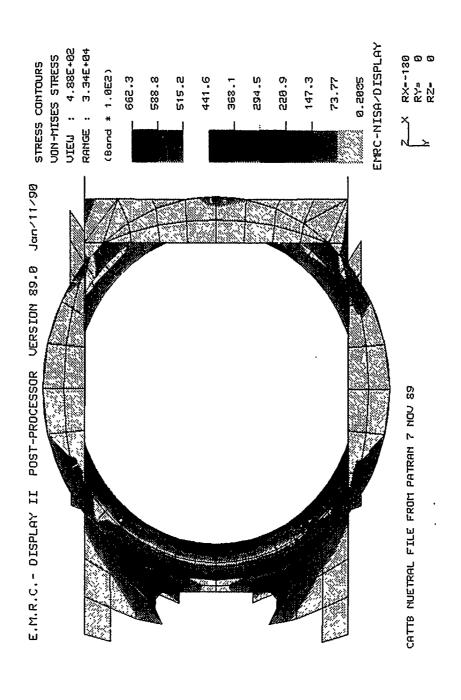


FIG 34 STRESS IN TYRRET AND HULL CASTINGS-GUN FIRING AT U 48

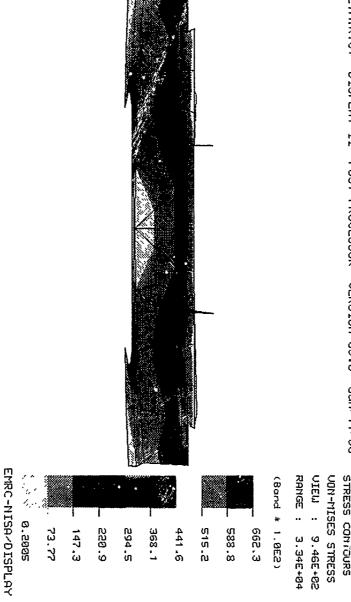


FIC 35 STRESS IN TURRET AND HULL CASTINGS-GUN FIRING AT 0 $^{\circ}$

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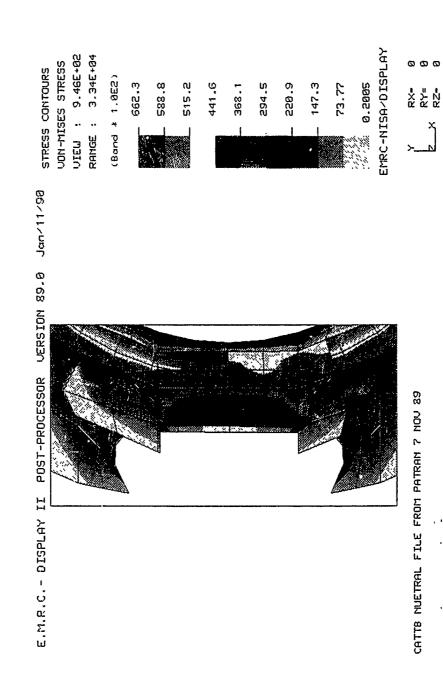
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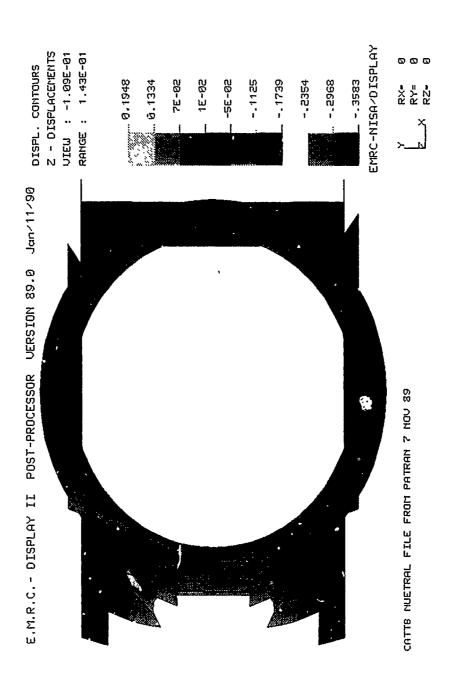
RY= -98 RZ- -98



STRESS IN TURRET AND HULL CASTINGS-GUN FIRING AT 0 $^{\circ}$

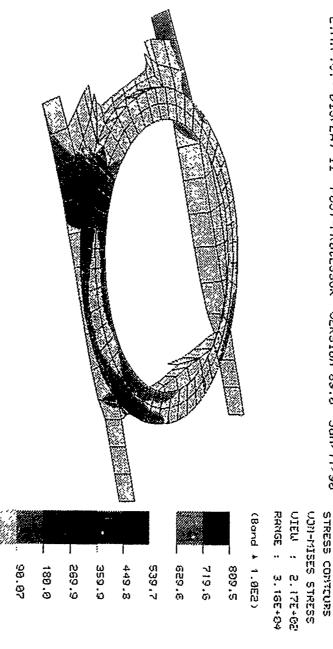
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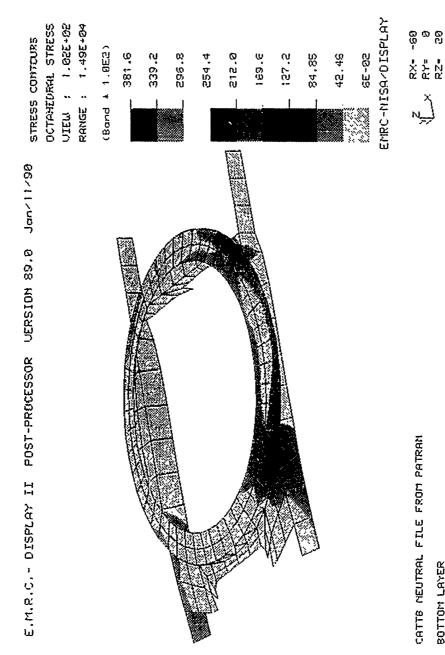
BOTTOM LAYER

CATTB NEUTRAL FILE FROM PATRAN

EMRC-NISA/DISPLAY

0.1351

RX: -60 RY: 8



CATTE NEUTRAL FILE FROM PATRAN BOTTOM LAYER

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U DISPL. CONTOURS
Y - DISPLACEMENTS
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RANGE : 2.47E-01

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- 0.2797

- 0.2016

- 0.2016

- 0.1625

- 0.1634

- 0.1634

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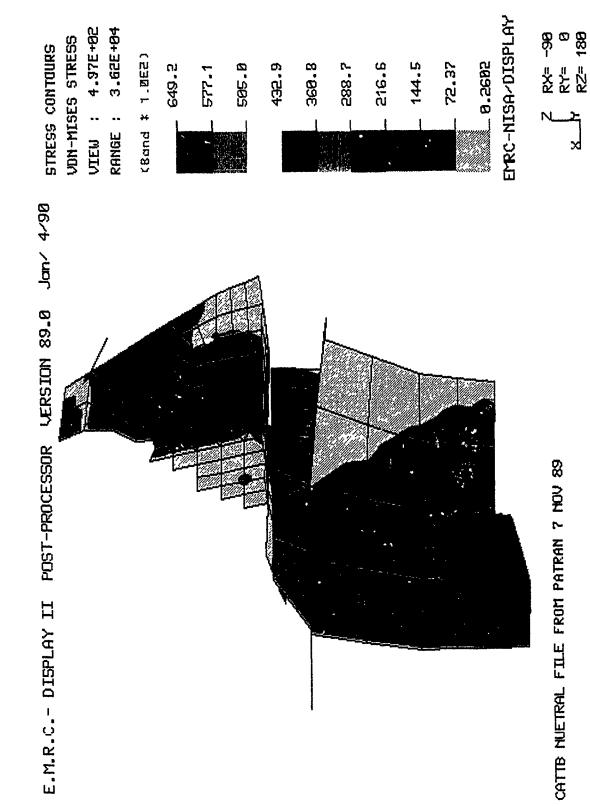
- 0.1634

- 0.1634

RX- -69 X RY= 8 RZ- 28

BOTTOM LAYER

CATTB NEUTRAL FILE FROM PATRAN



STRESS IN TURRET AND HULL CASTINGS-57

4.2.10 Hull Model

The M1A1 hull will be used and modified where necessary to assure strength and space utilization. The hull finite element model was created using IRM software in similar fashion to turret FEM model. A wire frame was created from a 3D solid model available on the Intergraph CAD System. Then this wire frame was translated to IGDS and transferred to the VAX computer to serve as a skeleton for the finite element model Fig (44). Thickness of the various plates are shown in Fig (45). The hull was constrained in the vertical direction at all roadwheel attachment points. In the horizontal direction, the hull was constrained at the attachment points of the roadwheels 1 and 7, to maximize the bending effects in the chassis due to lateral loads.

4.2.11 Hull Loads

The reaction forces in the 48 mounting bolts found in the FEM turret analysis (Appendix C) was applied on the hull model and analyzed. The results indicated high stress (130,000 PSI) in the hull top plate around the trunnion area. In this preliminary analysis, the interaction between the turret and hull was not considered, resulting in high stress. To represent the real situation, this interaction must be considered. For this, it was necessary to merge turret FEM model with hull FEM model resulting, in chassis FEM model Fig (46 & 47). This model will be analyzed as one entity.

4.2.12 Hull Analysis Results

Gun-firing load was applied to the chassis FEM model, and the results are as follow:

4.2.13.1 Gun Firing at O degrees Horizontal

Stresses in the hull are in the range of 60,000 PSI, as shown in Fig (48).

4.2.12.2 Gun Firing at 90 degrees Horizontal

To investigate this case, another CATTB FEM model had to be created by rotating the turret 90 degrees as shown in Fig (49). This model was analyzed, and the hull stresses are in the range of (95,000 - 130,000) PSI Fig (50 & 51). Depending on the number of roadwheel attachment points constrained in the lateral direction (7 and 2 respectively), the hull lateral deformation for these two ranges from 0.16 - 0.25 inches, as shown in Fig (52). The hull's deformed shape are shown is Fig (53).

It is worthwhile to note that shear stress in the hull (36,000 PSI) is closer to its yield limit (50,000 PSI) than bending stress (65,000 PSI) to its yield limit (100,000 PSI). This is due to the dominant shear behavior in the trunnion, turret, and hull casting near the trunnion area. Chassis deformed shapes are shown in Fig (68 & 69).

4.2.13 Hull Modification (1)

Hull stresses and deformations were excessive, and the hull had to be strengthened. This was accomplished by eliminating the blow-off panel in floor plate and by reducing the size of the opening in the middle bulkhead as shown in Fig (54).

4.2.14 Hull Analysis Results

After these modifications, the chassis was analyzed again. The stresses were reduced to (70,000 - 90,000) PSI Fig (55 & 56), and the lateral deflection were reduced to 0.15 - 0.2 inches Fig (57 & 58) for the two cases of roadwheel attachment points constraints mentioned previously.

4.2.15 Hull Modification (2)

Stresses and deformations are still reasonably high. The hull had to strengthened in the lateral direction. This was accomplished by extending the hull casting plate between the two side-plates as shown in Fig (54).

4.2.16 Hull Analysis Results

Stresses were reduced to the 45,000 PSI range and deformation to 0.10 inches Fig (59 & 60). These values are over-estimated due to the simplicity of contraints assumption. In reality, all seven roadwheels resisted lateral displacement to a varied degree. To understand this behavior, a dynamic analysis is required when the turret is rotated 90 degrees.

4.2.17 Hull Modifications (3)

It was found necessary to reduce the height of the rear bulkhead, in order to be able to install the Auto Loader. The rear bulkhead contribute to hull's lateral strength. To study the effects of the bulkhead height on the chassis strength and stiffness, the bulkhead height was varied (from 33 to 20 & 13 inches).

4.2.18 Hull Analysis Results

Stresses in the hull were observed and are shown in Fig (61 - 63, & 67). Deformations are shown in Fig (64 - 67). The results indicated that the rear bulkhead height could be reduced to half of its original height before any significant reduction in hull strength and stiffness could be observed.

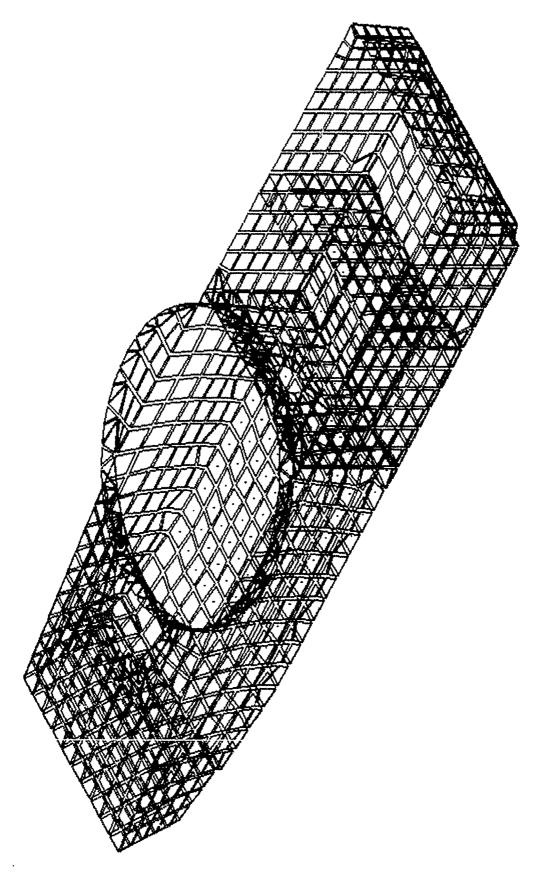
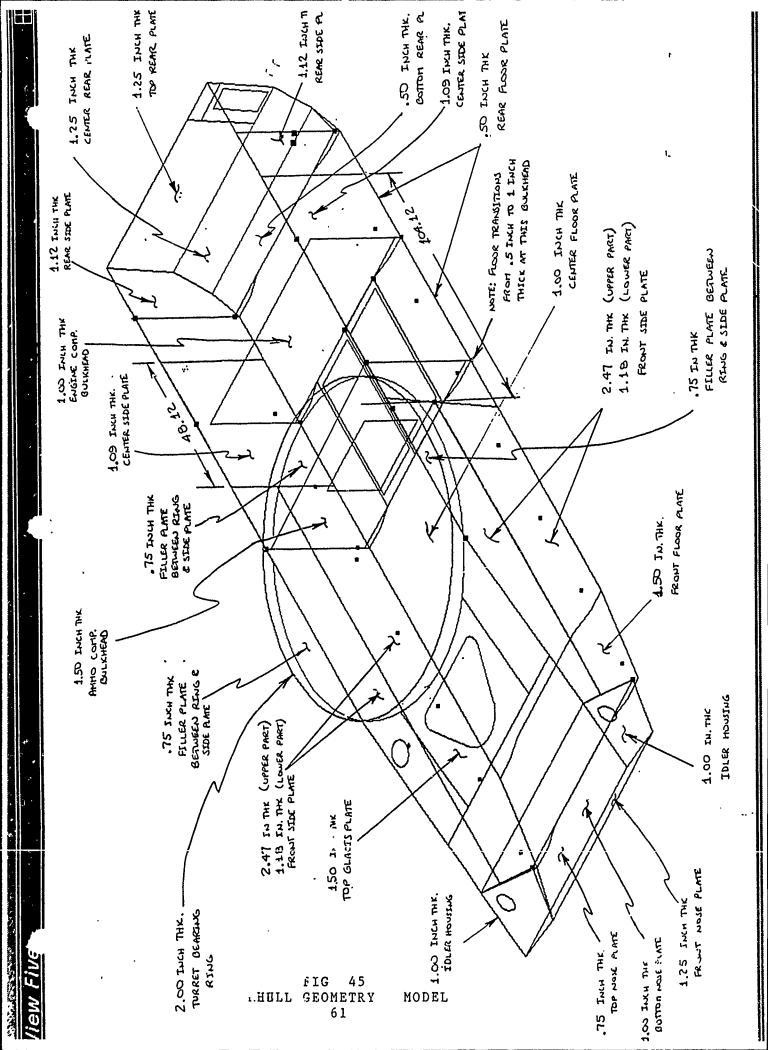


FIG 46 MULI FEM MODE: 60



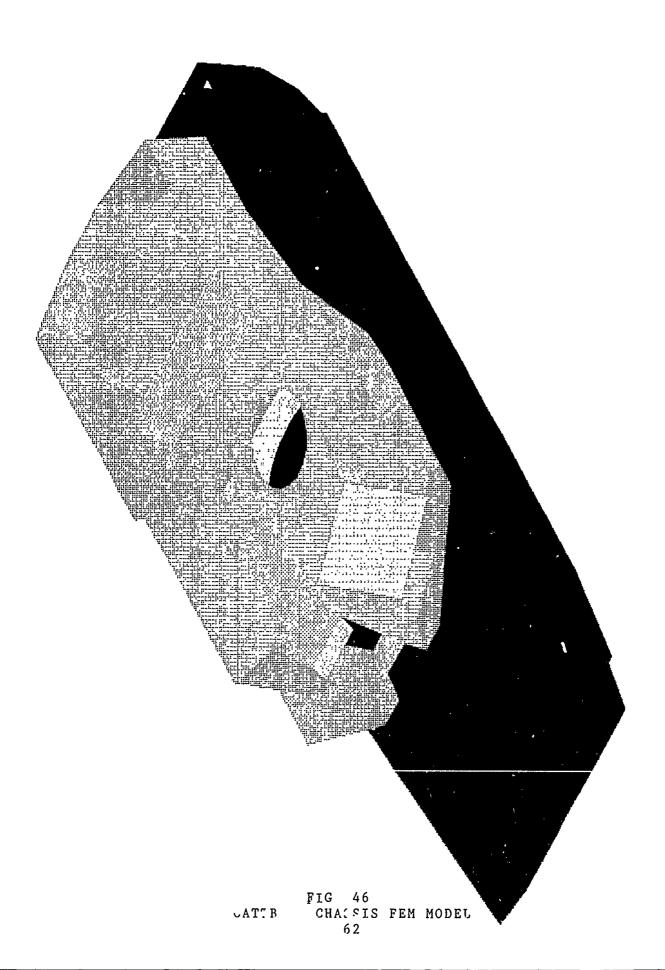


FIG 47 CATTB CHASSIS FEM MODEL 63



























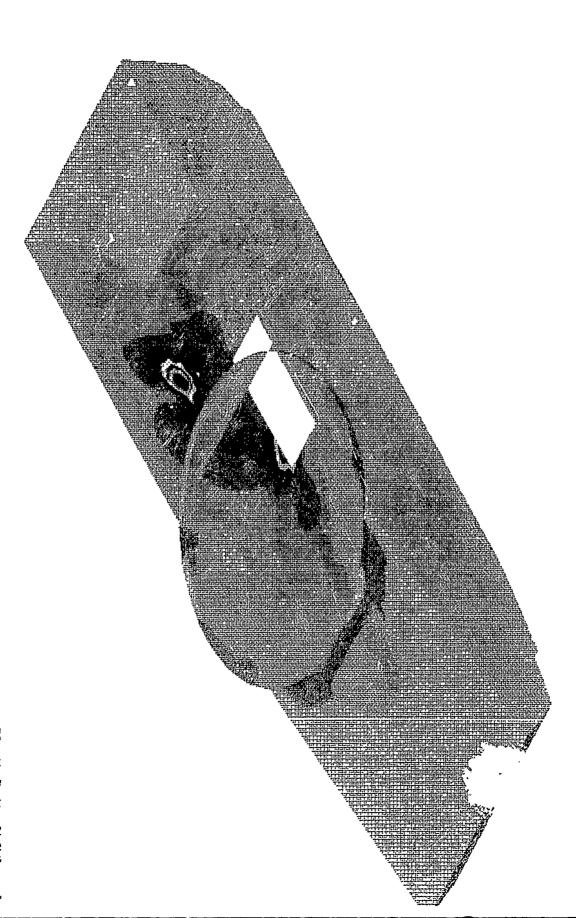


FIG 49 CATTB CHASSIS FEM MODEL (TURRET ROTATED 90°)

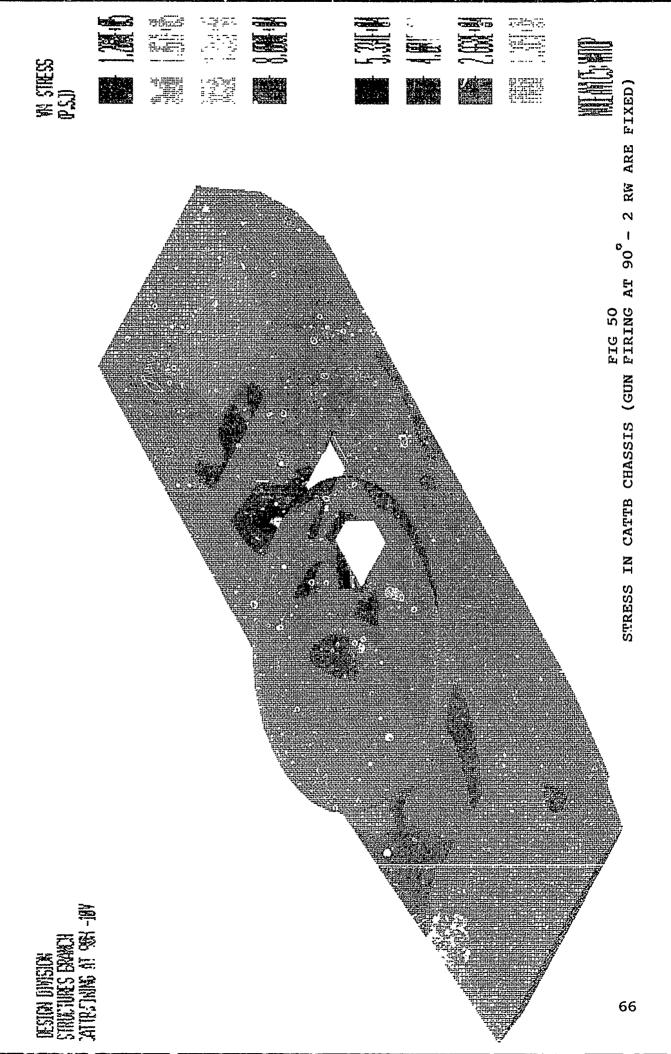
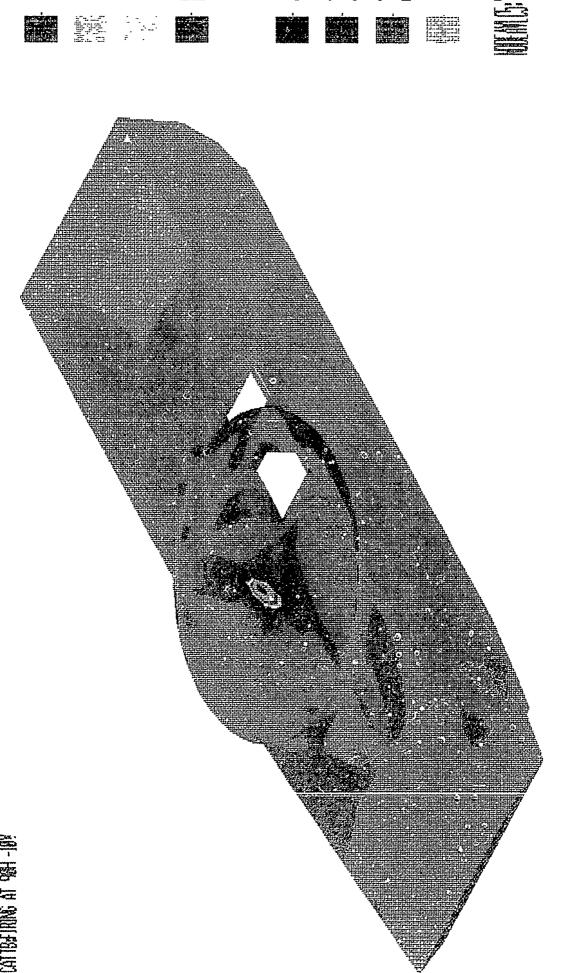
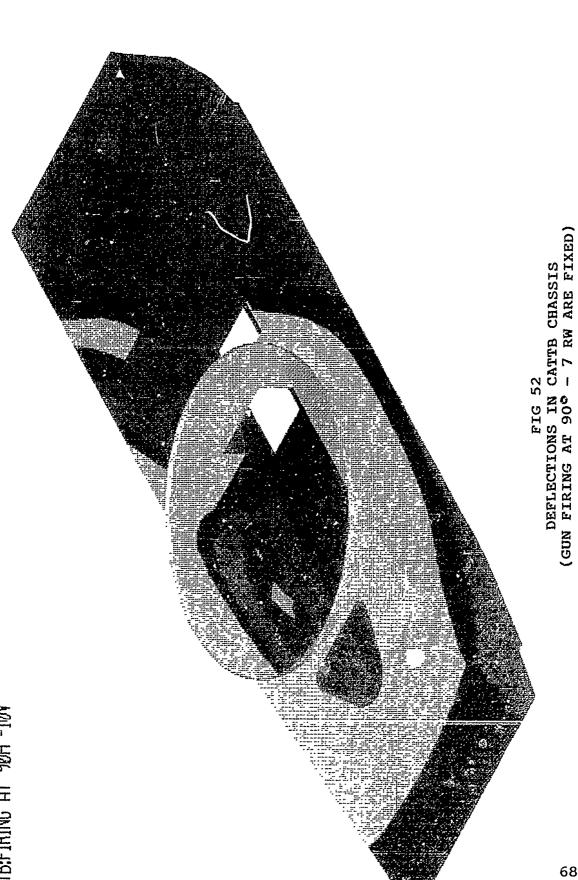


FIG 51 STRESS IN CATTB CHASSIS (GUN FIRING AT 90 - 7 RW ARE FIXED)



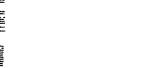
VA STRESS P.S.D

ESION DIVISION TRUETURES BONNEY



LATERAL DEF



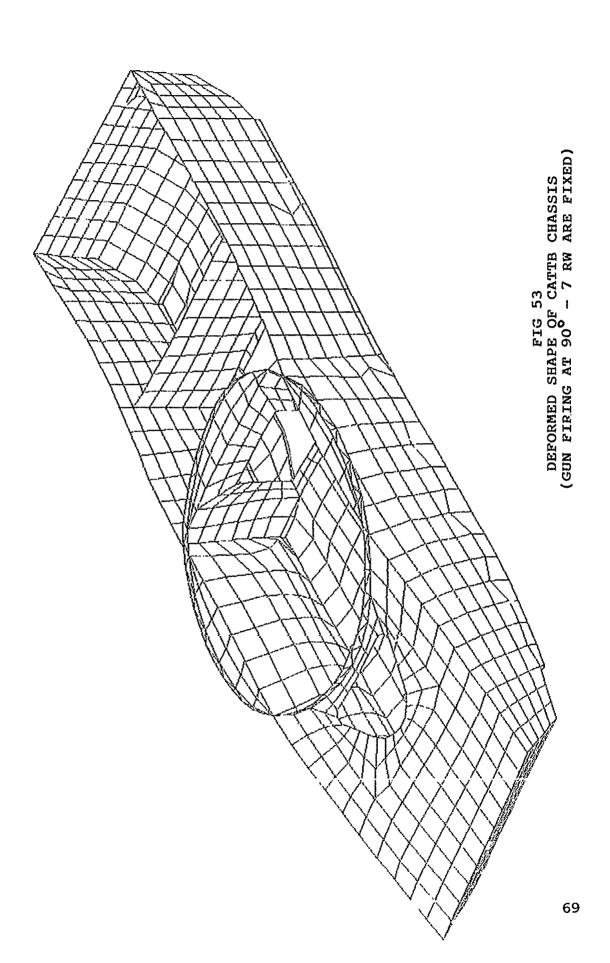


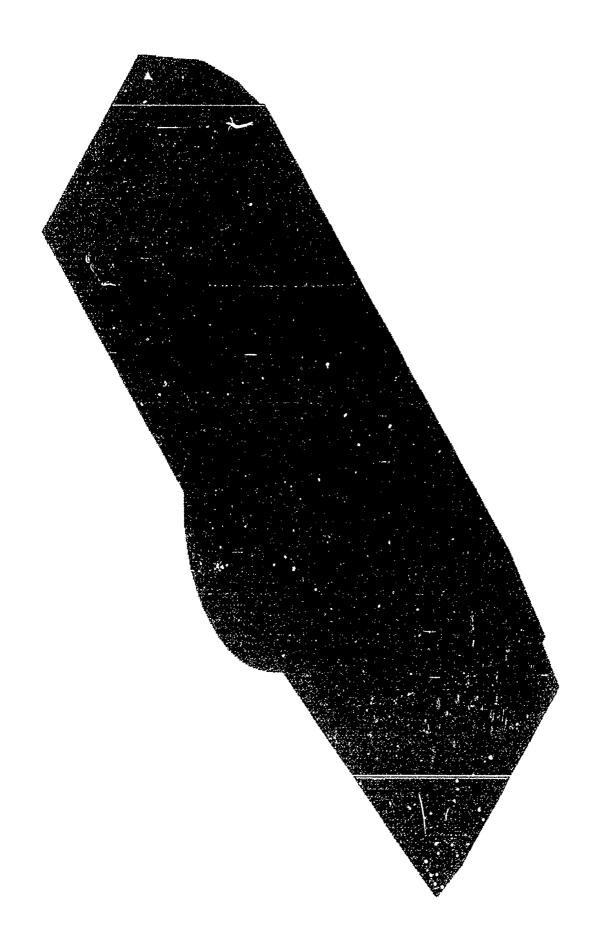




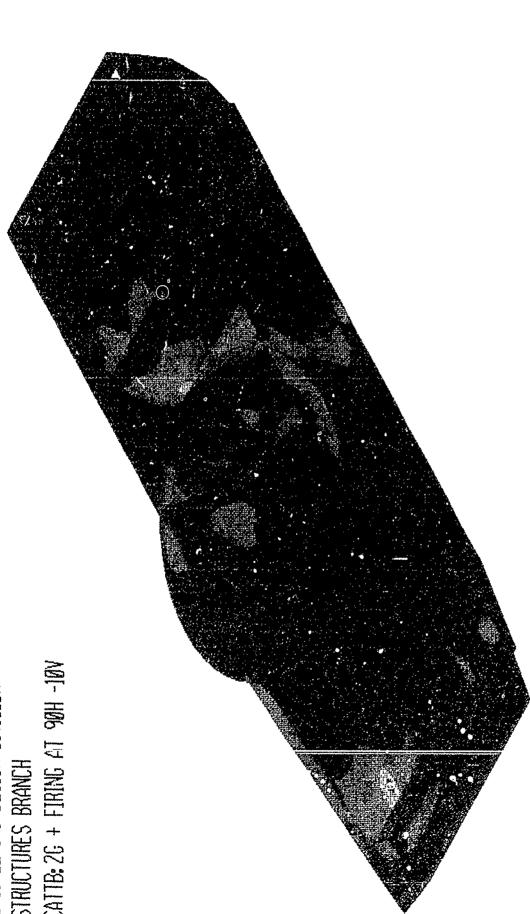












VM STRESS (P.S.I)











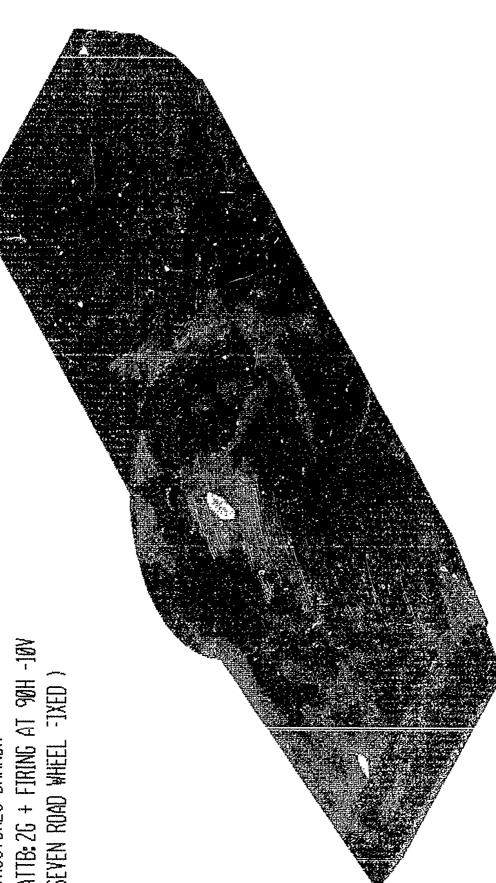








VM STRESS (P.S.I)



STRESSES IN MODIFIED GUN FIRING AT 900 -

DEFLECTION IN MODIFIED (1) CATTB HULL (GUN FIRING AT 90° - 2 RW ARE FIXED)

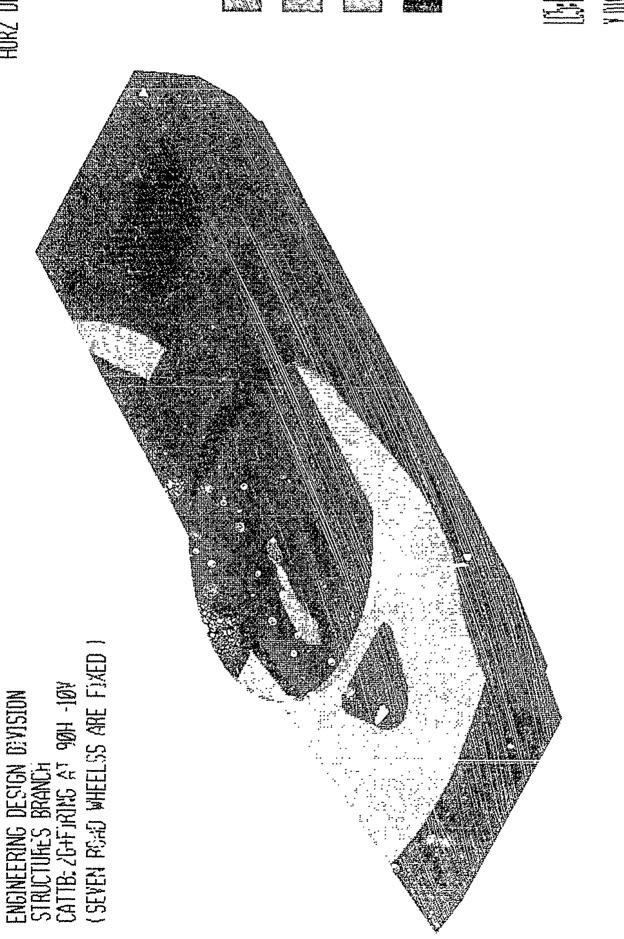
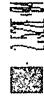


FIG 58
DEFLECTION IN MODIFIED (1)CATTB HULL (GUN FIRING AT 90° - 7 RW ARE FIXED)

and and provided in the control of t















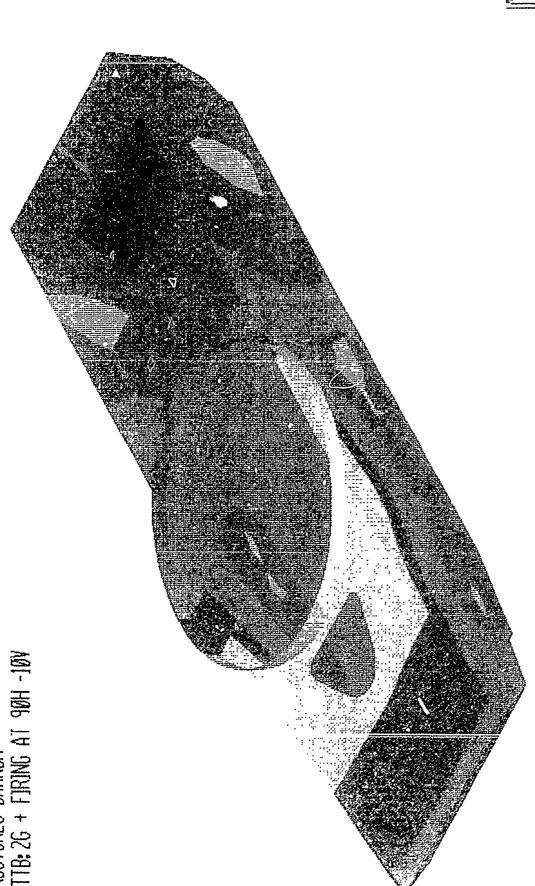






LATREAL DEF (IN)





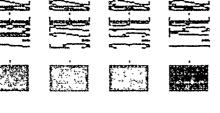


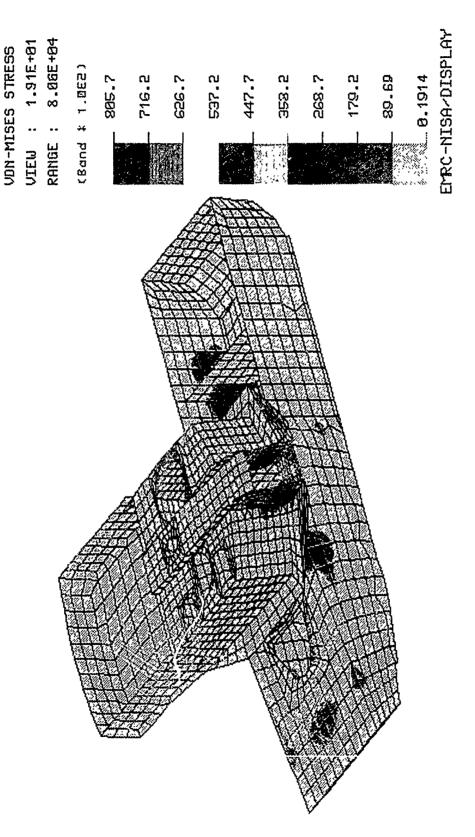


FIG 60 MODIFIED (2)CATTB HULL 90° - 7 RW ARE FIXED)

DEFLECTIONS IN (GUN FIRING AT

Dec/18/89 LERSION 89.0 POST-PROCESSOR E.M.R.C.- DISPLAY II

STRESS CONTOURS



CATTB NEUTRAL FILE FROM PATRAN TOP LAYER

STRESSES IN MODIFIED (3) CATTB HULL (GUN FIRING AT 90° - 7 RW ARE FIXED)

EMRC-NISA/DISPLAY 3.86E+84 1.91E+81 **UDN-MISES STRESS** STRESS CONTOURS (Band # 1.8E2) 886.B 716.4 626.9 537.4 447.8 358.3 179.2 89.75 3 B. 1912 268.8 VIEW : RANGE Dec/20/89 **LERSION 89.0** POST-PROCESSON E.M.R.C. - DISPLAY II

FIG 62 STRESSES IN MODIFIED (3)CATTB HULL (GUN FIRING AT 90 - 7 RW ARE FIXED)

CATTB NEUTRAL FILE FROM PATRAN

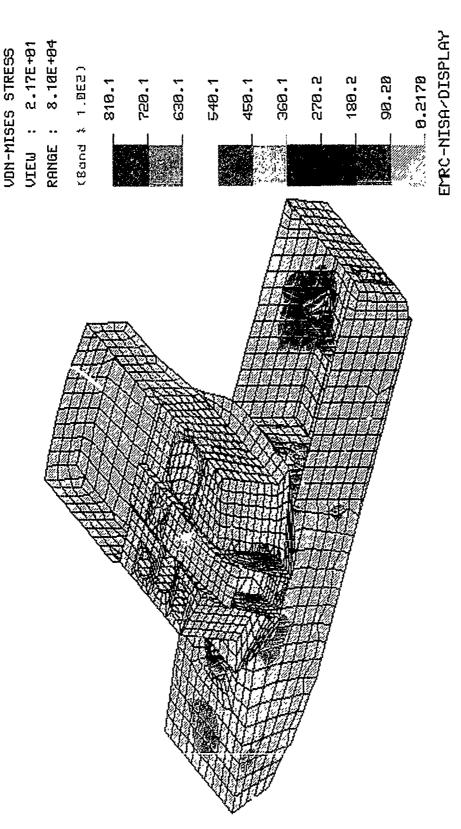
TOP LAYER

RX= -68 RY= 8 RZ= 38

ΝŽ

Jan/ 5/98 POST-PROCESSOR VERSION 89.0 E.M.R.C.- DISPLAY II

STRESS CONTOURS



CATTB NEUTRAL FILE FROM PATRAN BOTTOM LAYER

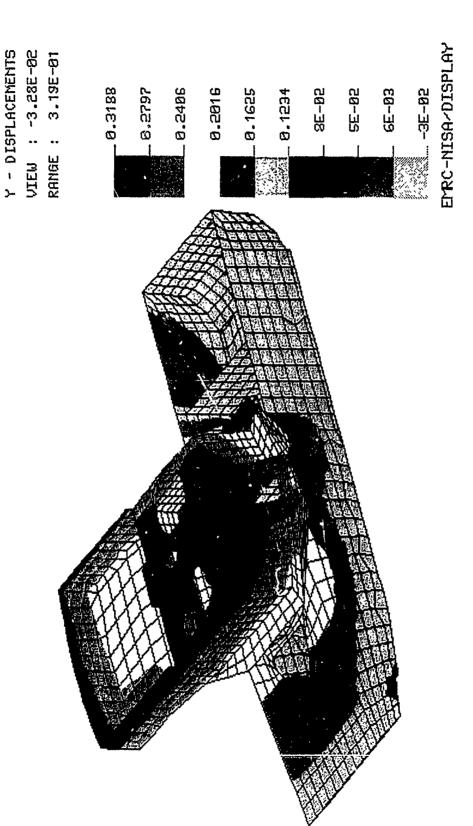
Z RX= -69
Y RY= 9
X RZ= -39

STRESSES IN MODIFIED (3) CATTB HULL (GUN FIRING AT 90° - 7 RW ARE FIXED)

on the colorest from the setting the setting of the

LERSION 89.0 Dec/18/89 POST-PROCESSOR E.M.R.C. - DISPLAY II

DISPL. CONTOURS



CATTB NEJTRAL FILE FROM PATRAN

MIDDLE LAYER

FIG 64
DEFLECTIONS IN MODIFIED (3) CATTB HULL (GUN FIRING AT 90° - 7 RW ARE FIXED)

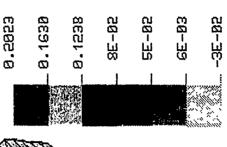
7 RY= -60 7 RY= 0 7 RZ= 38

80

Dec/28/89 LERSION 89.0 POST-PROCESSOR E.M.R.C.- DISPLAY II

Y - DISPLACEMENTS VIEW : -3.30E-82 RANGE : 3.20E-81 DISPL, CONTOURS





CATTB NEUTRAL FILE FROM PATRAN

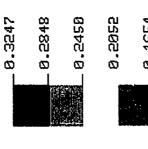
⁴ζ RX= -68 4 7 RY= 8 RZ= 38

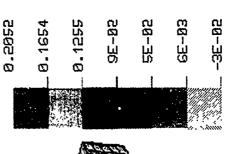
EMRC-NISA/DISPLAY

FIG 65 MODIFIED (3)CATTB HULL 90° - 7 RW ARE FIXED) DEFLECTIONS IN (GUN FIRING AT

Jan/ 3/98 POST-PROCESSOR LERSION 89.0 E.M.R.C.- DISPLAY II

Y - DISPLACEMENTS UIEW : -3.38E-02 3.25E-01 DISPL. CONTOURS RANGE:





EMRC-NISA/DISPLAY

CATTB NEUTRAL FILE FROM PATRAN BOTTOM LAYER

DEFLECTION IN MODIFIED (3) CATTB HULL (GUN FIRING AT 90 - 7 RW ARE FIXED) FIG 66

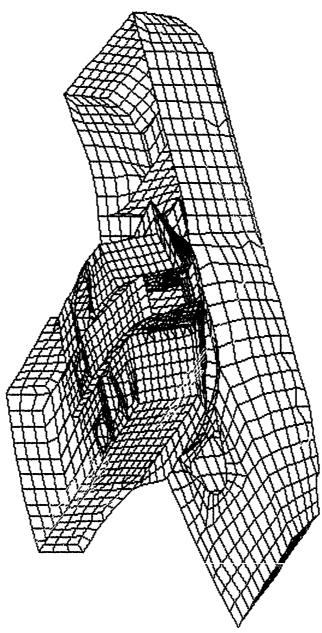
EMRC-NISA/DISPLAY OCTAHEDRAL STRESS 3.825+84 STRESS CONTOURS (8and # 1.8E2) 338.5 212.2 84.96 42.53 254.7 127.4 9.1846 381.9 297.1 169.8 VIEW : RANGE: E.M.R.C.- DISPLAY II POST-PROCESSOR VERSION 89.0 Dec/20/89

SHEAR STRESS IN MODIFIED (3)CATTB HULL (GUN FIRING AT 90° - 7 RW ARE FIXED)

99 98

E.M.R.C.- DISPLAY II POST-PROCESSOR VERSION 89.0 Dec/18/89

DISPLACED - SHAPE
MX. DEF- 4.29E-01
NNDE NUMBER= 1737
SCALE = 2.0
KMAPPED SCALING)



CATTB NEUTRAL FILE FROM PATRAN

MIDDLE LAYER

KX= -68 X RY= 9 RZ= 38

FIG 68
DEFORMED SHAPE FOR CATTB CHASSIS
(GUN FIRING AT 90° - 7 RW ARE FIXED)

<u>A DE LA ELLE MONTO DE LA TRESTA A ALTERNATION DE PORTO DE LA PORTO DE LA CONTRACTOR DE LA TRACTOR DE LA CONTRA</u>

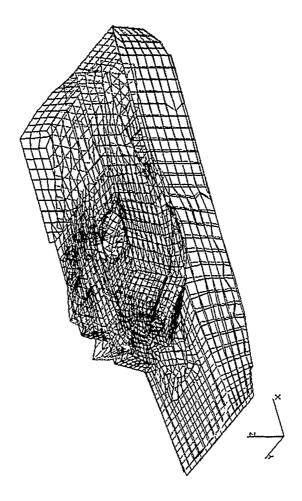


FIG 69
DEFORMED SHAPE FOR CATTB CHASSIS
(GUN FIRING AT NORMAL POSITION)

A separate finite element model was built exclusively to study the stress behaviour of the sponsons and skirts and to study the interaction between them and the outriggers. Sponson and skirt model consist of 720 plate elements (eight noded quad and 6 noded triangle), were used to model the outriggers, and 142 beam elements were used. Total number of the FEM active nodes for the whole model is 1136. Each node has six Degrees of freedom-three rotations and three translations. Thickness of the sponson plates are 0.50 in., whereas the skirts and the various bulkhead are 0.31 in. thick. The various outriggers consist of 1.5 in. Dia tube. The sponsons are constrained at the nodes coinciding with the location of the main side plates.

The load on the sponsons bottom plate consist of the weight of six batteries and the weight of the NBC unit and the various control boxes. This load is 800 lbs. and distributed over an area of 25×60 sq in. which represent a uniform pressure of 0.2 lb/in. To study the effect of acceleration effects, a mass density of 0.000732 slug/in. was used.

The finite element model was analyzed using IFEM available at the intergraph work station, because IRM is no longer available on the vax computer. To account for the various forces acting on the sponsons and skirts, a combined case of acceleration load of 12 G, 6 G, and 3 G in the longitudinal, vertical and lateral direction respectively was used.

Fig. (70) shows the finite element model including sponsons covers. The stress for the 1 G lateral case is 13,500 PSI, as shown in Fig. (71). The lateral displacement is 0.3 in., as shown in Fig. (72). The stress due to the compound acceleration is 122,500 PSI Fig. (73). Lateral and vertical deformations are in the range 3 to 4 in. as shown in Fig. (74 and 75). The deformed shape is shown in Fig. (76). It is obvious that stresses and deformations are excessive and the skirts had to be reinforced, this was accomplished by adding a 1.5 in. tube (3/16 in. thick) at the location of the first outrigger. Fig. (77 and 78) show the FEM model without the sponson cover plates. This model was analyzed under the same loading conditions; stresses and deformations were reduced substantially. For the 1 G lateral the stress is reduced to 13,400 PSI and the deflection to 0.4 in. as shown in Fig. (79 and 80). In the case of the combined acceleration, the stress is reduced to 41,000 PSI Fig. (81), and the deformations to 0.5 - 1.2 in. as shown in Fig. (82 and 33); the deformed shape is shown in Fig. (34). By comparison, adding the strut, the stresses and deformations were reduced by more than 70%.

Forces in the outriggers are maximum in the attachment bolt at rear skirt element no. 13 in Fig. (85) from which maximum stresses can be easily obtained as follows:

$$f = \frac{Fx}{A} + \frac{Mz}{Sz} + \frac{My}{Sy}$$

Where

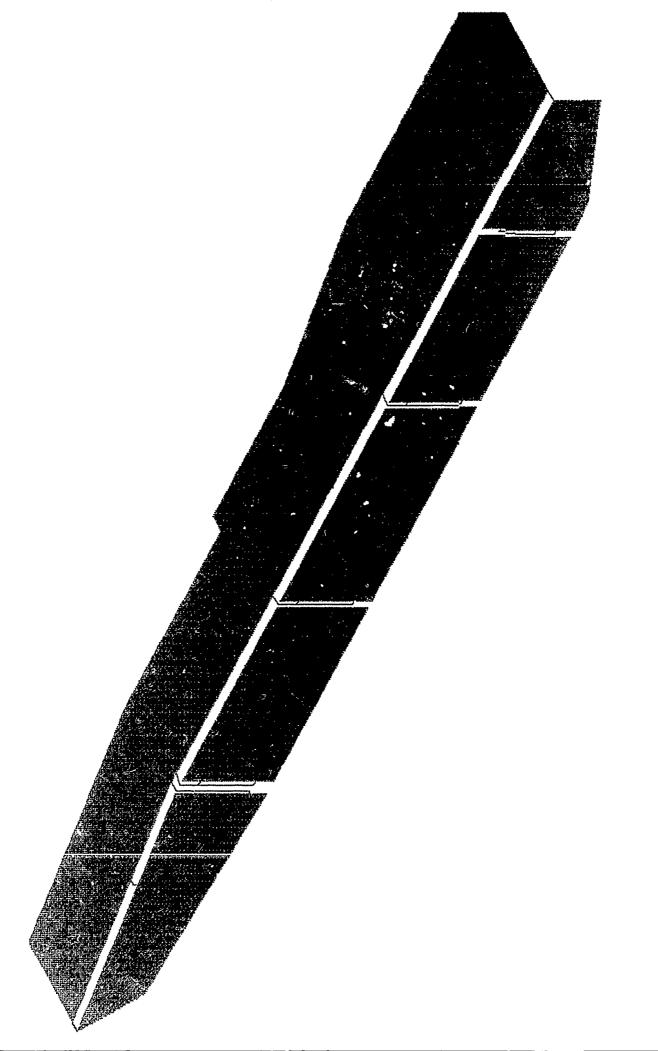
f Maximum Stress (PSI)
Fx Axial Force (lbs)
A Cross Section Area
Sy, Sz Section Modulus About y and z axis
Iy, Iz Moment of Inertia About y and z axis
My, Mz Bending Moments About y and z axis

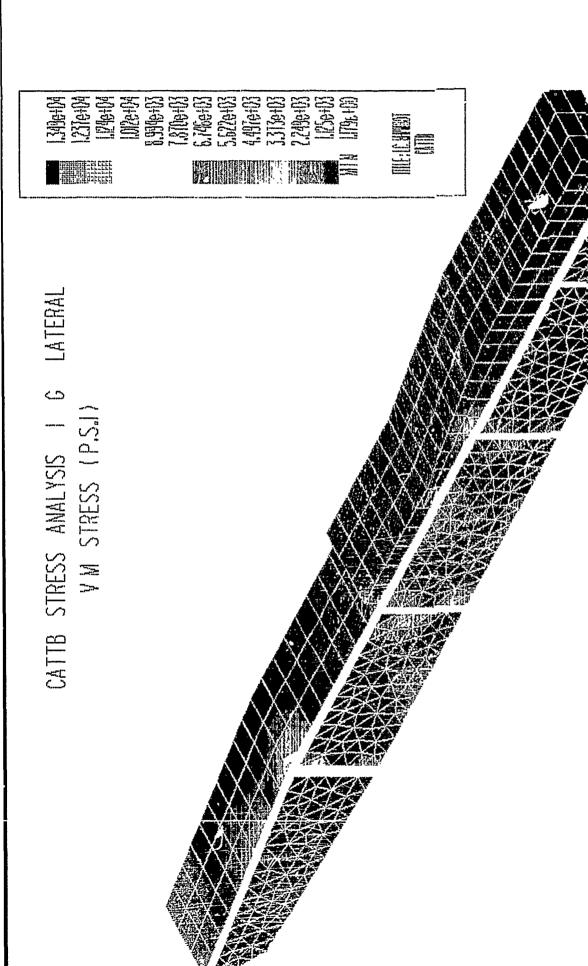
Applying above equation yields

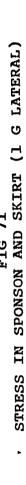
$$f = \frac{72}{0.78} + \frac{5770}{\frac{.05}{0.5}} + \frac{3485}{\frac{.05}{0.5}}$$

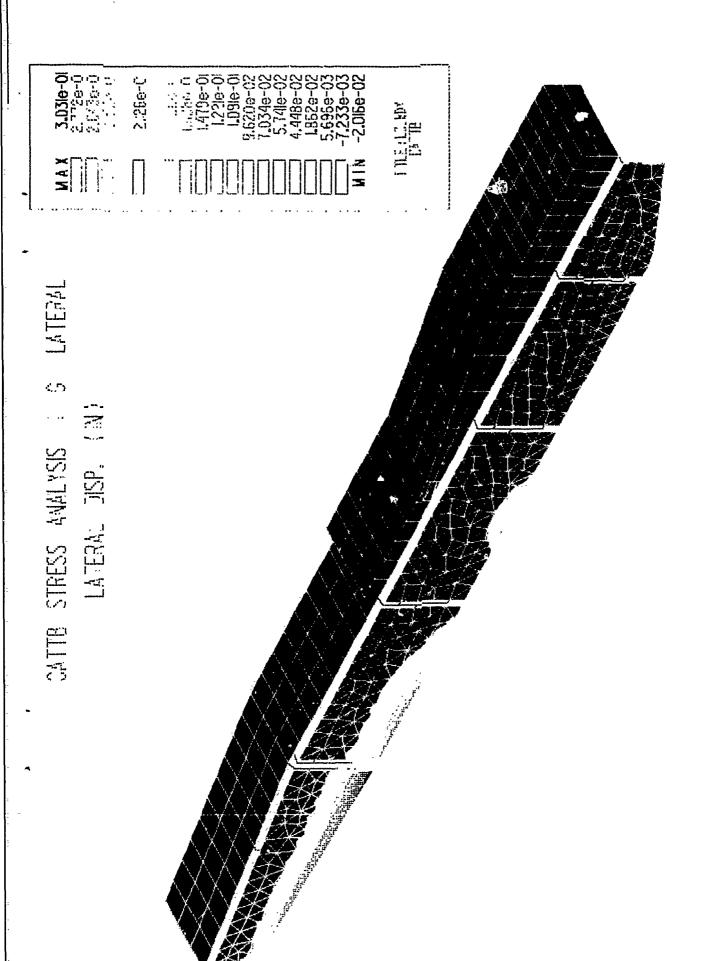
$$= 90 + 57,690 + 34,850$$

$$= 92,630 < Fy = 100,000 PSI$$









8.53.56+04 7.1446+04 6.1246+04 5.1056+04 3.0666+04 1.0286+04 8.5436+04

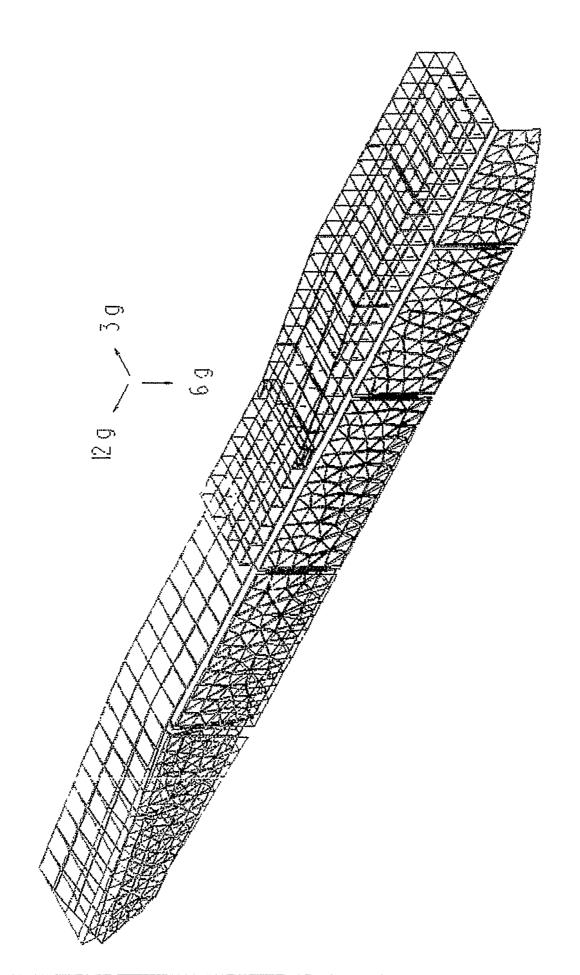
.2246+05 1.1226+05 1.226+05

STRESS ANALYSIS stress (p.s.i)

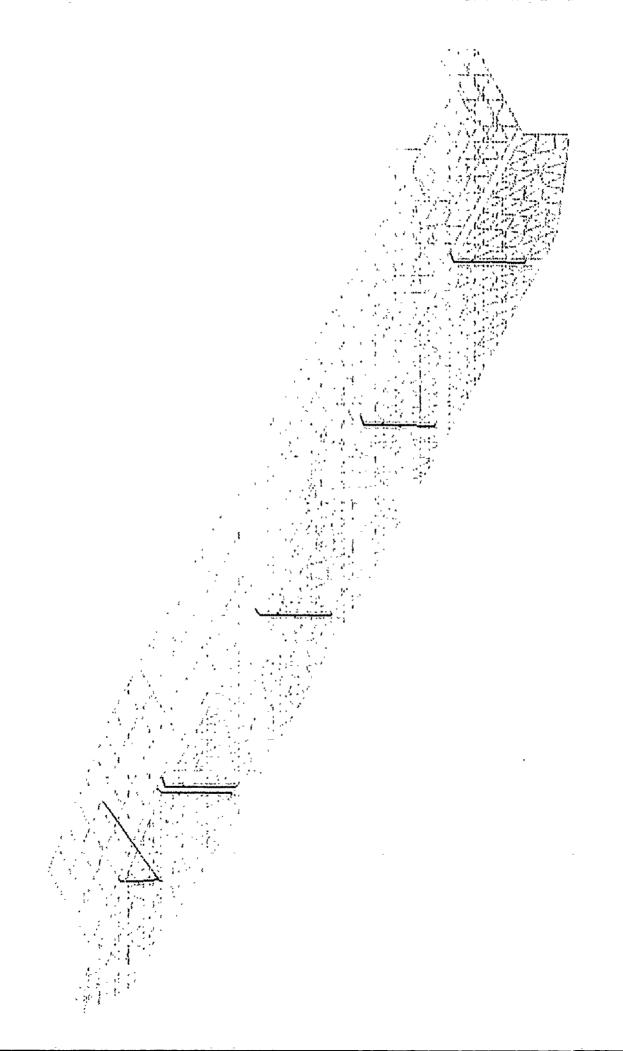
CATTB

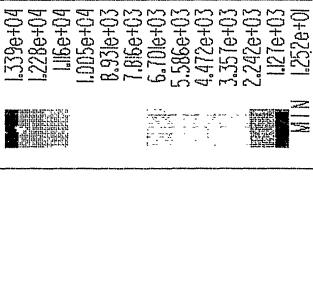
3.182e+04

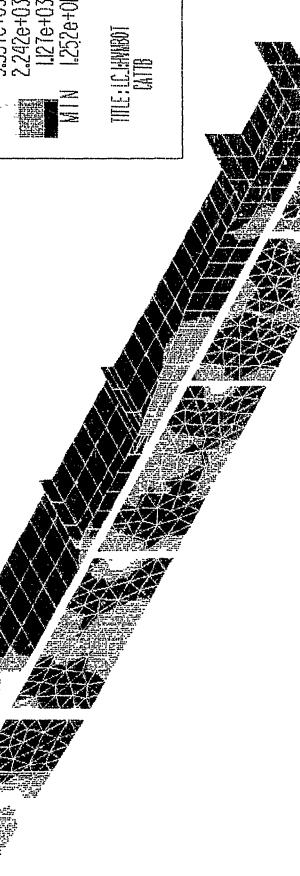
VERTICAL DEFLECTION IN SPONSON AND SKIRT (COMBINED ACCELERATION)



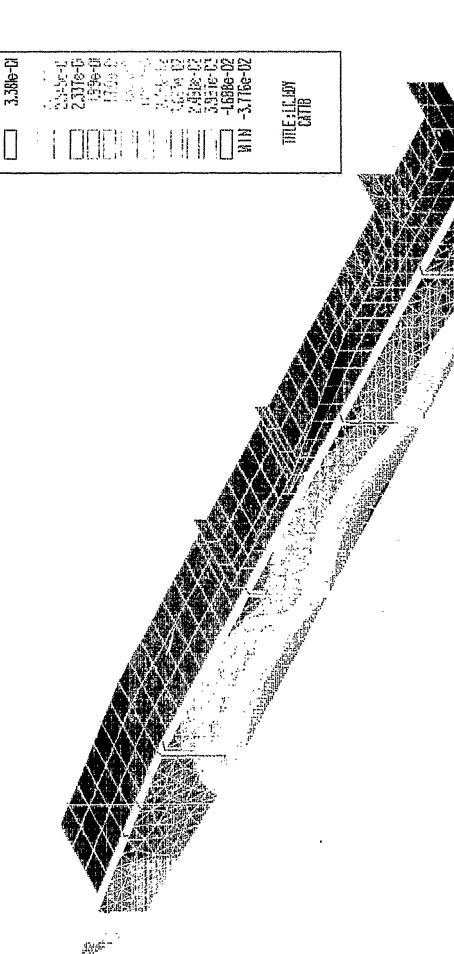
G LEFT SPONSON AND SKIRT FEM MODEL (RETNFORTING STRITT ADDRESS AT STOCKE STRITT ADDRESS AT STRICT ADDRESS AT STRIPT ADDRESS AT STRITT ADDRESS AT STRIPT ADDRESS AT STRI







4.878-0 4.425-1 4.755-1



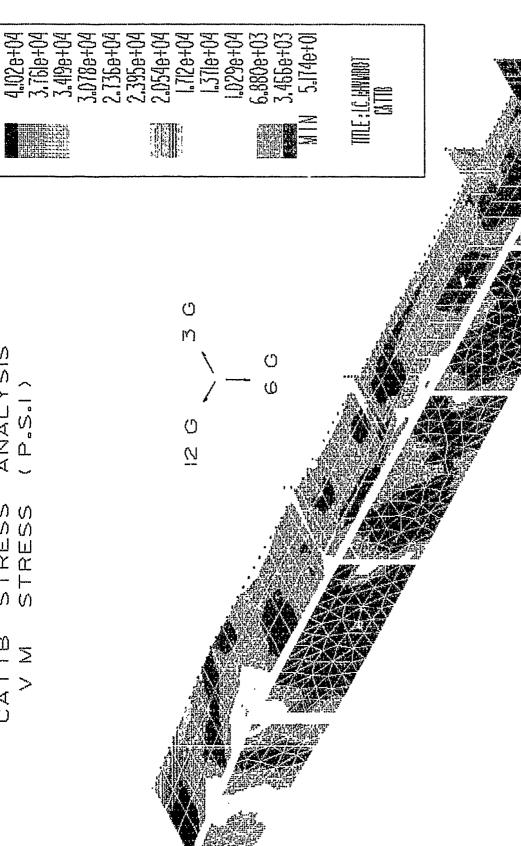
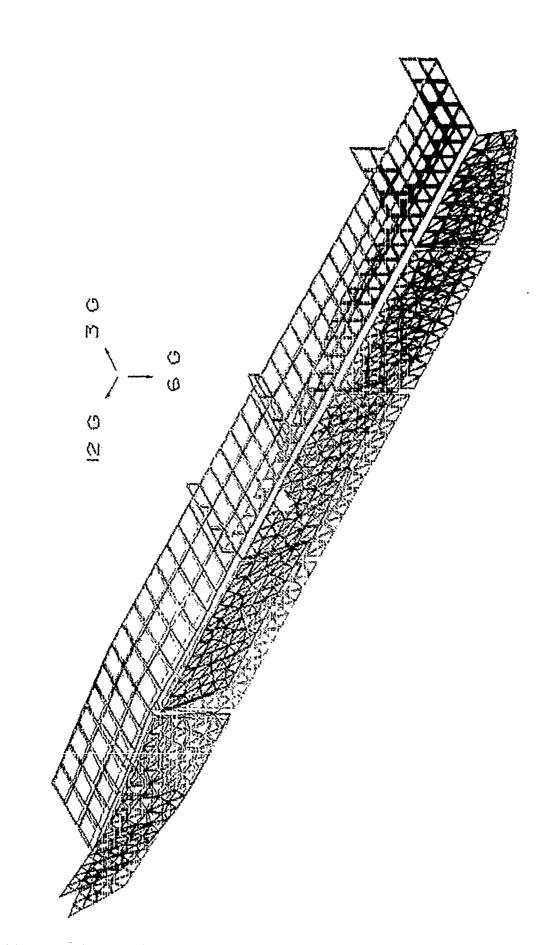




FIG 82
VERTICAL DEFLECTION IN REINFORCED SPONSON AND SKIRT
(COMBINED ACCELERATION)

LATERAL DEFLECTION IN REINFORCED SPONSON AND SKIRT (COMBINED ACCELERATION)

CATTB STRESS ANALYSIS DEFORMED SHAPE



FORCES IN OUTRIGGERS AND STRUT

4.3 Dynamic Analysis

The desire to determine the CATTB geometric and operating characteristics, such as gun, breach displacement, velocity and acceleration, chassis roll and pitch angle and suspension effects on the CATTB chassis due to terrain and firing loads, all necessitate conducting a dynamic analysis for the CATTB. This was accomplished by building a dynamic model and analyzing it, using the DADS program on the Cray supercomputer. This study supplements a concurrent simulation, study prepared by another TACOM directorate, since it mainly deals with the effect of the various dynamic forces on the CATTB Chassis.

4.3.1 DADS Model

To create a DADS model, the geometry of the CATTB chassis had to be established. Road arms, idler and sprocket positions must be established with regard to Chassis CG. This is shown in Figures (86 - 88). The mass properties are established from CATTB solid models (section 3.2) and summarized in Table 5. The DADS model consists of 17 rigid bodies, guns, turret, hull and 14 road wheels. These bodies are connected by 16 joints, trunnion, ring, and 14 roadwheel attachment points, as shown in Fig (89). The track and suspension and terrain characteristics are imposed on this model, as shown in Fig (90). Suspension stiffness and damping curves utilized where those of Teledyne 3870 ESS Series as shown in Fig (91 & 92).

These two curves are transformed into torque versus angular displacement and torque versus angular velocity by using the following formulas:

 $T = FR \cos 0$ $A = R \sin 0$

WHERE:

T: Torque (lb - in)
R: Road Arm Length (17 inches)

F: Force (lbs)
A: Wheel Travel (inches)

0: Road Arm Angle From horizontal position.

The resulting curves are shown in Fig (93 & 94). The impulse curve for the lightweight gun used is shown in Fig (95). The terrain used was APG 4 whose profile is shown in Fig (96). A more drastic custom-made profile with a series of bumps and holes (spaced to maximize terrain effects on the Chassis), can be used in Fig (97). The CATTB DADS model was driven at a constant speed (30 mph), and the acceleration and forces at various location were calculated. It is worthwhile to mention that the hydroneumatic suspension model runs on DADS were not successful. In lieu of waiting for the DADS code to be fixed, an M1 suspension was used on the CATTB DADS model. In the future, when the DADS code is fixed, a follow-up study can be performed with minimum efforts. A detailed input file for the DADS model is attached in Appendix D.

4.3.2. DADS Results

A DADS model was analyzed under two separate load cases so that they could be combined at any time step and with any proportion desired. The first load case is ABG4 terrain effects on the CATTB. This can be presented in the form of time-dependent curves for the following parameters:

4.3.3 Terrain Effects

Pitch and Roll Angles	Fig 98
Vertical Acceleration of Chassis at C.G	Fig 99
Vertical Acceleration of First Road	Fig 99
Vertical Forces in Road Wheels 1,4 and 7	Fig 100
Vertical Forces in Road Wheels 2,3,5 and 6	Fig 101
Maximum Vertical Chassis Acceleration	Fig 102
Maximum Chassis Angular Acceleration	Fig 103

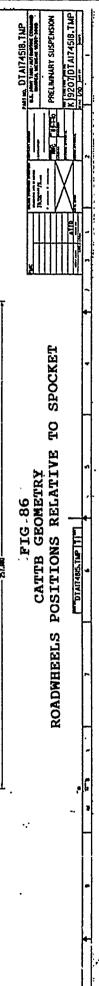
	Maximum Vertical Forces in roadwheels (Case	1):	
	L1, L4 and L7	Fig	104
	L2, L3, L5 and L6	Fig	105
	R1, R7 and R7	Fig	106
	R2, R3, R5 and R6	Fig	107
	Maximum Vertical Forces in roadwheels (Case	2):	
I	.1, L4 and L7	Fig	108
1	.2, L3, L5 and L6	Fig	109
1	R1, R4 and R7	Fig	110
1	R2, R3, R5 and R6	Fig	111

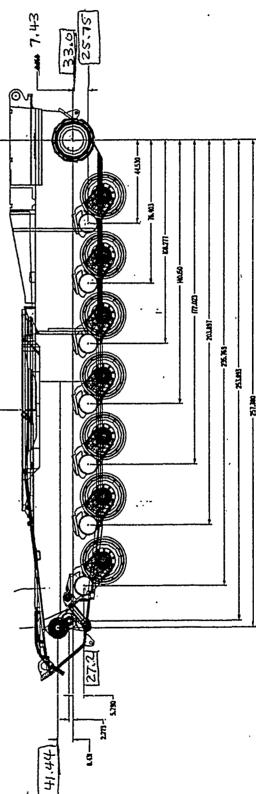
Case (1) assumed maximum bending to occur under first roadwheel and it occurred at 23.8 seconds. Case (2) assumed maximum bending to be under the forth roadwheel and it occurred at 30.5 seconds. In reality, there are many cases for the bending of the chassis which falls between these two load cases, and their effects must be considered. However, the complexity of the process leads to this simplification. This will be discussed later when addressing the bending stresses in the dynamic finite element analysis.

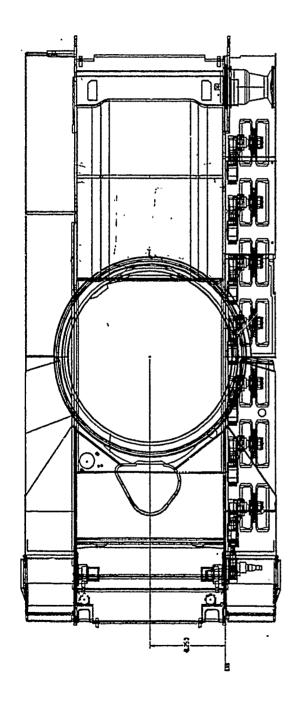
4.3.4 Firing Load Effects

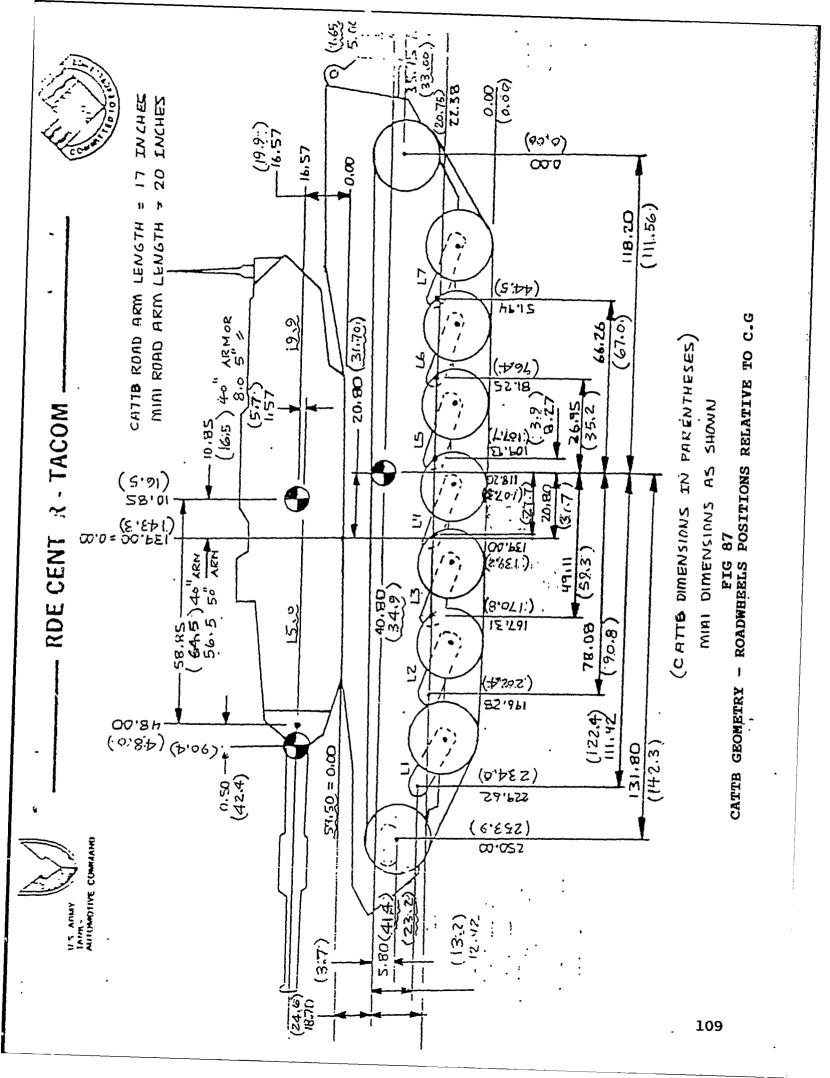
Fore AFT Gun Breach Displacement	Fig 112
Fore AFT Gun Pitch Angle Displacement	Fig 113
Fore AFT Gun Velocity	Fig 114
Fore AFT Gun Acceleration	Fig 115
Chassis Longitudinal Acceleration	Fig 116
Chassis Vertical Acceleration	Fig 116
Maximum Vertical Forces in Road Wheels:	
L1 to L7	Fig 117
L1, L4 and L7	Fig 118
L2, L3, L5 and L6	Fig 119

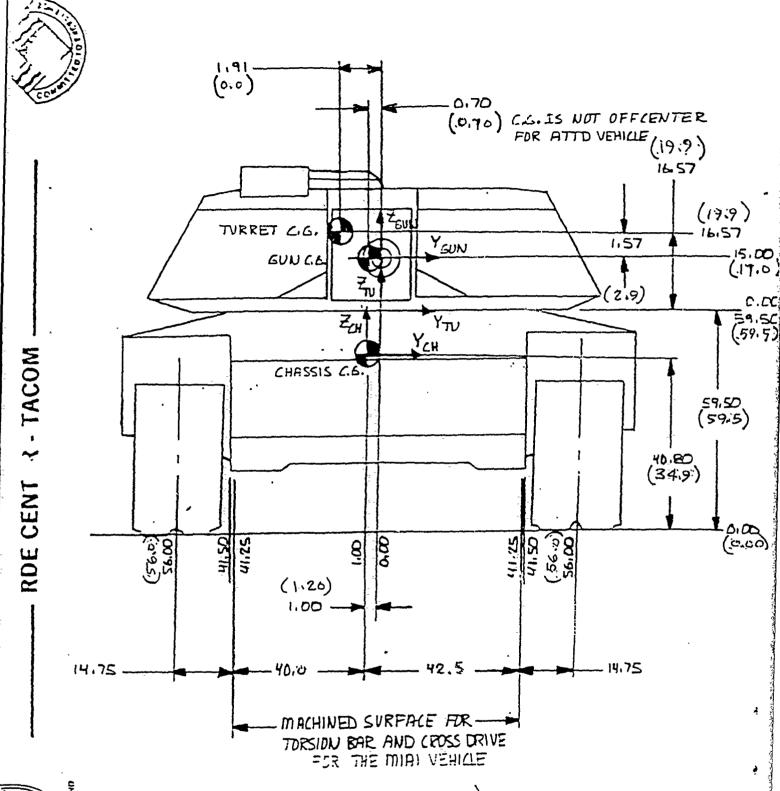
Results of the previous DAD analyses are attached for comparison Fig (120 - 122).





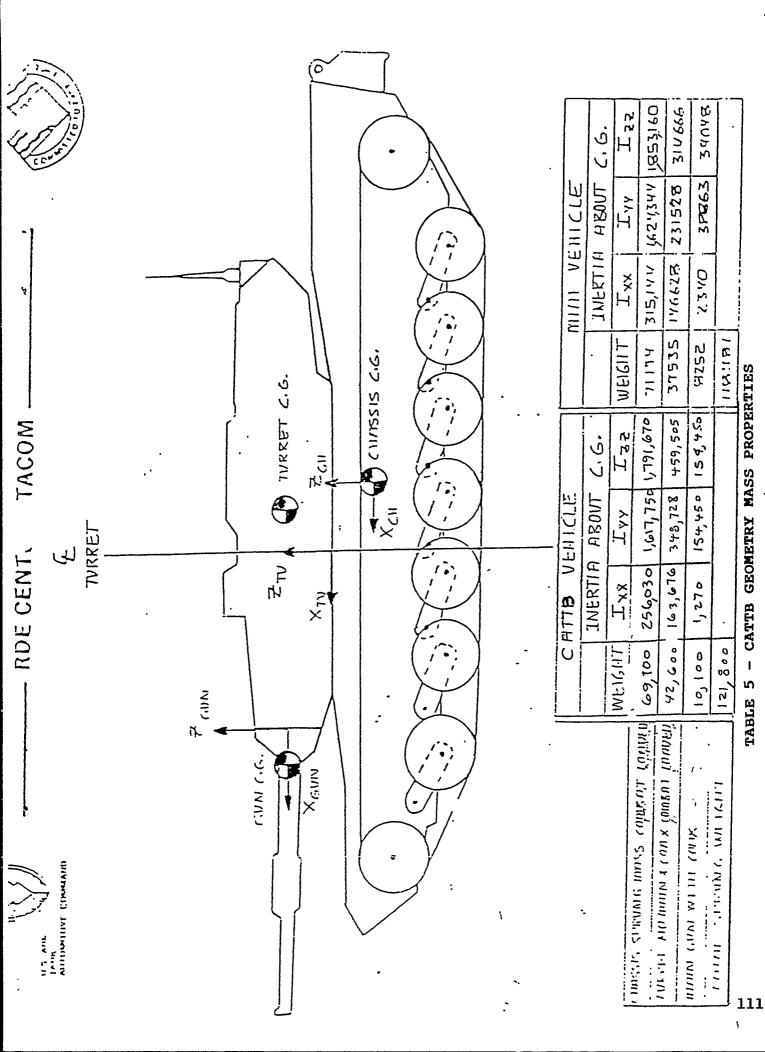




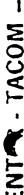


(CATTE DIMENSIONS IN PARENTHESES)

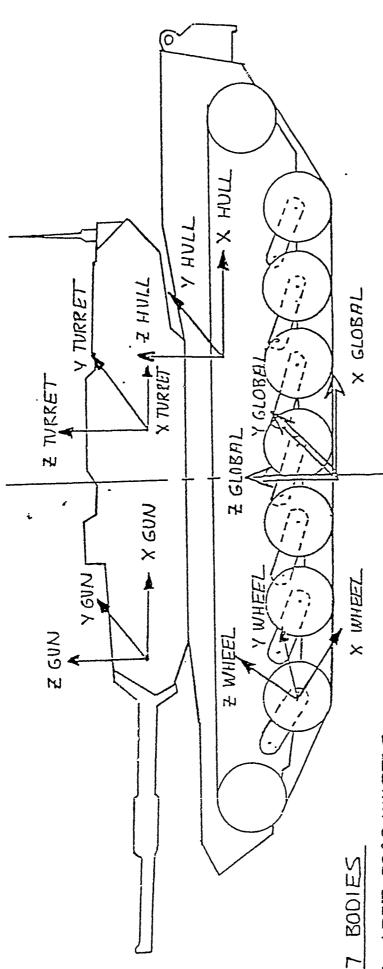
FIG 88
CATTB GEOMETRY
ROADWHEELS POSITIONS RELATIVE TO C.G



TATH TATH ALTUMDTIVE COMMAND







LEFT ROAD WHEEZS

RIGHT ROAD WHEELS

HWLL.

TURRET

GUN

FIG 89 CATTB GEOMETRY - SUSPENSION



RDE CENTER - TACOM -



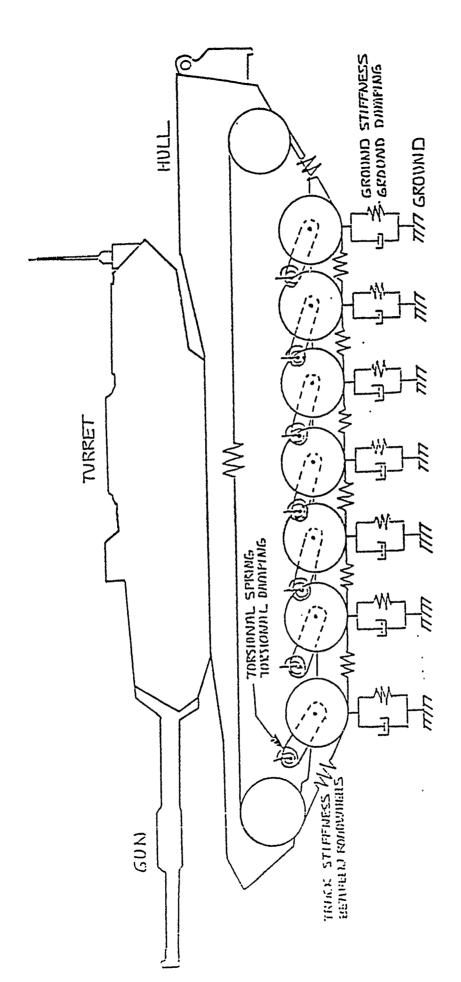
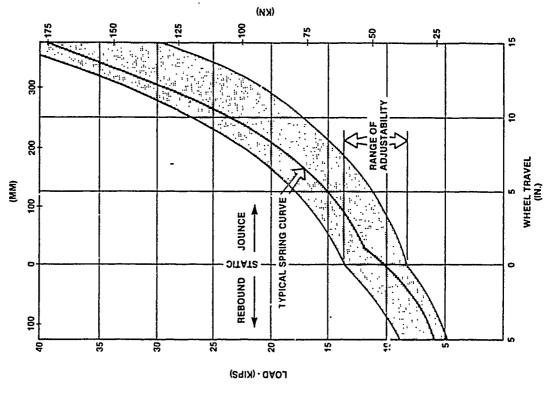
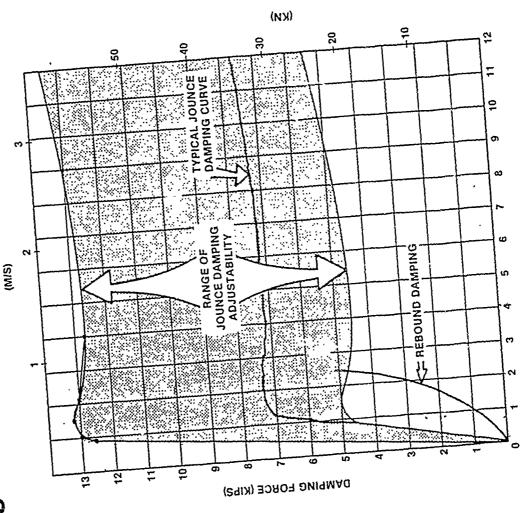


FIG 90 CATTB GEOMETRY - TRACK AND SUSPENSION

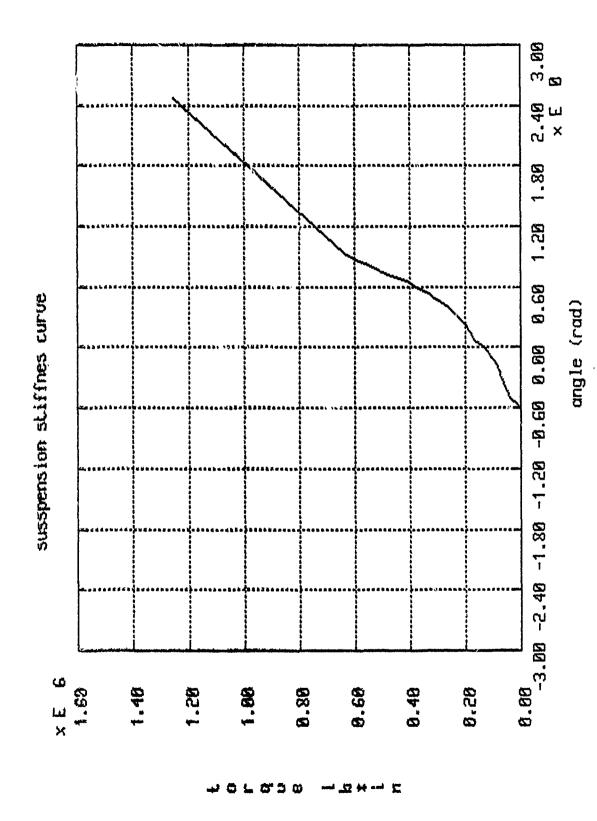
CATTB/3870 ESS Spring Response



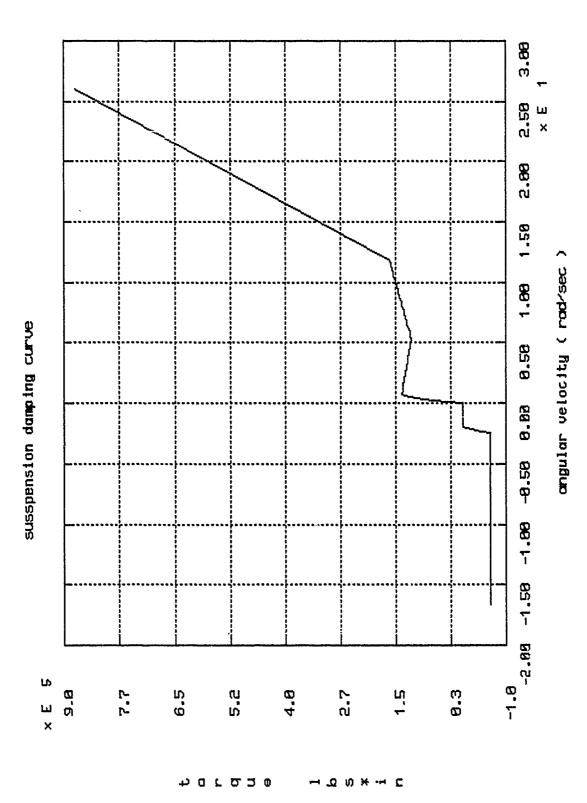
CATTB/3870 ESS Damping Response

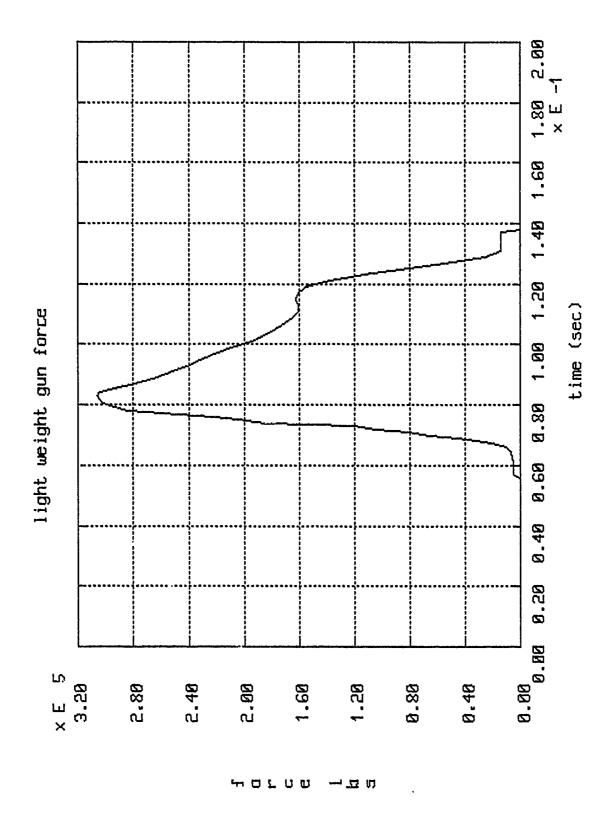


(FIG 92) CATTB GEOMETRY - SUSPENSION DAMPING CURVE



(FIG 93) CATTB GEOMETRY - DADS SUSPENSION CURVE

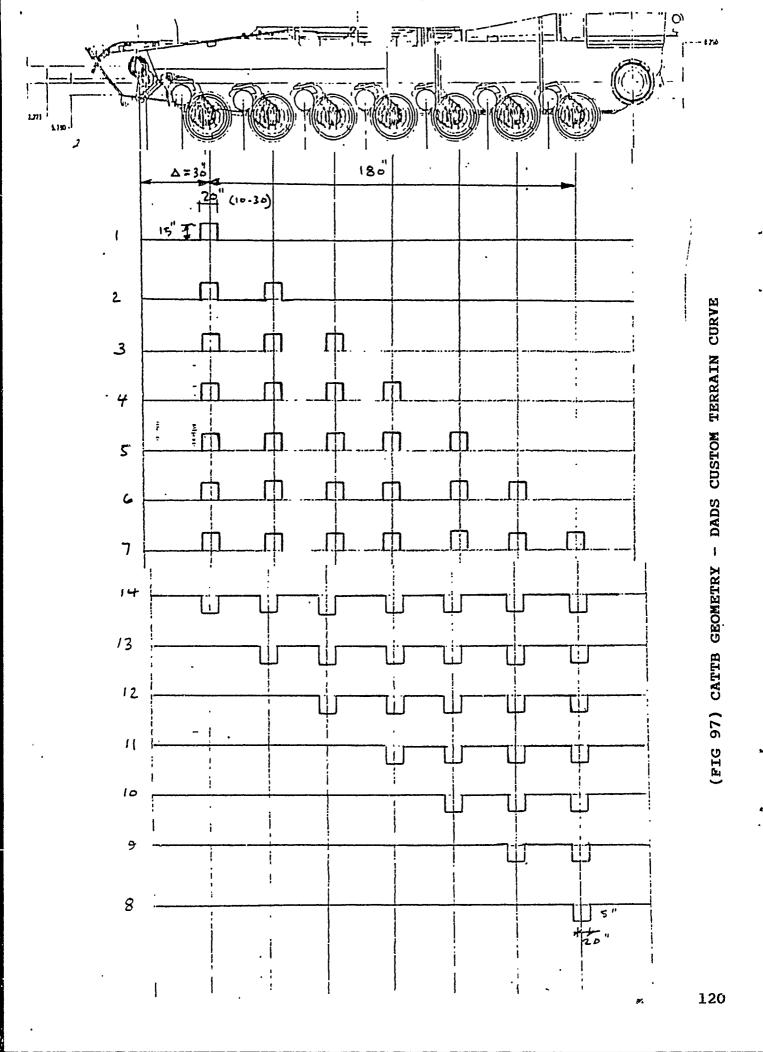




(FIG 95) CATTR GEOMETRY - DADS IMPULSE CURVE

ZOH-IDCMLM

(FIG 96) CATTB GEOMETRY - DADS ABG4 TERRAIN CURVE



0 - 0 - 0

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(FIG 98) CATTB ROLL AND PITCH ANGLE

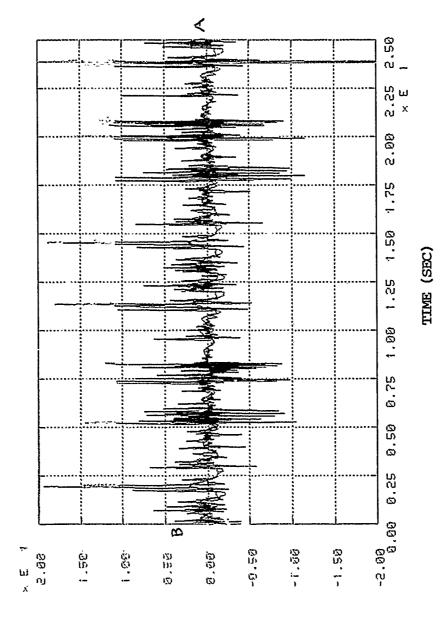


FIG 99 VERTICAL ACCELERATION AT CHASSIS C.G AND FIRST ROADWHEEL

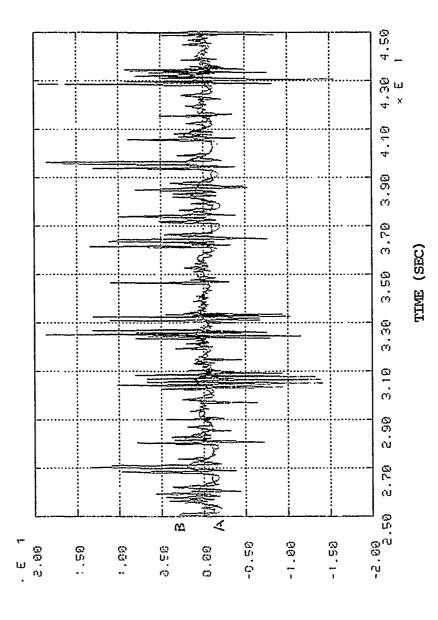


FIG 99

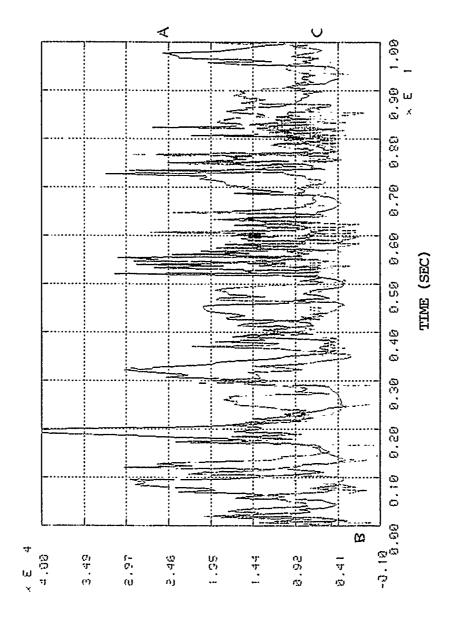


FIG 100 VERTICAL FORCES IN ROADWHEELS 1, 4, and 7

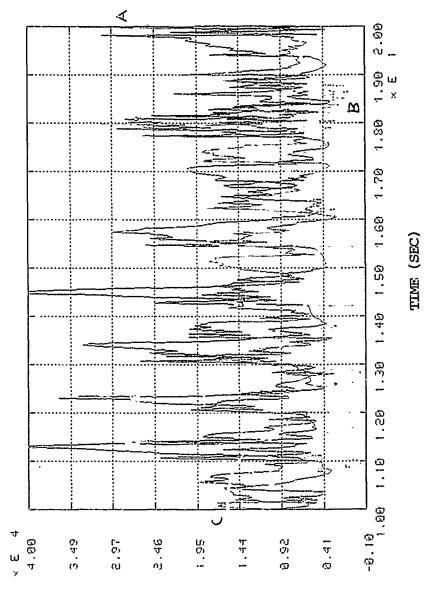


FIG 100

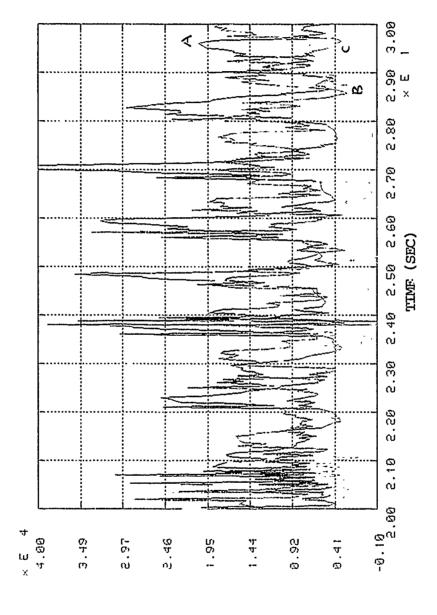


FIG 100

للخاهلا والمرافئة والمقامية والكائب مراوحة فمدهم فاستنام وفاستان بملاستان والمراه المهام فالمنافي الممام فالمالية والمالية والمراملات فالمالية والمالية والم

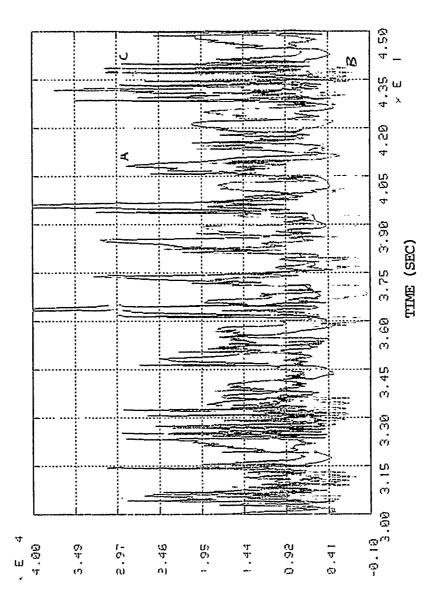


FIG 100

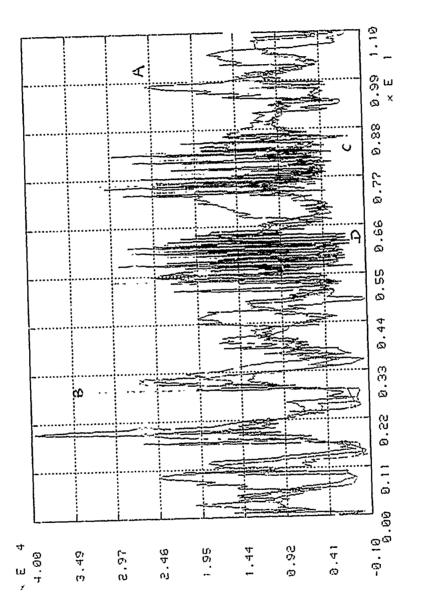


FIG 101 VERTICAL FORCES IN ROADWHEELS 2, 3, 5, and 6

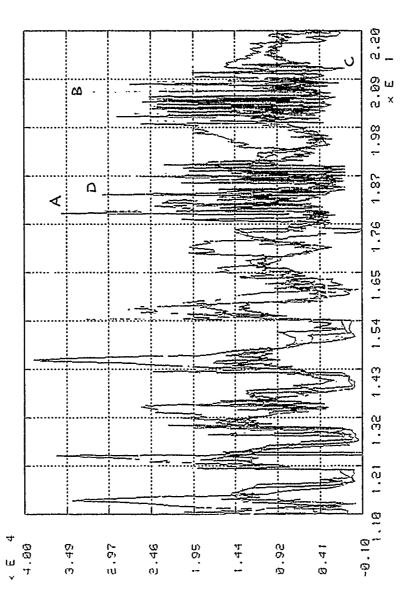


FIG 101

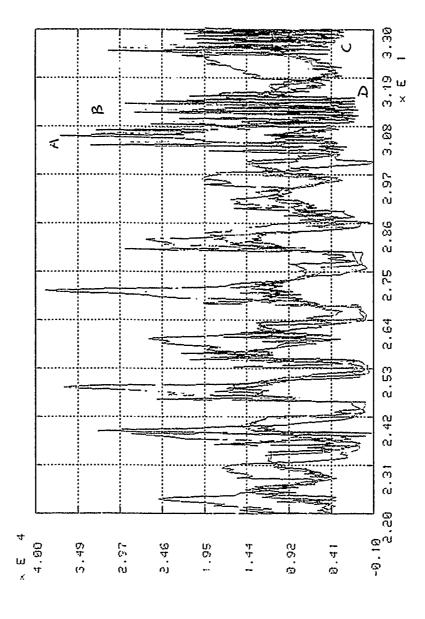
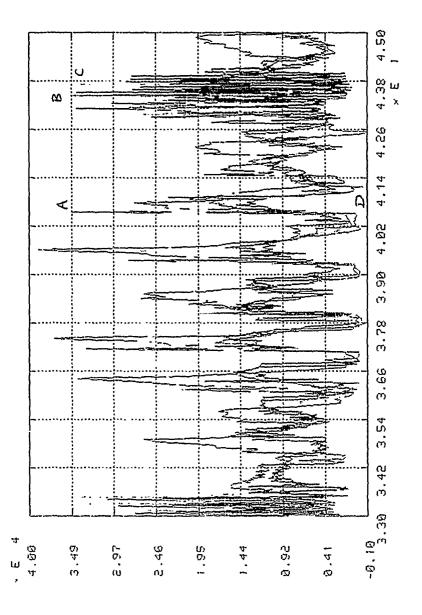


FIG 101

ماعقات كالمصيدا كالمامات لاسفوساك مجاسلا فالتعقيقات ومكاماتان والالتاجات المعادة كتجاب المامان الماعات



2000-0124-

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FIG 102 MAXIMUM CHASSIS ACCELERATION

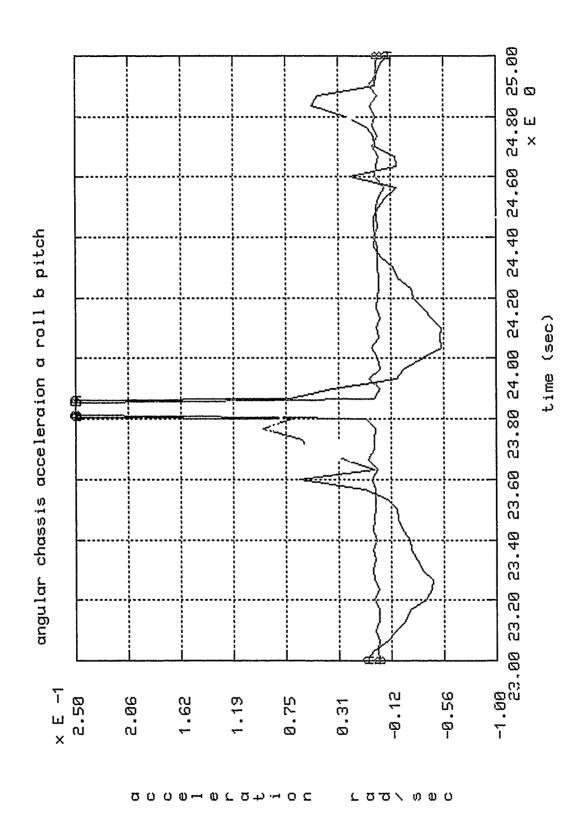
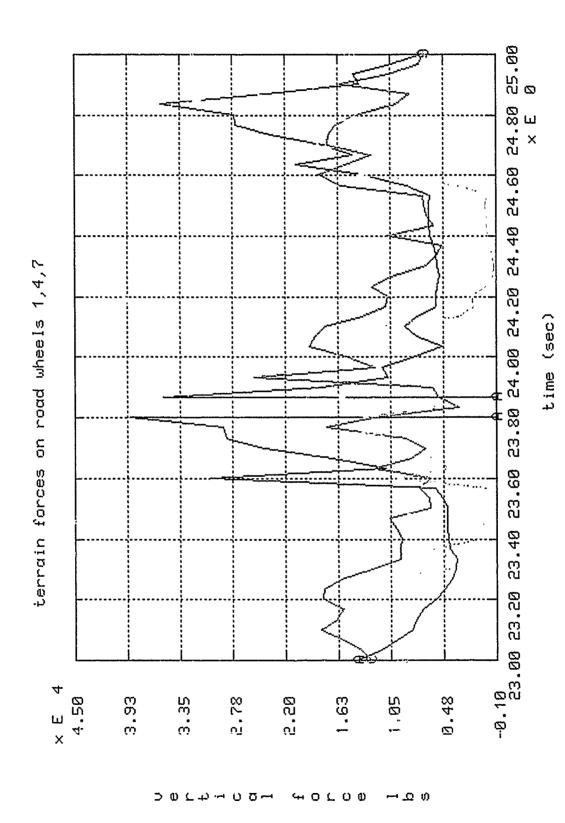


FIG 103 MAXIMUM CHASSIS ANGULAR ACCELERATION



MAXIMUM FORCES IN ROADWHEELS LI, 4, and 7 (CASE, 1)

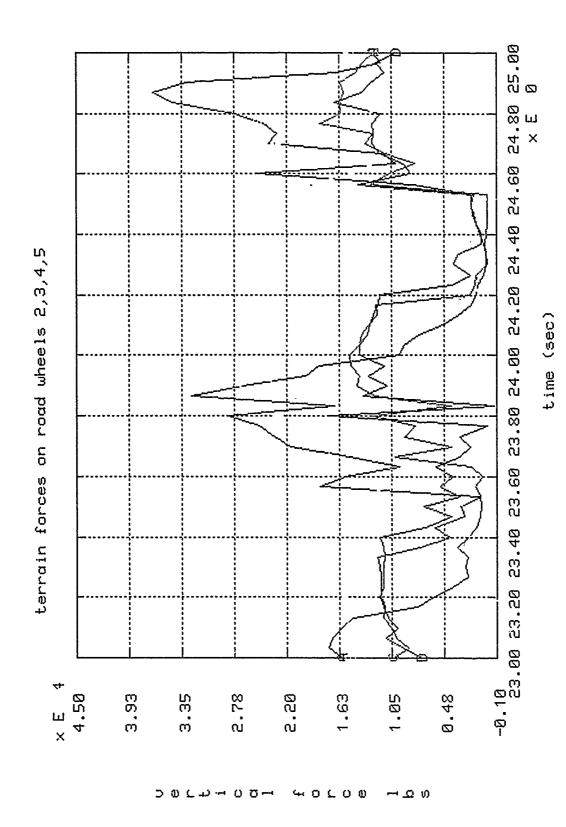


FIG 105 MAXIMUM FORCES IN ROADWHEELS L2: 3, 5, and 6 (CASE 1)

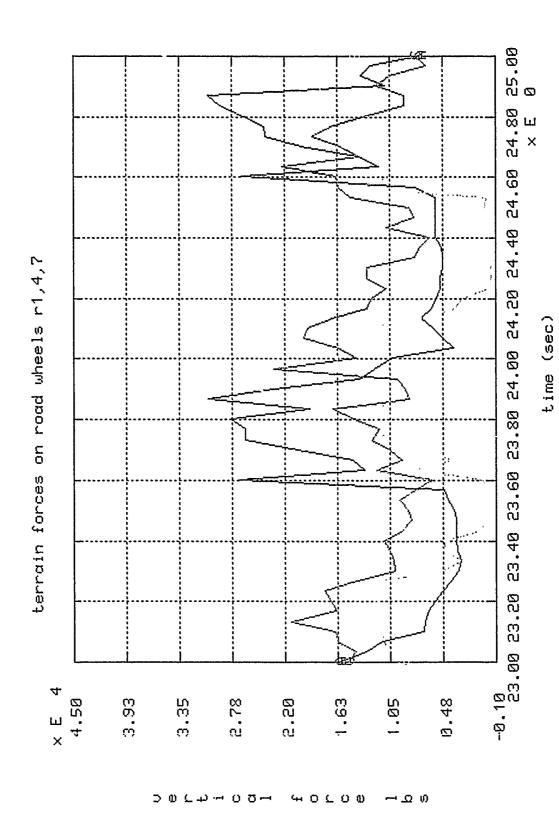


FIG 106 MAXIMUM FORCES IN ROADWHEELS R1, 4, and 7 (CASE 1)

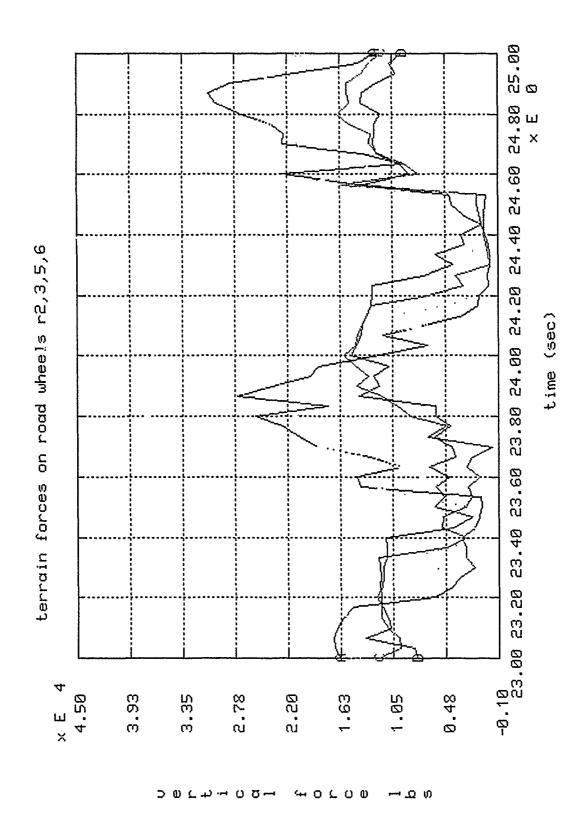


FIG 107 MAXIMUM FORCES IN ROADWHEELS R2, 3, 5, and 6 (CASE 1)

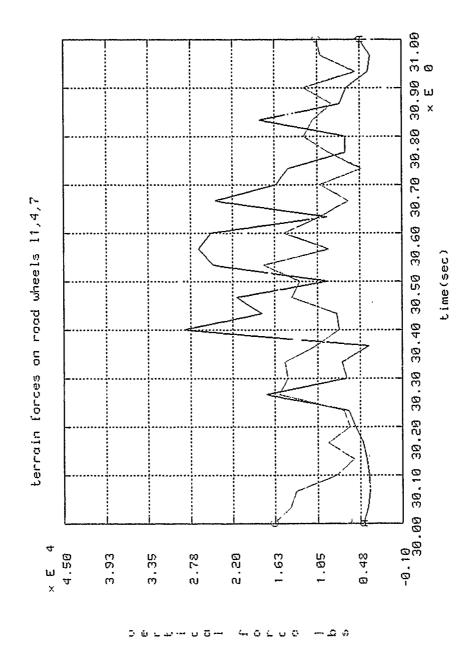


FIG 108
MAXIMUM FORCES IN ROADWHEELS L1, 4, 7 (CASE 2)

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FIG 109 MAXIMUM FORCES IN ROADWHEELS L2, 3, 5, 6 (CASE 2)

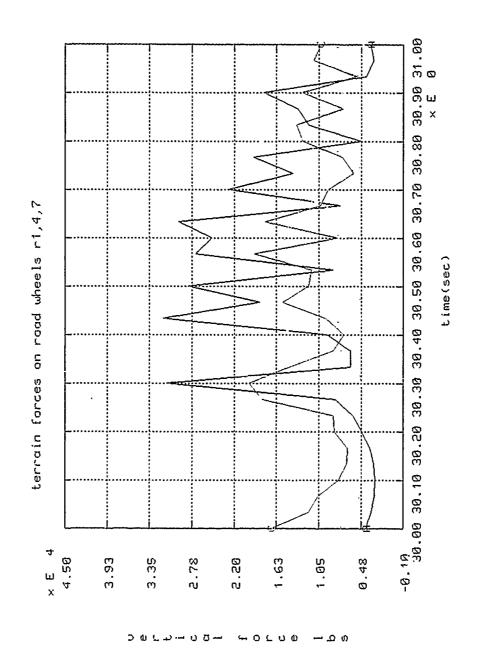


FIG 110
MAXIMUM FORCES IN ROADWHEELS R1, 4, and 7 (CASE 2)

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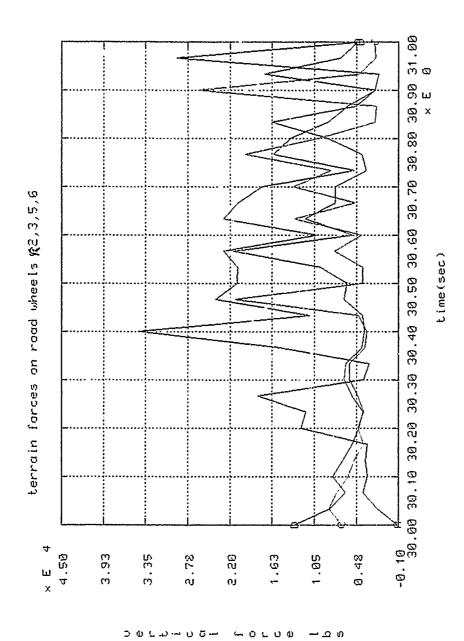


FIG 111 MAXIMUM FORCES IN ROADWHEELS R2, 3, 5, and 6 (CASE 2)

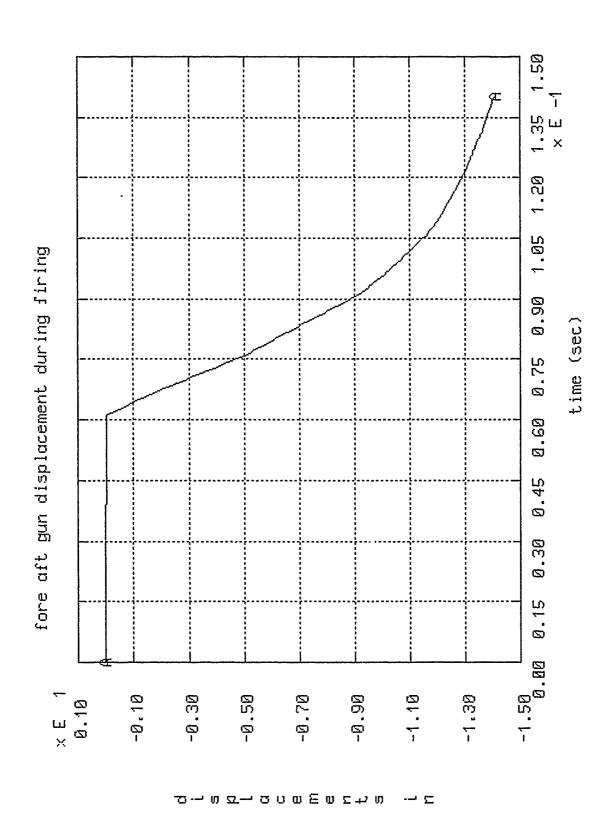


FIG 112 FORE - AFT GUN DISPLACEMENT DURING FIRING

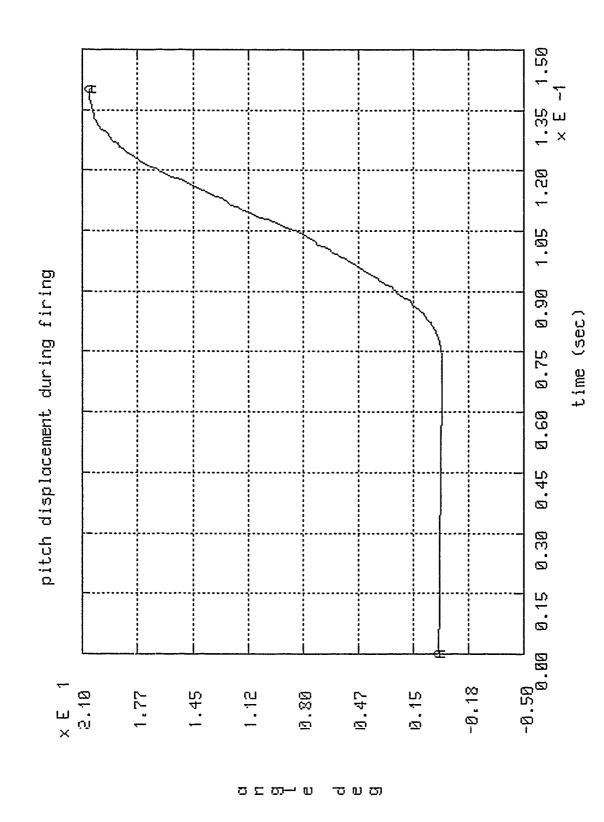


FIG 113 PITCH DISPLACEMENT DURING FIRING

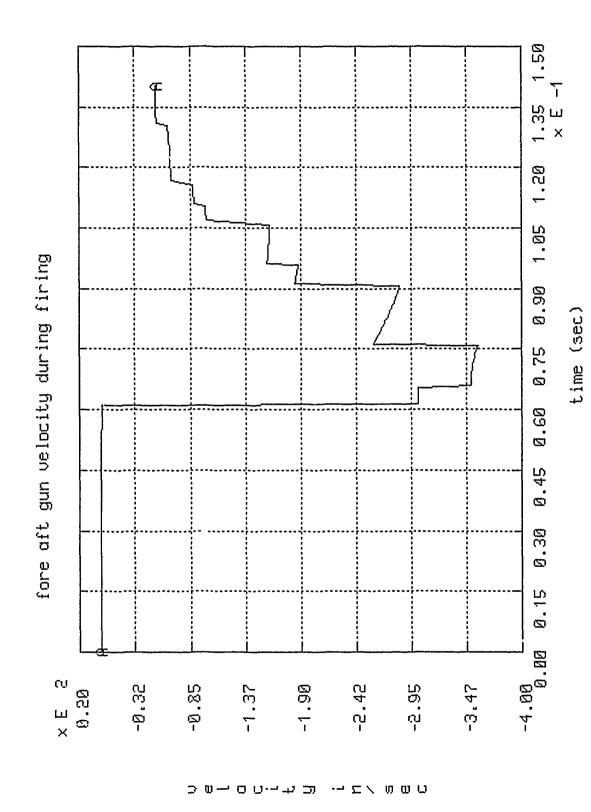


FIG 114 FORE - AFT GUN VELOCITY DURING FIRING

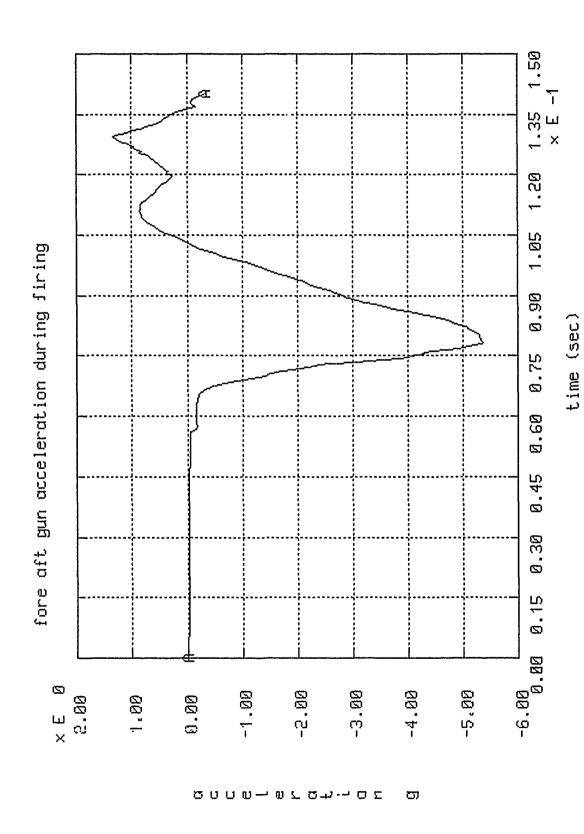


FIG 115 FORE - AFT GUN ACCELERATION DURING FIRING

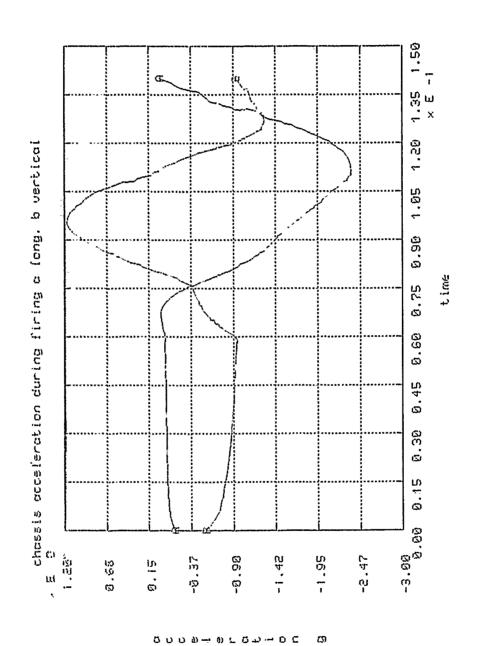


FIG 116 CHASSIS ACCELERATION DURING FIRING

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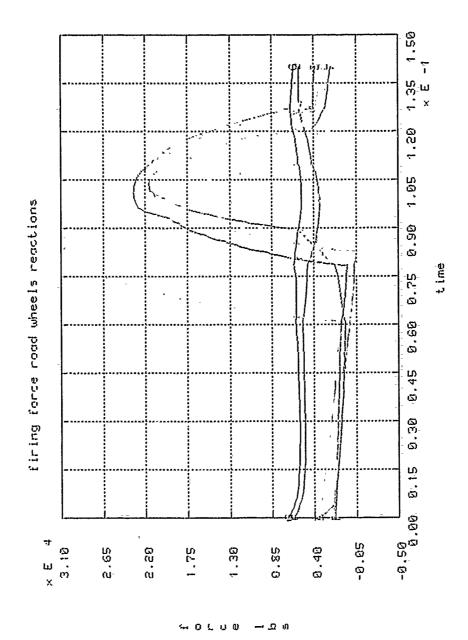


FIG 117
ROADWHEELS REACTIONS DUE TO FIRING FORCE

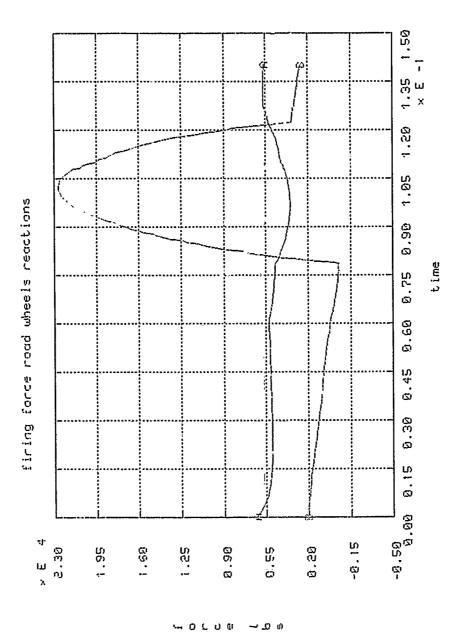


FIG 118
FIRING FORCE ROADWHEELS REACTIONS (1,4, and 7)

-- 12 0

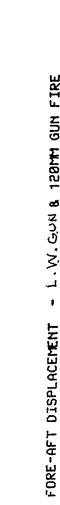
4-0 L U 0

FIG 119
FIRING FORCE ROADWHEELS REACTIONS (2,3,5, and 6)

فالأعط فأحمل كالكامل مبعي عبيرها ووجفتك بأبيد وملاعظتها يتجامعين والإيمان يجدر الإيامي بروريا والجادة والإدامة

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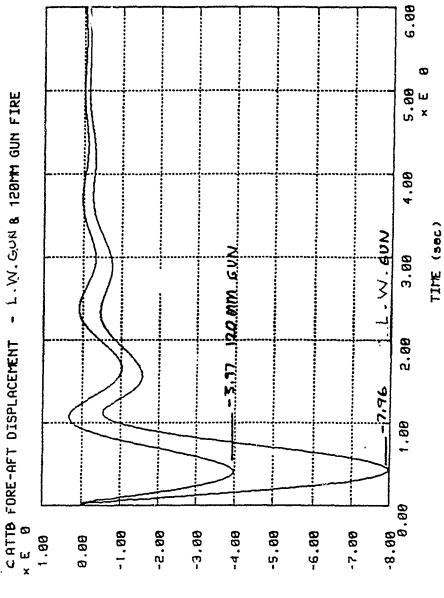


FIG 120 FORE - AFT DISPLACEMENT FOR LW GUN AND 120 MM GUN



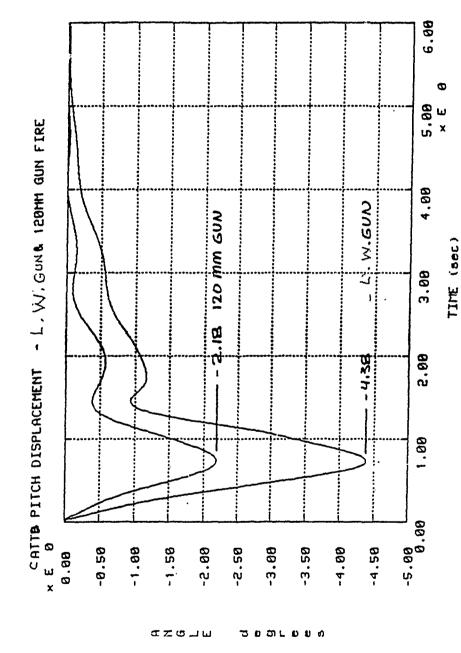


FIG 121
PITCH DISPLACEMENT FOR LW GUN AND 120 MM GUN

151

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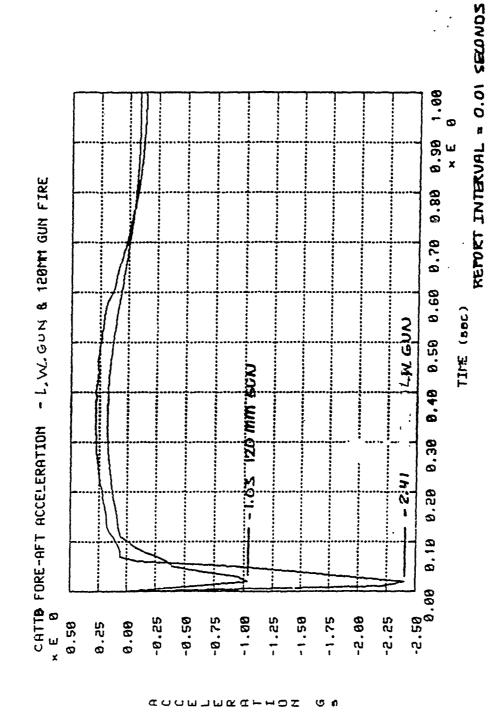


FIG 122 - AFT ACCELERATION FOR LW GUN AND 120 MM GUN FORE

4.4 Dynamic Finite Element Stress Analysis:

In the previous finite element analysis section (4.2), the dynamic nature of the load (terrain and gun firing) was not investigated. To complete this study, the dynamic effects of this load on the CATTB Chassis must be evaluated. Dynamic analysis software NISA (Numerically Integrated System Analysis) was utilized. To have access to this software, it was necessary to transfer the CATTB FEM model to the Cray Supercomputer. To accomplish this, the CATTB FEM model, which was built using IRM Software on the Intergraph CAD System, had to be transferred to the prime computer and had to be translated into PATRAN and then into NISA. Then it had be brought back to the Cray for analysis. This tedious procedure proved to be useful, due to the amazing speed at which the analysis could be performed on the Cray supercomputer.

4.4.1 Dynamic Effects of Terrain Forces

In the dynamic analysis of CATTB (section 4.3), the forces in the roadwheel attachment points were found to be time dependent and were maximum at roadwheels 3 and 4, as shown in Fig (117). In the static FEM analysis (section 4.2), these forces were calculated as support reactions and were maximum at roadwheels 1 and 7 (Fig. 124). To reconciliate between the two results, the roadwheel attachment points had to be allowed to have relative movement to each other so that the corrected support reactions in the Static FEM analysis would equal those found in the dynamic analysis.

The relative movement for all roadwheels attachment points created additional stress in the chassis which had to be added to static FEM analysis stresses (Fig 125 shows the chassis stresses due to vertical movement of 0.10 inches at first left roadwheel). To maximize the effects of Terrain Dynamic Forces, the forces in the roadarms attachment points obtained from DADS analysis were chosen in such a way that they caused maximum bending in the chassis. Two cases for these terrain forces were considered; the first case yielded maximum bending at first roadwheel, whereas the second assumed maximum bending at the fourth roadwheel. The dynamic effects of the terrain forces could easily be visualized by comparing the results of the static FEM analysis (Fig 123) and the results of Dynamic FEM analysis (Fig 126 & 127)

Total VON Mise stresses for the two terrain cases are shown in Fig (128 & 129) and Fig (130 & 131) respectively.

4.4.2 Dynamic Effects of Firing Load:

In the previous FEM analysis (section 3.2) the firing load was considered static. To account for its dynamic nature, a dynamic load factor of 2 was used as a multiplier. To study the dynamic nature of the gun firing load, a transient dynamic analysis was required. The first step in this type of analysis was the modal analysis or EIGEN VAWE and EIGEN VECTOR analysis (natural frequency and vibrated shape).

This was accomplished, and the results were satisfactory (Table 6 - 8). However, the binary files, which will be used in the transient dynamic analysis, could not be properly translated from analysis results. Further studies in this area can be resumed when future software revision enables correct translation of the binary files.

CATTB STRESS ANALYSIS FOR STATIC FIRING LOAD

4.10+04

3.43+04

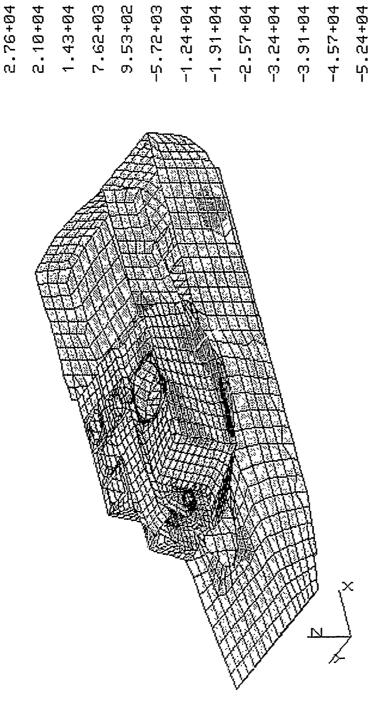


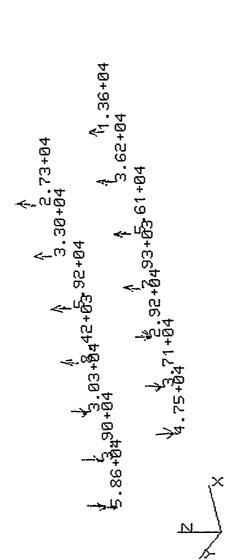
FIG 123 CATTB STRESS ANALYSIS FOR STATIC FIRING LOAD

STRESS (PSI)

-5.91+04

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CATTB ROAD WHEELS REACTIONS UNDER STATIC FIRING LOAD



CHAME A STATE OF 585.7 446.8 391.B 167.B 279.3 111.7 335.1 223.4 RANGE: VIEW Dec/14/89 **LERSION 89.0** POST-PROCESSOR E.M.R.C.- DISPLAY II

5.83E+84 **UDN-MISES STRESS** STRESS CONTOURS

55.86

EMRC-NISA/DISPLAY

CATTIB NUETRAL FILE FROM PATRAN 7 NOV 89

LOAD CASE NUMBER 1, BOTTOM LAYER

CATTB STRESSES DUE TO 0.10 IN VERTICAL MOVEMENT AT FIRST ROADWHEEL FIG 125

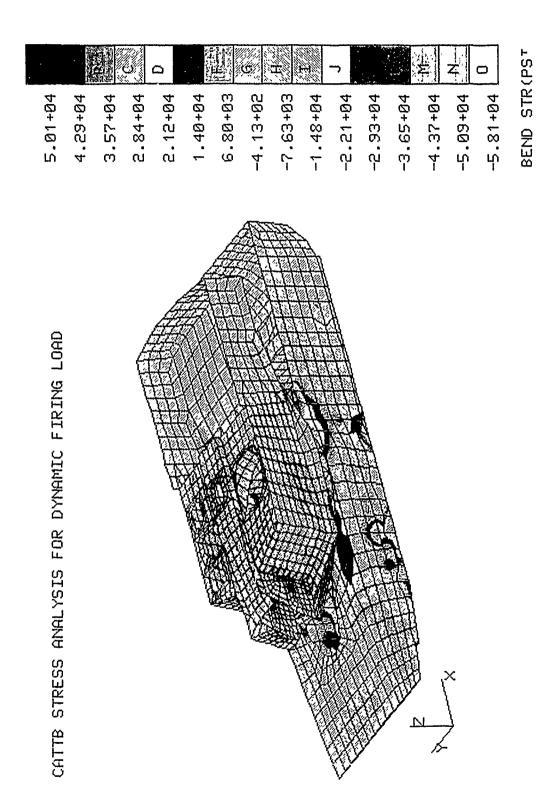
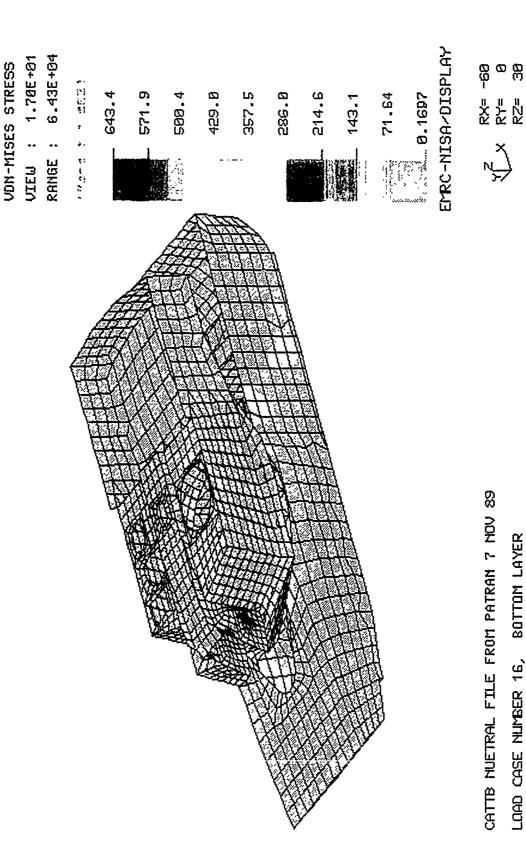


FIG 126 CATTB STRESSES FOR DYNAMIC FIRING LOAD

UERSION 89.8 Dec/14/89 POST-PROCESSOR E.M.R.C. - DISPLAY II

STRESS CONTOURS



CATTB STRESSES FOR DYNAMIC FIRING LOAD FIG 127

LOAD CASE NUMBER 16, BOTTOM LAYER

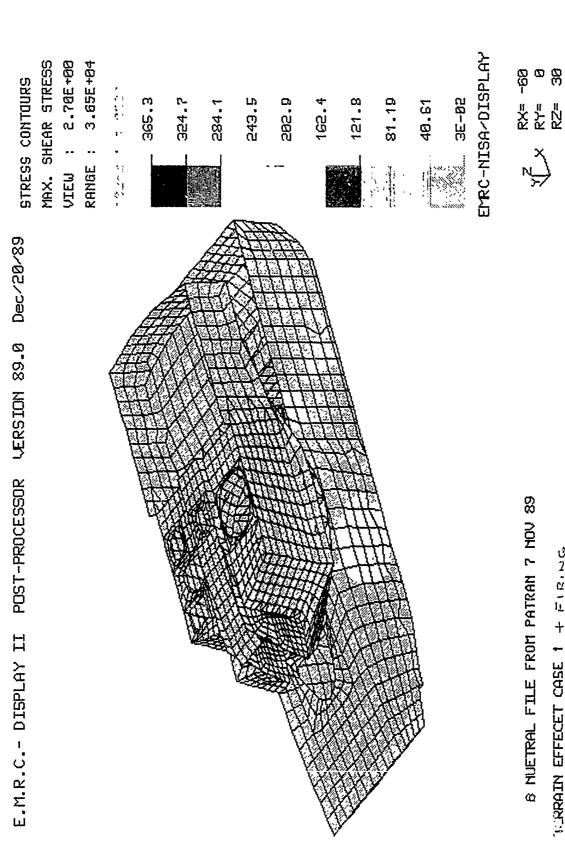
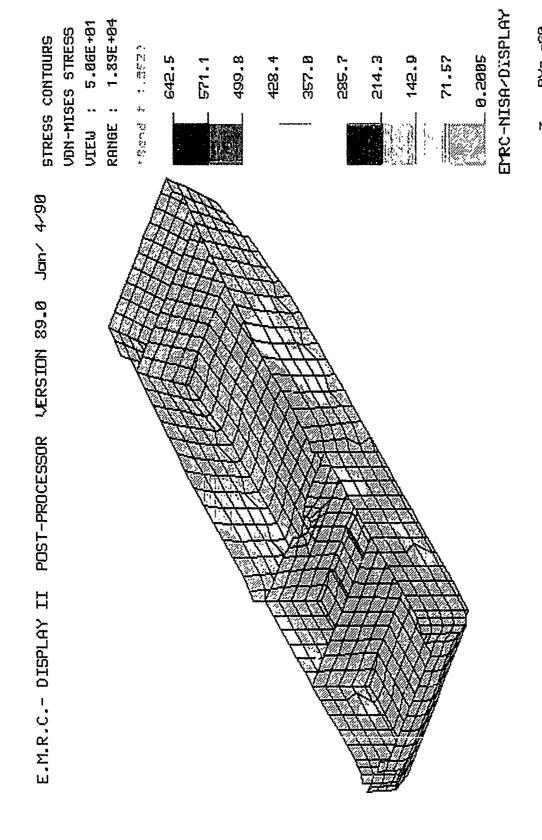


FIG 128 CATTB STRESSES FOR FIRING LOAD AND TERRAIN LOAD (CASE 1)

the territory and the second section is a factor of the second second section of the second

THERETH EFFECET CASE 1 + FIRENCE



Z RX= -68 X RY= 9 RZ=-138 FIG 129 CATTB STRESSES FOR FIRING LOAD AND TERRAIN LOAD (CASE 1) CATTB NUETRAL FILE FROM PATRAN 7 NOV 89 TERRAIN EFFECET CASE 1 + FIRING

. AGENESA KKEST NASTATUTAK KITANDES CIEGERIA SEKALERIK SEKARIK PERKETAK KESAK BANDES SEKATERA DA SEKATURA DA

Dec/14/89 CERSIEN 89.8 POST-PROCESSUR E.M.R.C.- DISPLAY II

UDN-MISES STRESS STRESS CONTOURS

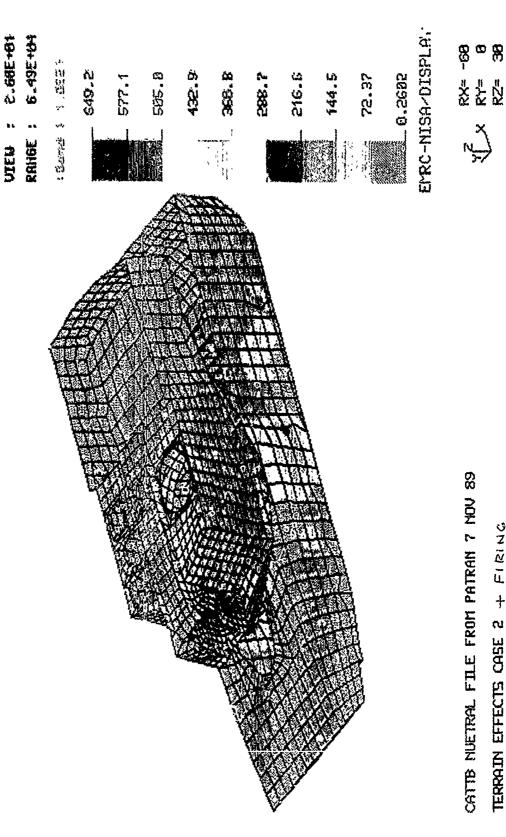


FIG 130 CATTB STRESSES FOR FIRING LOAD AND TERRAIN LOAD (CASE 2) TERRAIN EFFECTS CASE 2 + FIRING

CATTB NUETRAL FILE FROM PATRAN 7 NOV 89

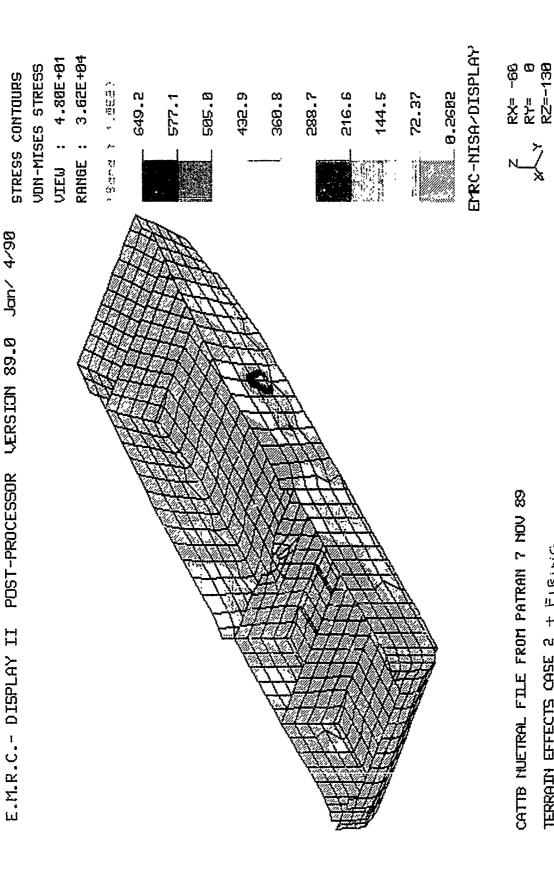


FIG 131
CATTB STRESSES FOR FIRING LOAD AND TERRAIN LOAD
(CASE 2) TERRAIN EFFECTS CASE 2 + FIRING

TABLE 6 CATTB EIGEN VALUE ANALYSIS RESULTS - FREQUENCY

***** REACTION FORCES AND MOMENTS AT NODES **

MODE NO.

	Ø	Ø	Ø	Ø	Ø	60	©	Ø	Ø
ጅ	0.0000E.+00	6.8888E+88	8.8888E+88	B.88888E+88	B. BBBBBE+68	B.BBBBE+BB	8.00000E+00	B. BBBBBE+BB	8.88888E+88
FZ	-4.18480E+03	5.00486E+03	5.58802E+01	-2.10084E+03	-2.81085E+03	2.59796E+03	-2.40608E+04	-8.88090E+d3	2.73841E+04
F -	B. BBBBBE+BB	B. BBBBBE+BB	B. BBBBBE+BB	0,0000E+00	B. BBBBBE+BB	8.8888E+88	B. BBBBBE+8B	୫. ୭ ୭୭୭୭≝+୭୭	0.0000E+00
χ	ଡ ୁ ଓଡ଼ଉଉଷର +ଃଡ	B.88888E+88	B.BBBBE+88	ଡ ୍ଡେଅଉଉପE+ଉଉ	0.0000E+00	8.8888E+88	8.8888E+88	0.8888E+88	0.0000E+00
NODE	1732	1733	1738	1739	1744	1745	1750	1788	1837

S MODE NO.

**** 9:23:35 M R C N I S A DEC/29/1989

ш

38 38 38

VERSION 88.7 (88/11/88)

EIGENVALUES OF CATTB MODEL

**** AVERAGE NODAL STRESSES ****

NODE SYZ

8X 82X

S

22

SX≺

9.20810E+02 -2.50339E+01

1.22855E+82

9.8888E+88 6.38854E+00

-3.58670E+02

4.53680E+8

3.85587E+8

3.87728E-81

2 -4.87447E+81 3 1.93401E+02

4.95336E+82 3.88859E+82

-7.32581E+01 6.51869E+02

7.50168E+01

-1.87588E+82

-3.86280E-0

TABLE 8
CATTB EIGEN VALUE ANALYSIS RESULTS - NODAL STRESSES

5. Conclusions:

- 5.1 Turret Design The new locations of the turret side-plates significantly increased turret strength and kept stress at its current level. Whereas locating these side-plates in similar fashion to the M1 Turret could have resulted in higher stresses and deformations, due to the reduced turret strength.
- 5.2 Trunnion Design It is recommended that the size of the bolts in the gun-mounting block not exceed 3/8" to minimize the loss of the resisting area, and the pretension load in these bolts should not exceed 6000 8000 lb/bolts, because it will create additional stress in the trunnion in the range of (9,000 12,000) PSI.
- 5.3 <u>Casting</u> Hull casting reinforcement is needed. It can be achieved by extending the casting plate to the chassis side-plates and should not be compromised.
- 5.4 Power Pack Mounting From stress analysis results, it is clear that the power pack will not cause excessive stress in the hull floor plate. But the current analysis did not consider the rigidity of the power-pack, which is more than enough to transfer its weight to hull side-plates. In this case, the floor mounting will not only be ineffective but it might be a nuisance, since the floor plates are not stiff, and it might transmit unnecessary vibration to the power-pack components. For this reason, it is better to utilize side-plate mounting for all major CATTB components, such as the auto-loader and the power-pack. This will allow effective optimization for floor plates.
- 5.5 <u>Design Optimization</u> It is recommended to optimize the design (when optimization software becomes available) to reduce the percentage of CATTB basic structure weight (currently it is about 30%).

6.2 Recommendations:

This study was conducted under extraordinarily difficult circumstances due to the relatively recent software utilized (EMS, IGDS, IRM, IFEM, PATRAN, NISA), which is under continuous revision, not to mention the operating difficulties encountered on the VAX computer. All this combined complicated and hindered the interface between various design stages, and it did not allow this study to be concluded to the extent intended. Therefore, the following recommendations are directed toward improving the operating system.

- 6.1 It is beneficial to obtain a translator from intergraph FEM software (IFEM) to analysis software ABAQUS. This translator must provide complete translation for FEM Model (Load, Material and Element Properties etc.) and it must be available in the Cray supercomputer.
- 6.2 It will be beneficial to obtain a translator from future analysis software ABAQUS to DADS software. This will make building a DADS model for dynamic analysis much easier, and it will allow an iteration process between Dynamic Analysis and Finite Element Analysis, which is essential for design optimization.
- 6.3 It will be beneficial to obtain optimization software to work closely with analysis software ABAQUS.
- 6.4 The implementation of the various software and hardware revisions should be made coincidently and not more than once a year to allow smoother transition between design stages of long project.
- 6.5 DADS program (Tracked Super Element) should be enhanced so that it can handle hydroneumatic suspensions and DADS software must be debugged thoroughly.

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nererence point [8,8,8]
Axes Orientation wrt global co-ordinate system:
1,8,8
                                                       - inch
                                  Object description: Manipulations
Mass units - MU; Length units - in
Density
                                                                                    Genera
SUMMARY OF MASS PROPERTIES Object number: 8
                                                                                    Axes or ientation
                  Object number:
                                                                Density
```

:56.4641, -0.18296, 21.28381 68315 inch**3 inch**2 inch**2 inch**2 inch[※]² inch**2 1.18486e+88 | 1.17457e+88 | -168532 MU ir 2.25278e+87 ax is a XXXX XXXX XXX momen t moment moment ละคล about about about Centroid Product Surface Product Product Moment Volume Moment Moment Mass

Radii of gyration:
X axis 40.5723 inch
Y axis 80.454 inch
Z axis 82.953 inch

(A)

```
co-ordinate system:
                           inch
   Orientation wrt global co-n
                                           General
SUMMARY OF MASS PROPERTIES Object number: 8
                                           Axes or ientation
                                                   Reference point
                                                           Axes
```

```
[-24.9139, -0.657351,18.5299]
183835 inch**3
17388.3 MU
s 4.28329e+87 MU inch**2
s 3.65686e+87 MU inch**2
s 6.47632e+87 MU inch**2
c 62588.3 MU inch**2
-292855 MU inch**2
-7.48568e+86 MU inch**2
-7.48568e+86 MU inch**2
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  Centroid
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                                                                                          Product
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                                   Moment
                                              Moment
            Volume
                                                         Moment
                       Mass
```

Radii of gyration:
X axis 49.6318 inch
Y axis 45.8591 inch
Z axis 61.8289 inch

(1)

```
system:
                                                                                                                                                    [14.1535, 0.253762, 42.0144]
23887.1 inch**3
2902.29 MU
s 6.85467e+86 MU inch**2
s 7.31564e+86 MU inch**2
s 4.49644e+86 MU inch**2
54887.8 MU inch**2
26948.9 MU inch**2
1.70518e+86 MU inch**2
                                                                          Reference point
Axes Orientation wrt global co-ordinate
                                      Mass units - MU; Length units - inch
Densitu
             Object number: 8
Object description: Manipulations
                                                               General
SUMMARY OF MASS PROPERTIES
                                                                                                                                                                                              Axes or ientation
                                                                                                                                                                                            about X
about Y
about Z
                                                                                                                                                         Centroid
                                               Dens i ty
                                                                                                                                                                                              Moment
                                                                                                                                                                   Volume
                                                                                                                                                                                Mass
                                                                                                     –, Θ, Θ,
```

inch inch Radii of gyration:
X axis 48.5985 inch
Y axis 58.206 inch
Z axis 39.3608 inch

moment moment momen t area

Product

Moment

Moment

Product Surface

Product

```
Reference point [8,8,8]
Rxes Orientation wrt global co-ordinate system:
1, 8, 8
8, 1, 8
8, 1, 8
      Summan, ... 8
Object number: 8
Object description: Manipulations
Mass units - MU; Length units - inch
8.84
SUMMARY OF MASS PROPERTIES
```

Uentroid 31218.5 inch**3
Volume 31218.5 inch**3
I248.74 NU
Noment about X axis 2.18745e+86 MU inch**2
Moment about Y axis 2.43883e+86 MU inch**2
Moment about Z axis 2.59283e+86 MU inch**2
Product moment XY 15484.8 MU inch**2
Product moment YZ 12226.1 MU inch**2
Product moment ZX 553384 MU inch**2
Surface area 75126.3 inch**2

Radii of gyration:
X axis 41.8537 inch
Y axis 44.1931 inch
Z axis 45.567 inch

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TURRET MASS PROPERTIES BASKET

```
co-ordinate system:
                                                                                                                               [-2.64185,0.716254,2.9899]
2939.33 inch**3
831.83 MU
s 1.34007e+06 MU inch**2
s 1.29398e+06 MU inch**2
s 777900 MU inch**2
                                                                                                                                                                                                              inch**2
                                                                                                                                                                                                                        inch**2
                                                                                                                                                                                                   inch**2
                                                                                                                                                                                        inch**2
                                Mass units - MU; Length units - inch
Densitu
                      Object description: Manipulations
                                                                                                                                                                                                  31721.2 MU
-14713.8 M
                                                                            Axes Orientation wrt global
1, 8, 8
8, 1, 8
8, 1, 4
                                                      Genera
SUMMARY OF MASS PROPERTIES
                                                                                                                                                                                                                                                                                nch
                                                                                                                                                                                                                                                                                           nch
                                                                                                                                                                    of gyration:
axis 48.1372
axis 39.4489
axis 38.5885
                                                       Axes or ientation
                                                                   Reference point
                                                                                                                                                                                           about Z
             Object number:
                                                                                                                                                                                                     momen t
                                                                                                                                                                                                                momen t
                                                                                                                                                                                                                           momen t
                                                                                                                                                                     about
                                                                                                                                                                                                                                      area
                                                                                                                                                                               about
                                                                                                                                    Centroid
                                                                                                                                                                                                     Product
                                                                                                                                                                                                                                     Surface
                                           Density
                                                                                                                                                                                                               Product
                                                                                                                                                                                                                          Product
                                                                                                                                                                    Tomen t
                                                                                                                                              Volume
                                                                                                                                                                                          Moment
                                                                                                                                                                               Momen t
                                                                                                                                                                                                                                                          Radii
                                                                                                                                                         Mass
```

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49

TURRET MASS PROPERTIES GEAR BOX

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```
Reference point [-24.1529,35.2052,27.2905]
Axes Orientation wrt global co-ordinate system:
                                                       - inch
                                   Object description: Manipulations
                                                 Mass units - MU; Length units
Densitu
                                                                                        Generai
PROPERTIES
                                                                      Density
Axes orientation
OF MASS
                   Object number:
SUMMARY
```

inch**2 inch**2 818.215 inch**3 163.643 MU 152308 MI nch**2 nch**2 inch**2 inch**2 165887 MU 165887 MU -76971.9 31738.4 M moment moment momen t about about area about Centroid Product Product Product Surface Volume Moment Toment Momen: Mass

Radii of gyration:
X axis 38.5879 inch
Y axis 25.2855 inch
Z axis 31.8388 inch

```
Axes Orientation wrt global co-ordinate system:

1, 8, 8
8, 1, 8
8, 1, 8
                                              - inch
                            Object description: Manipulations
                                          Mass units - MU; Length units
Density
Axes orientation General
PROPERTIES
SUMMIRRY OF MASS
                Object number:
```

```
-8.212544
I7.59824,5.28523,-8.3
926.818 inch**3
185.364 MU
183932 MU inch**2
89485.3 MU inch**2
157883 MU inch**2
                                                               inch**2
                                                        inch**2
                                                inch**2
                                                               -33816.2
2795.72
                                                       -79883.9
                                               58869.7
                         moment
                                                                momen t
                                                        momen t
                                        about
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 Centroid
                                                               Product
                                                                       Surface
                                                Product
                                                        Product
                         Moment
        Volume
                                Moment
                                        Moment
                 Mass
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Radii of gyration:
X axis 31.5804 inch
Y axis 21.9717 inch
Z axis 29.1847 inch

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system:
                                                                                     co-ordinate
                                      inch
                        Manipulations
                                                                       [8,8,8]
                                        ŀ
                                     Length units
0.283
                                                                                   Axes Orientation wrt global
                                                            Genera
SUMMARY OF MASS PROPERTIES
            Object number: 8
Object description:
                                   MU;
                                                            Axes or ientation
                                                                       Reference point
                                   Mass units -
                                                Density
```

.-67.8411,8.8559724,16.97591 24.958.4 inch**3 6886.27 MU inch**2 inch**2 inch**2 inch**2 inch**2 inch**2 2.13358e+86 MU i 6.42524e+87 MU i 6.22986e+87 MU i -68882.8 MU inch 6612.63 MU inch -7.93157e+86 MU inch**2 axis about Z momen t moment moment about about area Centroid Product Product Sur face Product Moment Volume Moment Moment Mass

Radii of gyration:
X axis 17.7051 inch
Y axis 97.1606 inch
Z axis 95.6658 inch

TURRET MASS PROPERTIES GUN (ENGLISH UNITS)

SUMMARY OF MASS PROPERTIES

```
global co-ordinate system:
                                                                                         _98.4116,8.224829,46.78961
                                                                                                                             inch**2
inch**2
        description: Accumulated properties
                                                                                                                                                                 inch**2
                                                                                                                                                         nch**2
                                                                                                                                                inch**2
                                                                                                                                                                          inch**2
                                                                                                                            5.96868e+87
5.96446e+87
141572 MU i
8046.37 MU
                 Length units
0.283
                                                                                                  35601.8
10075.3
490883 M
                                                                                                                                                                  -431696
                                   Globa
                                           Orientation wrt
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                                                                                                                                      axi
XX
XX
ZX ZX
ZX ZX
                                                                                                                                                                                            gyration:
                 <u>3</u>
                          Density
Axes orientation
Object number:
                                                                                                                                                          momen t
                                                                                                                                                                   moment
                                                                                                                                                 momen t
                 Mass units -
                                                                                                                                       about
                                                                                                                                                                            area
                                                                                                                     about
                                                                                                                              about
                                                                                                                                                                                              of
                                                                                          Centroid
                                                                                                                                                Product
                                                                                                                                                                  Product
                                                                                                                                                                          Surface
                                                                                                                                                         Product
                                                                                                                    Moment
                                                                                                   Volume
         Object
                                                                                                                              Moment
                                                                                                                                       Moment
                                                                                                                                                                                             Radii
                                                                                                           Mass
                                            Axes
```

inch

6.98887 76.968 76.9487

ax is ax is

4

inch inch

	4,645 4,645 1,537,540 6,640,000
rties te system:	18.97 17 17 17 17 18.97 17 17 17 17 17 17 17 17 17 17 17 17 17
ted properties s - mm co-ordinate sy	2 MU mm 7 MU m
Accumulate gth units 1 Global global co	316.12,-2. 84968e+88 84968e+88 84968e+13 38152e+15 29956e+15 23571e+12 71923e+11 94166e+13
on: Accum Length un 1 Globa wrt glob	ax is 2.8 ax is 2.8 ax is 2.3 ax is 2.2 XY 2.2 2X 1.3
t description units - MU; l ty orientation orientation or 8	about X a about Y a about Y a about Z a moment X moment X moment X area
Object description: Accumulated Mass units — MU; Length units — Density Axes orientation Global Axes Orientation wrt global co— 1, 8, 8 8, 1, 8 8, 1, 8	Centroid Volume Mass Moment ak Moment ak Moment ak Product m Product m

Kg Kg-Cm2 Kg-Cu2 Kg-Cm2

Radii of gyration: X axis 181.92 n Y axis 1950.48 Z axis 1949.65

PROPERTIES BASIC STRUCTURES HULL MASS

[-3.10678, 0.856768, -24.26811 84153.9 inch**3 23815.6 MU co-ordinate system: inch**2 inch**2 Object description: Accumulated properties inch**2 inch**2 inch**2 nch**2 inch s 1.72286e+87 MU s 1.919e+88 MU int 688568 MU inch** 25817.9 MH MU; Length units 8.283 25817.9 -968816 Axes Orientation wrt global Global axis XX XX ZX ZX axis axis axis 34 or Axes orientation moment moment moment l about area about about Mass units Centroid Surface Density Product Product Product Volume Moment **Moment** Toment Mass

inch inch inch

34.8583 85.8539 89.7651

axis axis

××N

Radii

HULL MASS PROPERTIES FRONT ARMOR

```
.-116.927, 0.527742, -24.77641
43368.7 inch**3
4859.31 MU
                                                        co-ordinate system:
                                                                                                                                                   inch**2
                                                                                                                                 inch**2
                                                                                                                                                                      inch**2
inch**2
                                                                                                                                                             inch**2
                                                                                                                                          inch**2
                             inch
                                                                                                                                                                                        inch**2
                                                                                                                               2.42776e+86 MU
418833 MU inch:
2.52974e+86 MU
969.229 MU incl
-5878.91 MU incl
-88846.3 MU incl
                               ı
                             Length units
                                                       global
                                     6.8936
Global
PROPERTIES
                                                                                                                                                                                        9184.
                                                                                                                                                                                                                     nch
                                                                                                                                                                                                                             nch
                                                                                                                                                                                                                                      nch
                                                      Axes Orientation wrt
1, 0, 0
                                                                                                                                          ax is XX
                                                                                                                                  axis
          Object number: 1
Object description:
                                                                                                                                                                                                           of gyration:
axis 24.4555
axis 10.0602
axis 24.9639
                           <u>E</u>
                                     Density
Axes orientation
 SUMMARY OF MASS
                                                                                                                                                                       moment
                                                                                                                                                              momen t
                                                                                                                                                                                 momen t
                             Mass units -
                                                                                                                                  about
about
                                                                                                                                                                                          area
                                                                                                                                                    about
                                                                                                      Centroid
                                                                                                                                                                                        Surface
                                                                                                                                                             Product
                                                                                                                                                                      Product
                                                                                                                                                                               Product
                                                                                                                                 Moment
                                                                                                                                                   Moment
                                                                                                               Volume
                                                                                                                                          Moment
                                                                                                                                                                                                           Radii
                                                                                                                                                                                                                   ××N
                                                                                                                        Mass
```

6

HULL MASS PROPERTIES FUEL TANK

HRRY OF MASS PROPERTIES act number: 1 act description: 5 units - MU; Length units - inch 5 ity 6.857 5 orientation Global 5 Orientation wrt global co-ordinate system: 7, 8 1, 8 1, 8	troid [-88.8655,38.3942,-24.5929] Jent about X axis 172484 MU inch**2 Inch about Y axis 349738 MU inch**2 Inct moment XY 588.833 MU inch**2 Ject moment ZX -25162.7 MU inch**2	ii of gyration: X axis 18.7485 inch Y axis 15.2974 inch Z axis 13.6832 inch
SUMMARY Object Object Object Mass un Density Axes or	000000000000000000000000000000000000000	

HULL MASS PROPERTIES ELECTRICAL CONTROL BOXES

```
Density
Axes orientation Global
Axes Orientation wrt global co-ordinate system:
                                                                                                [-80.8656,-29.9113,-25.2175]
26219.5 inch**3
393.293 MU
45369.4 MU inch**2
                                                                                                                                                                inch**2
inch**2
                                                                                                                                     nch**2
                                                                                                                                              nch**2
                                                                                                                                                      nch**2
                                                                                                                                                                                 inch**2
                          MU: Length units
                                                                                                                                             73636.6
131.644
-146.851
                                                                                                                                    92834, 2
                                                                                                                                                                                 5622.11
OF MASS PROPERTIES
                                                                                                                                                                                                                      inch
                                                                                                                                                                                                              inch
                                                                                                                                                                                                                               nch
                                                                                                                             description:
                                                                                                                                                                                                   of gyration:
axis 18.7485
axis 15.2974
axis 13.6832
         Object number:
                                                                                                                                                       Product moment
                                                                                                                                                                 moment
                                                                                                                                             about Z
                                                                                                                                                                          moment
                          Mass units -
                                                                                                                             about
                                                                                                                                      about
                                                                                                                                                                                   area
                                                                                                  Centroid
                                                                                                                                                                         Product
SUMMARY
                                                                                                                                                                                  Surface
                                                                                                                                                                Product
                                                                                                                             Moment
                  Object
                                                                                                           Voiume
                                                                                                                                     Moment
                                                                                                                                               Moment
                                                                                                                                                                                                   Radii
X
X
                                                                                                                    Mass
                                                                                                                                                                                                                                        4
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TOTAL STATE OF THE STATE OF THE

HULL MASS PROPERTIES SKIRTS

[22.6216, 0.122172, -21.9445] 4656.64 inch**3 1317.66 MU 5 5.88884e+86 MU inch**2 5 8.83791e+86 MU inch**2 5 1.44962e+87 MU inch**2 co-ordinate system: Object description: Accumulated properties inch**2 inch**2 inch**2 9264.63 MU 8.122912 MU 915.863 MU - MU; Length units 8.283 global Globa inch inch inch Orientation wrt axis of gyration: axis 66.3916 axis 81.898 axis 184.888 Axes orientation moment momen t moment about area about about Mass units Centroid Product Surface Product Product Dens i tų Volume Moment Moment Moment Radii Mass Axes --(ထိုထ်

HULL MASS PROPERTIES SPONSONS

system: Object description: Accumulated properties Mass units - MU; Length units - inch co-ordinate q loba! 6.283 Global Axes or ientation Axes Orientation wrt Density

[55.915,-0.8522779,-6.27638] 17383.8 inch**3 4919.61 MU s 1.43141e+87 MU inch**2 s 2.5649e+87 MU inch**2 s 3.9792e+87 MU inch**2 inch**2 inch**2 inch**2 moment momen t momen t about about area about Centroid Surface Product Product Product Moment Volume Moment Moment Mass

Radii of gyration:
X axis 53.9488 inch
Y axis 72.2855 inch
Z axis 89.9358 inch

HULL MASS PROPERTIES GRILLS

set description: Accumulated properties sunits - MU; Length units - inch	orientation wrt Orientation wrt 8	123.389, -8.111899, 8.285811 13824.3 inch**3 3912.27 MU	i of gyration: X axis 24.8495 inch Y axis 35.8217 inch Z axis 42.3412 inch
Object de Mass unit	HXes Orie 6, 4, 4, 69, 1	Centroid Volume Mass Moment ak Moment ak Moment ak Product n Product n Product n	

HULL MASS PROPERTIES FINAL DRIVE

co-ordinate system: [257.38, -8.83868, -8.42325] 6284.6 inch**3 1778.54 MU s 152954 MU inch**2 s 74807.9 MU inch**2 s 152968 MU inch**2 1.73391 MU inch**2 1.73391 MU inch**2 inch**2 inch inch**2 1 MU; Length units 8.283 ion Global -9.17487giobai 3898.82 inch inch description:
nass units - MU; Ler
Density
Axes orientation
Axes Orientation wrt of
1, 8, 8
8, 1, 8 axis of gyration: axis 9.27359 axis 6.48547 axis 9.27481 about Z moment moment moment about about area Centroid Sur face Product Product Product Moment Volume Moment Moment ××N Radii Mass

inch

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HULL MASS PROPERTIES IDLER

co-ordinate system: -3.98758,-5.863641 inch**3 inch**2 inch**2 nch**2 nch**2 nch**2 nch**2 inch inch**2 I 11698.4 MU -1186.38 MU 2081.32 MU -1451.86 MU 2022.07 inc Length units [2.65812, 1185.29 335.437 14571.9 14544.8 global 6.283 Global nch Axes Orientation wrt ax XX XX ZX ZX ZX axis axixe Object description: 6.59182 6.58489 5.98551 of gyration: axis 6.59182 Ä Density Axes orientation momen t moment momen t Mass units area about about about Centroid Product Product Surface Product Moment Volume Moment Moment ××N Radii Mass

nch

axis

HULL MASS PROPERTIES AUTOLOADER

```
co-ordinate system:
                           inch
                              Į
                           Length units
                                                       qiobal
                                   0.0226
Global
PROPERTIES
                                                      Orientation wrt
         Object number: 2
Object description:
                           MU;
                                     Density
Axes orientation
SUMMARY OF MASS
                              I
                           Mass units
                                                  HX es s
```

```
[69.3098, -0.00975291, -26.2518]
159051 inch**3
3594.55 MU
2.32918e+06 MU inch**2
                                inch**2
inch**2
                                                         inch**2
                                                 inch**2
                                                                 inch**2
                                                                         inch**2
                               1.28752e+86
2.83197e+86
1213.43 MU
-2786.34 MU
                         moment
                                                          moment
                                                                  moment
                                                                          area
                          about
                                  about
                                          about
  Centroid
                                                  Product
                                                          Product
                                                                          Sur face
                                                                  Product
         Volume
                         Moment
                                 Moment
                                         Momen t
                 Mass
```

Radii of gyration:
X axis 25.4553 inch
Y axis 18.9258 inch
Z axis 28.0687 inch

6

HULL MASS PROPERTIES POWER PACK

```
1124.609, -0.00134059, -24.90891
166241 inch**3
                                                  system:
                                                                                                                           inch**2
inch**2
                                                                                                                    nch**2
                                                                                                                                                     inch**2
                                                   co-ordinate
                                                                                                                                            inch**2
                                                                                                                                                             inch**2
                          inch
                                                                                                                                                                     inch**2
                                                                                                 166241 inch
18523.1 MU
6.87798e+86
4.89736e+86
8.58472e+86
6833.83 MU
-18767.3 MU
                            I
                                                                                                                                                    7.3 MU
                         Length units
                                                  qlobal
                                                                                                                                                                    19588.4
PROPERTIES
                                 9.8633
                                         Globa
                                                                                                                                                                                                inch
                                                                                                                                                                                                       inch
                                                 Orientation wrt
                                                                                                                           axis
                 description:
                                                                                                                                                                                      of gyration:
axis 25.5658
axis 19.7324
axis 28.5622
                                         Axes or ientation
OF MASS
        Object number:
Object descrip
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                                                                                                                                                      moment
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                         Mass units -
                                                                                                                     about
                                                                                                                                     about
                                                                                                                             about
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                                                                                            Centroid
SUMMARY
                                Density
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                                                                                                                                             Product
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                                                                                                                    Moment
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                                                  Axes
                                                                                                           Mass
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inch

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	de	LC	x-force LBS	y-force LBS	z-force LBS	x-moment LBS-IN	u-moment LBS-IN	z-moment LBS-IN
	36	1	-254.0941	354.1914	57.0693	0.0000	0.0000	0.0000
		2	-+20058+05	0,4280E+05	-6375.3315	0.0000	0.0000	0.0000
		3 4	-,2194E+05 -79,4353	0.3015E+05	5857.2934	0.0000	0.0000	0.0000
		5	-,2038E+05	546.6164	-175,6688	0,0000	0.0000	0.0000
		ar G	2038E405	0.4390E+05 0.3125E+05	-6493.9311 5738.6938	0.0000	0.0000	0,000
L	66	1	-280.0328	440.9513	170 - 1373		0.0000	0,0000
	(3 (2)	5	1200.9515	0.68562+05	4478E+05	0.0000	0.0000	0.0000
		3	2614E+05	0.4464E+05	4724.2275	0.0000	0.0000	0.0000
		4	247.3138	651.3113	-634.0795	0.0000	0.0000	0.0000
ď		5	1168,2324	0.6965E+05	4524E+05	0.0000	0.0000	0.0000
		é	-,2617E+05	0.4573E+05	4230,2851	0.0000	0.0000	0,0000
	67	1	-236.5160	559.1224	10,4906	0.0000	0.0000	0.0000
	Q7	2	3219E+05	0.2164E+05	9379.6767	0.0000	0.0000	0.0000
		3	2138E+05	0.1774E+05	7172.0698	0.0000	0.0000	0.0000
		4	-256.8170	414.8857	24.4362	0.0000	0.0000	0.0000
		5	32686+05	0.2261E+05	9414.6035	0.0000	0.0000	0,0000
		ó	-,2187E+05	0.1871E+05	7206,9970	0.0000	0.0000	0.0000
	89	1	-214+3248	281.4126	202,8566	0.0000	0.0000	0.0000
		2	-3297.1437	0,4329E+05	4287E+05	0.0000	0.0000	0.0000
		3	48705+05	0.2470E+05	0.3102E+05	0.0000	0.000.0	0.0000
		4	462.5296	440.0636	-877.6386	0.0000	0.0000	0.0000
		5	-3048.9389	0.4401E+05	4355E+05	0.0000	0.0000	0,0000
		હ	4845E+05	0.2543E+05	0.3034E+05	0.0000	0,0000	0.0000
	90	1.	-299.4963	468.6830	44.0192	0.0000	0.0000	0:0000
		2	-,2966E405	5727,1875	9866.7822	0.0000	0.0000	0.0000
		3	1705E+05	9362,4267	5328.4404	0.0000	0.0000	0.0000
		.4	-308.1756	248.1729	78.40799	0.0000	0.0000	0.0000
		5	3027E 105	6444.0434	9988.8818	0.0000	0.0000	0.0000
		ó	1766E+05	0.1008E+05	5450,5395	0.0000	0-0000	0.0000
	112	1	18.8011	149.0347	-3.3993	0.0000	0.0000	0.0000
		2	5091E+05	1158E+05	0.1961E+05	0.0000	0.0000	0.0000
		3	3815E+05	-9851.4013	0.2402E+05	0.0000	0.0000	0.0000
		.4	-206.0739	30.5238	-27.3365	0.0000	0.0000	0.0000
		5	5109E+05	1140E+05	0.1958E+05	0.0000	0.0000	0.0000
	a (a 79	6	3834E+05	-9671.8427	0.2399E+05	0.0000	0.0000	0.0000
	113	1	-518.7282	191.9339	68+6621	0.0000	0.0000	0.0000
		2	21158405	888.4263	5978.0576	0.0000	0.0000	0.0000
(2)		3	1254E+05	5103.6142	2766.0773	0.0000	0.0000	00000
		4	-339.8917	112.6519	68.3809	0.0000	0.0000	0.0000

ATTD1

No	ode 	LC.	x-force LBS	s-force LBS	z-force LBS	x-moment LBS-IN	u-moment LBS-IN	z-moment L&S-IN
j	113	5	2201E+05	1193.0122	6115.1005	0.0000	0.0000	0.0000
		ద	-,1340E+05	5408.2001	2903.1206	0.0000	0.0000	0.0000
1	142	1	30.5871	35.5731	-35.1610	0.0000	0.0000	0.0000
		2	-8797.5839	0.1145E+05	1321.3614	0.0000	0.0000	0.0000
		3	-4581.7148	7182.5253	-7246,9790	0.0000	0.0000	0.0000
		4	-37.7902	77.7063	70.8010	0.0000	0.0000	0.0000
		5	-8804.7871	0.1157E+05	1357.0014	0.0000	0.0000	0.0000
	4 4 65	6	-4588,9174	7295.8051	-7211.3388	0.0000	0.0000	0.0000
•	149	i	-812.1624	533.7449	-388.7175	0-0000	0.0000	0.0000
		2 3	-5595.9853 -7387.2041	0.1899E+05 0.1040E+05	-9909.6210	0.0000	0.0000	0.0000
					-3937.5322	0-10000	0,0000	0.0000
		4	-283,9087 -6692,0566	414,8962 0.1994E+05	-254.3319	0.0000	0.0000	0.0000
		5 6	-8483,2753	0.1777ET05	1055E+05	0.0000	0.0000	0.0000
,	199		8,4837	-59.6820	-6580.5820	040000	0.0000	0,0000
•	£ 7÷7	1 2	-7405.9389	8828.8749	-0.101 <i>4</i> -9937,6357	0.0000 0.0000	0.0000	0.0000
		3	1002E+05	0,1188E+05	6523.7211	0.0000	0.0000	0.0000
		4	44.1825	-66.5126	-230.5342	0:+ 0:000	0.0000	0.0000
		5	-7353,2724	8702,6826	1017E+05	0.40000	0.0000	0.0000
		é	-9970,2480	0.1175E+05	6293.0854	0.0000	0.0000	0,0000
5	204	1.	-1240,1739	491.1315	-772,9278	0.0000	00000	0.0000
•	No. 1:	$\ddot{\tilde{z}}$	-9323.0000	0.2213E+05	2715E+05	0.0000	0.0000	0.0000
		3	1108E+05	0.1082E+05	1413E+05	0.0000	0,0000	0.0000
		4	-550,8495	445.6551	-588.8792	0,0000	0.0000	0.0000
		5	1111E+05	0.2306E+05	2851E+05	0.0000	0.0000	0.0000
		ô	1287E+05	0.1176E+05	1549E+05	0.0000	0.0000	0.0000
2	263	1	-1664.8498	21.1826	-175+6469	00000	0.0000	0.0000
		2	1935E+05	0.1577E+05	3504E+05	0.0000	0.0000	0.0000
•		3	1660E+05	6205.5141	1116E+05	00000	0.0000	0.0000
		4	-856,3114	267.2435	-625.1054	0.0000	0.0000	0.0000
		5	2187E+05	0.1606E+03	3584E+05	0.0000	0.0000	0.0000
_		Ó	1912E+05	6494.0405	1526E+05	0.0000	0.0000	0.0000
^ ′	266	1	-161.3522	-203,5603	194.9903	0.0000	0-+0000	0.0000
		2	1668E+05	2547E+05	-,3474E+05	0.0000	0.0000	0.0000
		3	-+4867E+05	-,1266E+03	0.3512E+05	0=(-0.0.00	0.0000	0.0000
		4	305.4491	-318.9123	-829.0529	0.0000	0.0000	0.0000
		5	1654E+05	2599E+05	3537E+05	0.0000	0.0000	0.0000
-		ćs	4853E+05	1318E+05	0.34496+05	0.0000	0.0000	0.0000
•	325	1.	-1632.7509	-340.0855	947.9761	0.0000	0.0000	0.0000
΄ ,		2	-,2984E+05	7146,0991	1730E+05	0-+0000-	0,0000	0,0000

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Node	LC	x-force LRS	y-force LBS	z-force LBS	x-moment LBS-IN	s-moment LBS-IN	2-moment LBS-IN
325	3	2026E+03	1515.1131	-2826.5571	0.0000	0.0000	0.0000
	4	-1038.2961	66.3306	-119.3067	0.0000	0.0000	0.0000
	5	3251E+05	6872.3442	1647E+05	0.0000	0.0000	0.0000
mg mg .e.	Ó	2293E+05	1241.3582	-1997.8876	0.0000	0.0000	0.0000
333	1	-266.8231	-368.5695	140.1167	0.0000	0.0000	0.0000
	2 3	2739E+05 4174E+05	5784E+05	1859E+05	0.0000	0.0000	0.0000
	3 4	28.6326	3962E+05 -543.7225	0+1747E+05 -435+9789	0+0000 0+0000	0.0000	0.0000
	5	2763E403	5876E+05	1889E+05	0.0000	0.0000	0.0000
	ယ ဝ	4198E+05	4053E+05	0.1718E±05	0.0000	0.0000	0.0000
380	1.	-1501.3331	-519.0402	1511.8194	0.0000	0.0000	0.0000
	$\hat{2}$	3240E+05	-1698.5906	3652-2590-	0.0000	0.0000	0.0000
	3	2061E+05	-2711.4775	7667.5439	0.000	0.0000	0.0000
	4	-1048,2556	-117.4435	364.3771	0.0000	0.0000	0.0000
	5	3495E+05	-2335.0747	5528,4555	0.0000	0.0000	0.0000
	6	2316E+05	-3347.9614	9543,7402	0.0000	0.0000	0.0000
390	1	-237.5613	-470.9484	47.2341	0.0000	0.000	0.0000
	2	6068,9604	-,4888E+05	3566E+05	0.0000	0+0000	0.0000
	3	-9133.0322	3377E+05	-7521.3935	0.0000	0.0000	0.0000
	4	111.8878	-573.5885	-425.9952	0.0000	0.0000	0.0000
	5	5943,2856	4992E+05	3604E+05	0.0000	0,0000	0.0000
	6	-9258,7060	3481E+05	-7900.1547	0.0000	0.0000	0,0000
433	1	-946.0357	-140.7482	1814.6645	0.0000	0.0000	0.0000
	2	-,2928E+05	-8210.4072	0.2038E+05	0.0000	0.0000	0.0000
	3	1718E+03	-6110.2543	0.1559E405	0.0000	0.0000	0.0000
	4	-848.5390	-295.7858	761.6219	0.0000	0.0000	0.0000
	5	3108E+05	-9246.9414	0.2296E+05	0.0000	0.0000	0.0000
_	Ó	1897E+05	-7146.7885	0.1817E+05	0.0000	0.0000	0.0000
445	1.	-188,0081	-484.7857	-7.2419	0.0000	0.0000	0.0000
	2	-9675.6474	3137E+05	-6899.0517	0.0000	0.0000	0.0000
	3	1027E+05	2240E+05	-240.9179	0.0000	0.0000	0.0000
~	4	-67.4669	-493,9767	-134.9418	0.0000	0.0000	0.0000
	5	-9931,1220	3235E+05	-7041.2358	0.0000	0.0000	0.0000
	6	-,1053E+05	-,2338E+05	-383,1017	0.0000	0.0000	0.0000
494	1	-288.3428	-619.2368	1005.1689	0.0000	0.0000	0.0000
	2	2158E+05	1170E,+05	0.1935E+05	0.0000	0.0000	0.0000
	3	1185E+05	-6843,1865	0.1170E+05	0.0000	0,0000	0.0000
	4	-491.2997	-366.3882	608.3247	0.0000	0.0000	0.0000
	5	2236E+05	1269E405	0.2096E+05	0.0000	0.0000	0.0000
	6	1263E+05	-7828,8115	0.1331E+05	0.40000	0.0000	0.0000

ATTD1

ANALYSIS NO.2 THIN SHELL FAGE 418

		x-force	y-force	z-force	x-moment	u-moment	z-moment
Node	LC	LBS	LBS	LBS	LBS-IN	rbs-in	LES-IN
504	1	-211.1177	-407.6978	25.7549	0.0000	0.0000	0.0007
	2	-,2003E+05	1573E+05	6437.8203	0.0000	0,0000	0.0000
	3	1229E+03	1355E+05	3721.3837	0.0000	0.0000	0.0000
	4	-196.1194	-358,6633	25.7988	0.0000	0.0000	0,0000
	5	2043E+05	1650E+05	6489.3740	0.0000	0,0000	0.0000
	ර	-,1270E+05	1432E405	3772.9375	0.4 0.0.00	0.0000	0.0000
565	1	-25.6876	-304 -2955	326,5323	0.0000	0.0000	0.0000
	2	1638E+05	-8 <u>0</u> 90,2065	8767.8593	0.0000	0.0000	0.0000
	3	-9286,8896	-3771,7648	4407,3945	0+0000-	0.0000	0,0000
	4	-217.8530	-276.7544	286.8719	0.0000	0.0000	0,0000
	5	1662E+05	-8673.2568	9381.2636	0.0000	0.0000	0.0000
	ó	-9530.4306	-4354.8149	5020.7988	0 + 0 0 0 0	0.0000	0.000.0
576	1	-389.2644	-287.1839	38,3607	0.0000	0.0000	0.0000
	2	1742E+05	-,1246E+05	5227.1020	0.0000	0.0000	0.0000
	3	1035E+05	11-02E+05	2387.3449	0.0000	0.0000	0.0000
	4	-254.1546	-299,4626	41.8784	0.40000	0.0000	0.0000
	5	1806E+05	-,1305E+05	5327.3413	0.0000	0.0000	0.0000
	ó	1099E+05	1161E+05	2487.5842	0.0000	0.0000	0.0000
ક4ક	1.	51.0307	-246.2756	147.5408	0.0000	0.0000	0.0000
	5	1415E+05	-3870,5434	2511.4072	0.0000	0.0000	0.0000
-	3	-8690,8574	-1414-3289	971.1271	0.0000	0.0000	0.0000
	4	0.0127	-240+6963	152,4656	0.0000	0.0000	0.0000
	5	1410E+05	-4357.5151	2811.4135	0.0000	0,0000	0.0000
2 m cm	6	-8639.8134	-1901+3009	1271-1336	0.0000	0.0000	0.0000
655	1	-732.0683	-515.0806	-179.6863	0.0000	0.0000	0,0000
	7	1371E+05	1290E+05	-1932+4252	0.0000	0.0000	0.0000
	3	-9979,2626	-9564.7714	-2102.8730	0.0000	0.0000	0.0000
_	4	-377.1217	-286,0310	-77.4530	0.0000	0.0000	0.0000
•	5	1482E405	1370E705	-2189,5646	0.0000	0.0000	0.0000
	6	1109E+05	1037E105	-2360.0124	0.0000	0.0000	0.0000
721	1	363,3000	-396.4500	155.3629	0 0 0 0 0	0.0000	0.0000
>	2	1212E+05	-4214,7304	1134.7403	0,0000	0.0000	0.0000
	3	-7659.7944	-2093+7006	459.3596	0.0000	0,0000	0,0000
	4 5	281.4858	-377.8491	155,2225	0.0000	0.0000	0.0000
		1147E+05	-4989+0297 -2867+9997	1445.3260	0.0000	0,0000	0.0000
729	6 1	-7015.0087 -1130.3397	-701,0131	769.9451 401.7705	0.0000	0.0000	0.0000
127	2			-621,7795	_	0.0000	0.0000
		1936E+05	1456E+05	1272E+05	0,-0000	0,0000	0.0000
	3 4	1536E+05	1018E+05	-8882.5830	Ø-+ Ø-Ø Ø-Ø	0.0000	0.0000
,	4	-637.6796	-318+2951	-287.4513	0.0000	0.0000	0.0000

ATTD1

MICAS REV 8.8.2 DEC 28,1988 14:19 ANALYSIS NO.2

THIN SHELL

PAGE 419

*** Support Reactions ***

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Node	LC	x-force LBS	y-force LBS	z-force LBS	x-moment LBS-IN	u-moment LBS-IN	z-moment LBS-IN
729	5	2113E+05	1558E+05	1363E+05	0.0000	0.0000	0,0000
	6	1713E+05	1120E+05	-9791.8134	0.0000	0,0000	0,0000
798	1	1036.2781	-837,7082	282,2303	0.0000	0.0000	0.0000
	2	-1246,8627	-7917.7045	-23.5097	0.0000	0.0000	0.0000
	3	~596.877S	-4909.2270	-138.1438	0.0000	0.0000	0.0000
	4	741.9924	-630.1438	231.5961	0.0000	0.0000	0.0000
	5	531,4078	-9415.5566	490.3168	0.0000	0.0000	0.0000
	6	1181.3930	-6407.0795	375.6826	0.0000	0.0000	0.0000
805	1	-1577.3575	-516.0983	-817.8409	0.0000	0.0000	0.0000
	2	2115E+05	2175E+05	3171E+05	0.0000	0.0000	0.0000
	3	1831E+05	12826+05	1899E+05	0.0000	0.0000	0.0000
	4	-814.3905	-376.2888	-580.8137	0.0000	0,0000	0.0000
	5	2354E+05	2264E+05	3311E+05	0.0000	0.0000	0.0000
	6	2070E+05	1371E+05	2039E+05	0.0000	0.0000	0.0000
862	1	1009,4035	-1460.7938	425.5678	0.0000	0.0000	0.0000
	2	-509.9897	1526E+05	-439.5634	0.0000	0.0000	0.0000
	3	-348.6518	1065 +05	-320.1556	0.0000	0.0000	0.0000
	4	717.8289	-1013.3742	302.0578	0.0000	0.0000	0.0000
	5	1217,2426	1774E+05	288.0621	0.0000	0.0000	0.0000
	6	1378.5805	-:1313E+05	407.4700	0.0000	0.0000	0.0000
878	1	-1823.2998	85.4030	71.4443	0.0000	0.0000	0.0000
	2 3	3453E+05	1527E+05	3500E+05	0.0000	0.0000	0.0000
		2607E+05	-7490.0615	1754E+05	0.0000	0.0000	0.0000
	4	-1051.7038	-183.6354	-466,9679	0.0000	0.0000	0.0000
	5	3740E+05	1536E+05	-,3539E+05	0.0000	0.0000	0.0000
en en en	6	2895E+05	-7588,2890	-+1794E+05	0.0000	0.0000	0.0000
923	1	1120.3796	-1381.3785	625,6754	0.0000	0.0000	0.0000
_	2	2049,4165	1462E+05	965.8071	0.0000	0.0000	0.0000
	3	1201.3679	1025E+05	515.0379	0.0000	0.0000	0.0000
	4	728.8759	-953.9065	404.8824	0.0000	0.0000	0.0000
	5	3898.6721	1696E+05	1996.3649	0.0000	0.0000	0.0000
	6	3050.8237	1259E+05	1545.5958	0.0000	0,0000	0.0000
946	1	-1623.9940	413.1006	1016.4624	0.0000	0.0000	0.0000
	2	3938E+05	-3680+3847	1422E+05	0.0000	0.0000	0.0000
	3	-,2786E+05	-440.7516	-3463.4443	0.0000	0.0000	0.0000
	4	-1056.0656	24.8699	2.5815	0.0000	0.0000	0.0000
	5	4206E+05	-3242+4143	1320E+05	0.0000	0.0000	0.0000
/5/DP	ó	3054E+05	-2.7810	-2444.4003	0.0000	0.0000	0.0000
985	1	1530.8405	-1344.6453	1097.5666	0.0000	0.0000	0.0000
	2	7483.5581	1506E405	5242.4291	0.0000	0.0000	0_• 0000

ATTD1

Node	LC	x-force LBS	y-force LBS	z-force LBS	x-moment LBS-IN	u-moment LBS-IN	z-moment LBS-IŅ
985	3	4686,4194	1063E+05	3217.0156	0.0000	0.0000	0.0000
	Ą	867,2994	-889,5796	623,6818	0.0000	0.0000	0.0000
	5	9881.4982	1729E+05	6963.6777	0.0000	0.0000	0.0000
1 4 11 7	6	7084.5595	1286E+05	4938 - 2641	0.0000	0.0000	0.0000
1.003	1.	-1300.7185	763+8793	2145.4096	0.0000	0.0000	0.0000
	2 3	3856E+05	4776.7978	0.1059E+05	0.0000	0.0000	0.0000
	4	-,2631E+05 -944,8826	5124.7988 227.4895	0.1342E+05 621.3545	0.0000	0.0000	0.0000
	5	-,4081E+05	5768.1669	0.1336E+05	0.0000	0.0000	0.0000
	క	2856E+05	6116.1679	0.1618E+05	0.0000	0.0000	0.0000
1041	1	2066.6308	-1063.4152	1813.5147	0.0000	0.0000	0.0000
7047	2	0.1418E+05	1302E+05	0.12526+05	0.0000	0.0000	0.0000
	3	9162.0613	-9380.4179	8019.2353	0.0000	0.00.00	0.0000
	4.	1072.8503	-679.5886	952.5922	0.0000	0.0000	0.0000
*	ន៍	0.1732E+05	1476E+05	0.15296+05	0.0000	0.0000	0.0000
	ა რ	0.1230E+05	11122+05	0.10796+05	0.0000	0,0000	0.0000
1048	1	2402+8081	-527.0577	2340.6958	0.0000	0.0000	0.0000
M V I W	2	0.1887E+05	-7756.6206	0.1360E+05	0.0000	0,0000	0.0000
	3	0.1250E+05	-5933.1523	0.1225E+05	0.0000	0.0000	0.0000
	4	1197,5661	-327.8864	1187.4877	0.0000	0.0000	0.0000
	5-	0.22476405	-8611.5654	0.2213E+05	0.0000	0.0000	0.0000
	6	0.1610E+05	-6788.0966	0.1578E+05	0.0000	0.0000	0.0000
1049	1	2357.2172	92+7177	2297.2834	0.0000	0.0000	0,0000
	2	0.1954E+05	-1064.6671	0.1932E+05	0.0000	0.0000	0.0000
	3	0.1326E+05	-1409.9241	0.1306E+05	0.0000	0.0000	0.0000
	4	1158,1772	63.1795	1151.0111	0,0000	0.0000	. 0.0000
	5	0.2306E405	-908.7698	0.22/7E+05	0.0000	0.0000	0.0000
	6	0.1678E+05	-1254.0268	0.1651E+05	0.0000	0+0000	0.0000
1059	1	-470.7892	708.1444	2161.1022	0.0000	0.0000	0.0000
	2	-,3063E+05	0.1256E+05	0.3062E+05	0.0000	0.0000	0.0000
	3	1939E+05	9718.1835	0.2400E+05	0.0000	0.0000	0.0000
	4	-571.6944	388.5559	955+4833	0.0000	0.0000	0.0000
	5	316/E+05	0.1386E+05	0.3374E+05	0.0000	0.0000	0.0000
	6	2043E+05	り・1101EH05	0.2712E+05	0.0000	0.0000	0.0000
1099	1	1960.2038	654.8960	1742.3414	0.0000	0.0000	0.0000
	2 3	0.1634E+05	5432.7519	0.1480E+05	0.0000	0.0000	0.0000
		0.11426+05	3111.3352	0.1030E+05	0.0000	0.0000	0.0000
	4	976.1085	422.3565	882.2664	0.0000	0.0000	0.0000
*	5	0.1927E+03	6510.0043	0.1742E+05	0.0000	0.0000	0.0000
	6	0.1436E+05	4188.5878	0.1293E+05	0.0000	0.0000	0.0000

ATTD1

Node	LC	x-force LBS	y-force LBS	z-force LBS	x-moment L8S-IN	u-moment LBS-IN	z-moment LBS-IN
1115	1.	207.0277	755.5904	1082.0546	0.0000	0.0000	0.0000
	2	1848E+05	0.1702E+05	0.2631E+05	0.0000	0.0000	0.0000
	3	1089E+05	0.1148E+05	0.1777E+05	0.0000	0.0000	0.0000
	4	-125,4902	459.3162	688,7649	0.0000	0.0000	0,0000
	5	1840E+05	0.1823E+05	0.2808E+05	0.0000	0.0000	0.0000
1147	ტ ქ	1081E+05 1343.2218	0.1269E+05 1030.7711	0.1955E+05 991.4389	0.0000	0.0000	0.0000
7.7.41.1	1 2	0.1020E+05	0.1004E+05	7704.7197	0.0000	0.0000	0.0000
	3	7516.9448	6462.3671	5646,6157	0.0000	0.0000	0.0000
	4	713.8812	681.8010	531,9371	0.0000	0,0000	0.0000
	5	0.1226E+05	0.1175E+05	9228.0957	0.0000	0.0000	0.0000
	6	9574.0478	8174.9394	7169.9916	0.0000	0.0000	0.0000
1162	1	538.7063	530.9070	456.6375	0.0000	0.0000	0.0000
	2	-,1079E+05	0.1373E+05	0.1245E+05	0.0000	0:0000	0.0000
•	3	-6174.7016	8556.0439	7736.9340	0.0000	0.0000	. 0.0000
	4	216.4391	426,2145	382.1062	0,0000	0.0000	0.0000
	5	1004E+05	0.1468E+05	0.1329E+05	0.0000	0.0000	0.0000
	6	-5419.5561	9513.1660	8575.6777	0.0000	0.0000	0.0000
1192	1	803.2297	1136.4099	460.3804	0.0000	0.0000	0.0000
	2	3725.0524	0:1130E+05	2111.9001	0.0000	0.0000	0.0000
	3	3215.4704	7547.8354	1825.0178	0.0000	0.0000	0.0000
	4	507.5852	789.9555	290.9257	0.0000	0.0000	0.0000
	5	5035.8676	0.1322E+05	2863.2065	0.0000	0.0000	0.0000
	6	4526.2856	9474.2001	2576.3242	0.0000	0.0000	0.0000
1194	1	916.3430	659.9765	368.8496	0.0000	0.0000	0.0000
	2	-5524.2480	0.1062E+05	5632.1621	0.0000	0.0000	0.0000
	3	-2773.1635	6662.3232	3463.0075	0.0000	0.0000	0.0000
	4	565.7381	508.1165	297.6970	0.0000	0.0000	0.0000
•	5	-4042.1672	0.1179E+05	6298.7089	0.0000	0.0000	0.0000
	ద	-1291,0823	7830.4165	4129.5541	0.0000	0.0000	0.0000
1195	1	566.3385	1055.2404	247.8643	0.0000	0.0000	0.0000
_	2	-804.5958	0.1006E+05	-524.8756	0.0000	0,0000	0.0000
	3	112.7531	6817.4291	-74.8023	0,0000	0.0000	0.0000
	4	449.8986	787.3642	195.7579	0.0000	0,0000	0.0000
	5	211.6413	0.1191E+05	-81.2532	0.0000	0.0000	0,0000
مەرىسىرى <u>.</u>	6	1128.9903	8660.0341	368.8199	0.0000	0.0000	0.0000
1197	1.	1041.8327	935.3052	301.5941	0.0000	0.0000	0.0000
	2	1437,4622	0.1132E+05	2469.9167	0.0000	0.0000	0.0000
	3	2020.4791	7444.3969	1604.9025	0.0000	0.0000	0.0000
	4	736.4599	678 + 4474	258.5570	0.0000	0.0000	0.0000

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ANALYSIS NO.2 THIN SHELL PAGE 422

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TURRET SUPPORT REACTIONS (TRUNNION)

*** Su	Suppor	t Reactions	**				•
Node	27	x-force LBS	y-force LBS	z-force LBS	x-moment LBS-IN	y-moment LBS-IN	z-moment LBS-IN
255 255 338 337 1259 1259 1263	 	1575E+05 -4305.5942 -1848E+05 -9699.7441 -8607.6083 -3902.6889 1177E+05 1572E+05 1739E+05 1739E+05 1739E+05 1739E+05 1748E+05	-2374.1516 3889.6125 -132.4175 -1355.4362 -778.7837 466.3665 -2136.4165 -4148.3378 -4262.4758 -2867.7692 -1959E+85 -2811.2518 5489.1899 6883.9968	9.8888 9.8888 9.8888 9.8888 9.8888 9.8888 9.8888 4988.2682 -2665E+85 3486E+85	8 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9 9	8 - 8 - 8 - 8 - 8 - 8 - 8 - 8 - 8 - 8 -	20000000000000000000000000000000000000
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